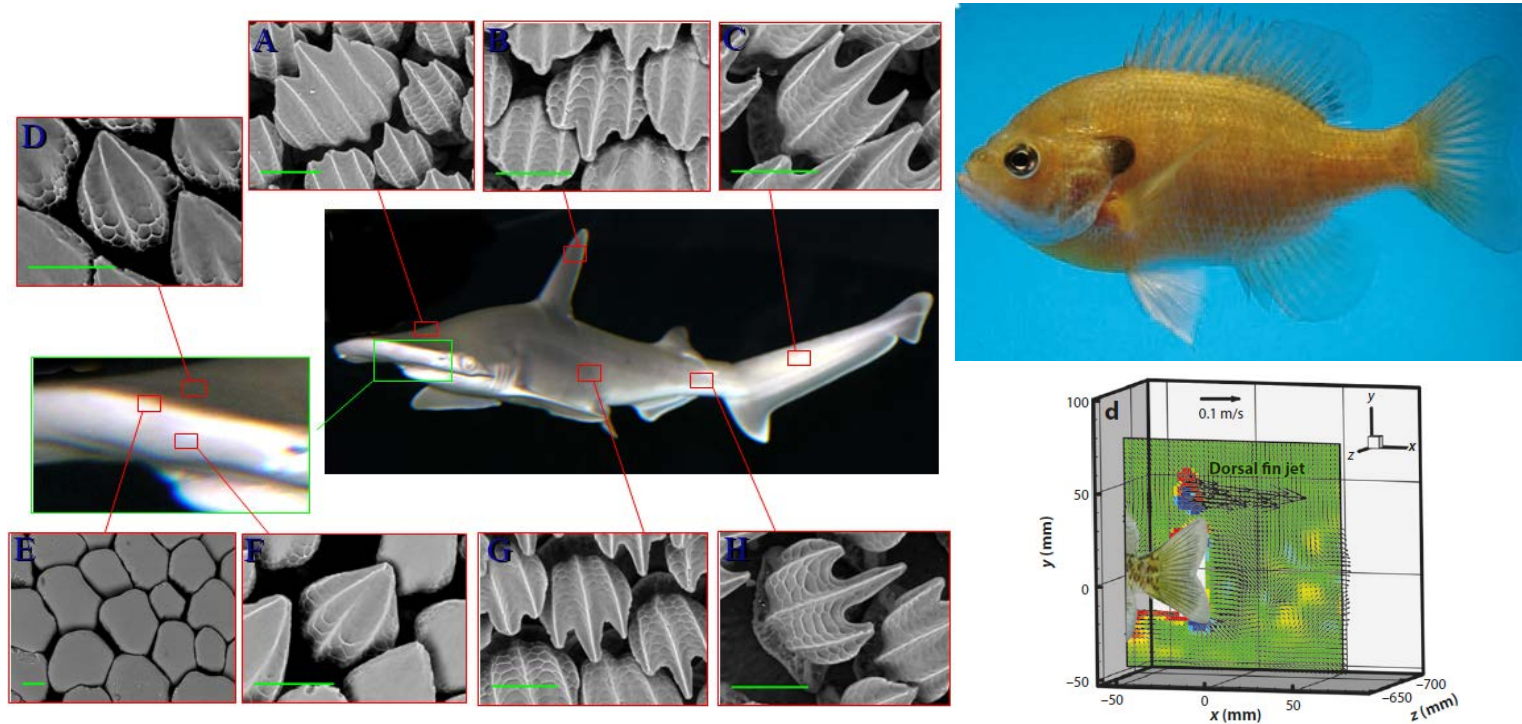


Biomimetics and Fish Hydrodynamics

Johannes Oeffner, Fraunhofer Center for Maritime Logistics and Services CML - Hamburg
Seminar held at INSEAN - Rome, 3rd December 2015



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Biomimetics

- Introduction
- Examples

2

Fish Hydrodynamics

- Swimming Modes
- Propulsion by Body and Tail
- Propulsion by Fish Fins

3

Flow Control

- Introduction
- Flow Sensing in Seal Whiskers
- Drag Reduction in Shark Skin

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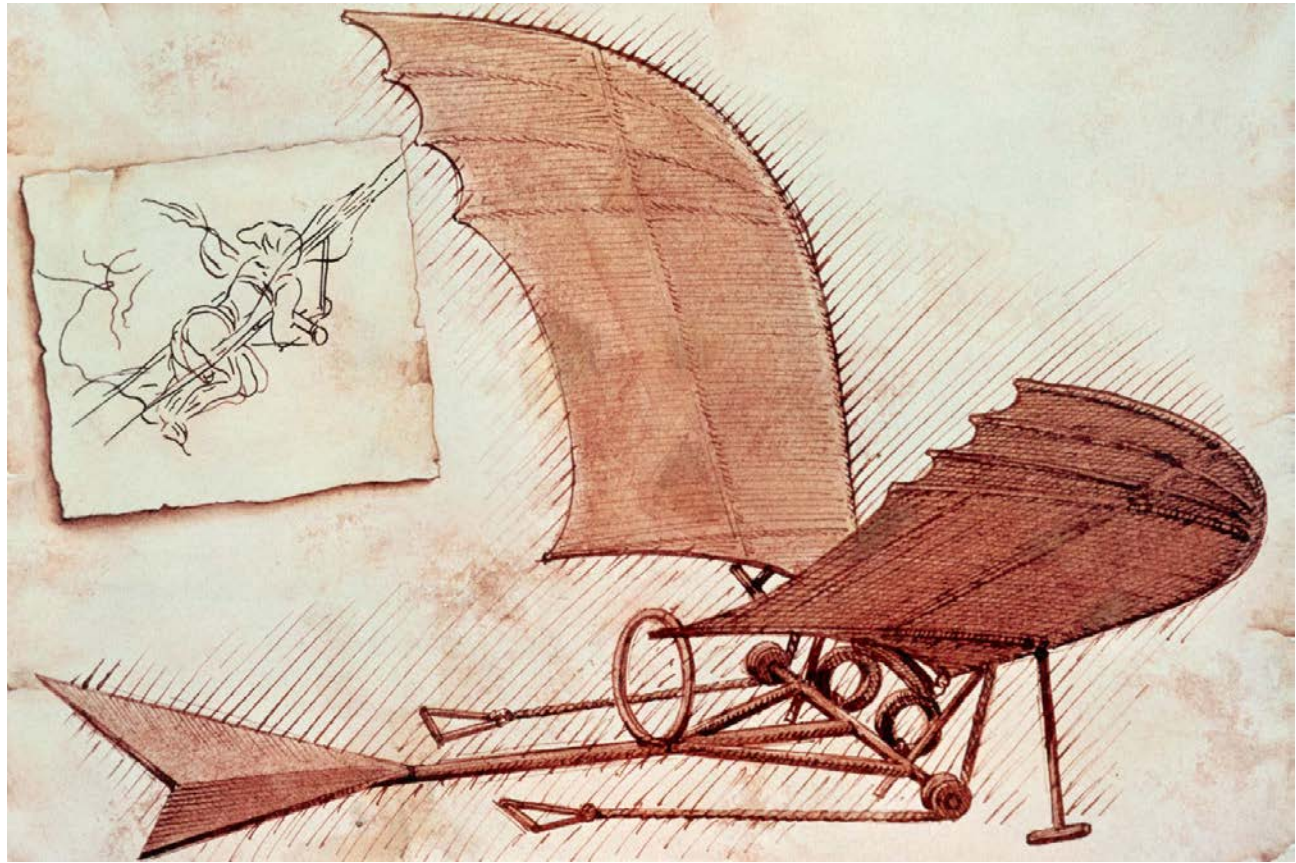
- Introduction
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Biomimetics - Introduction

Biomimetics (Bionics, Biomimicry, Bio-inspiration)

- Systematic investigation of biological models and the transfer to innovative technical applications
- Not just copying nature, but understanding underlying processes!
- Interface of Biology and Engineering
- Application range: Engineering, Material Science, Architecture, Robotics, Artificial Intelligence, Medicine, Mechanical Design, Fluid Dynamics

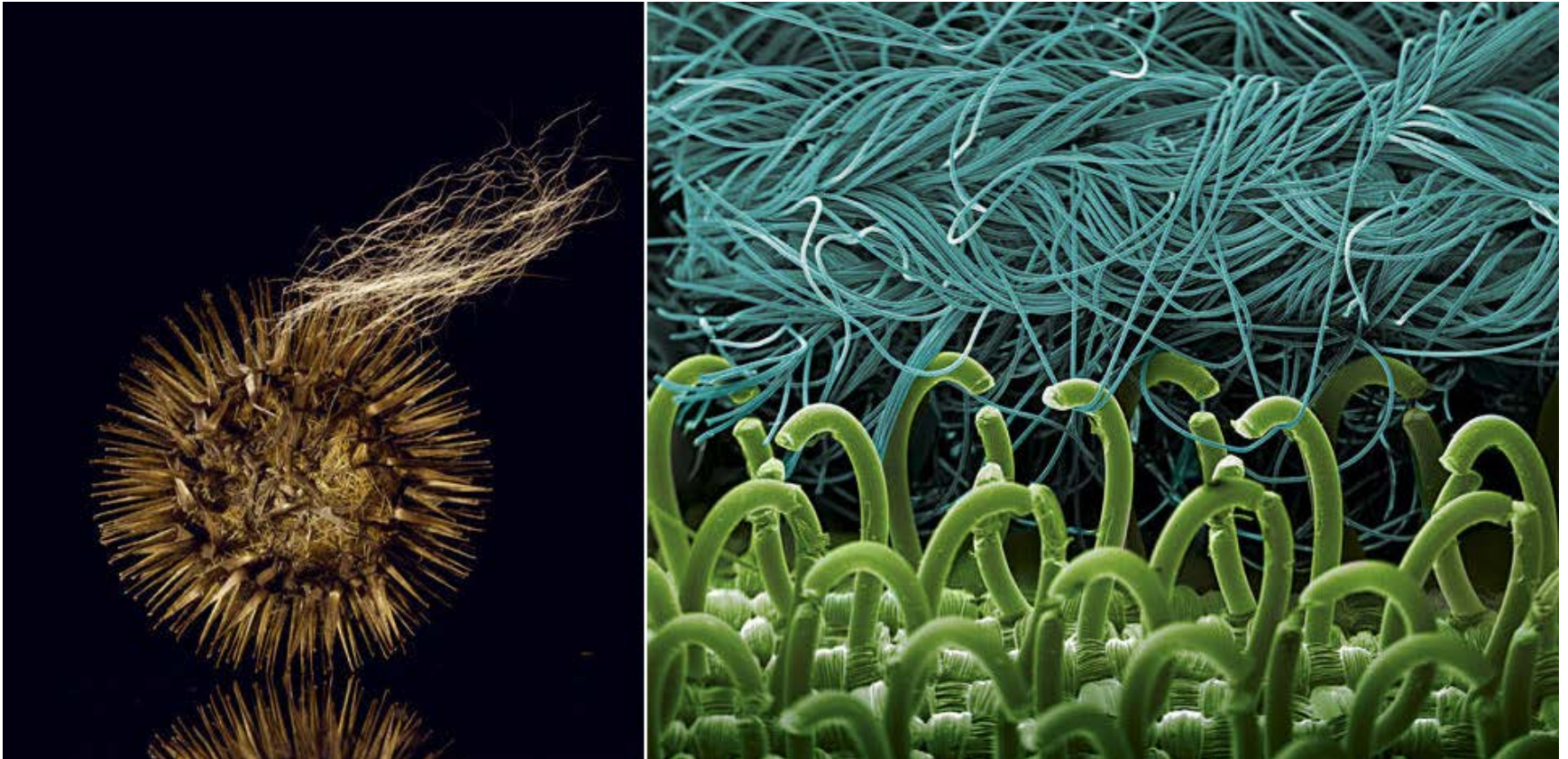
Biomimetics - Introduction



- Leonardo Da Vinci, 1452-1519
- Developed a concept for a flying machine applied from the study of birds and bats flight

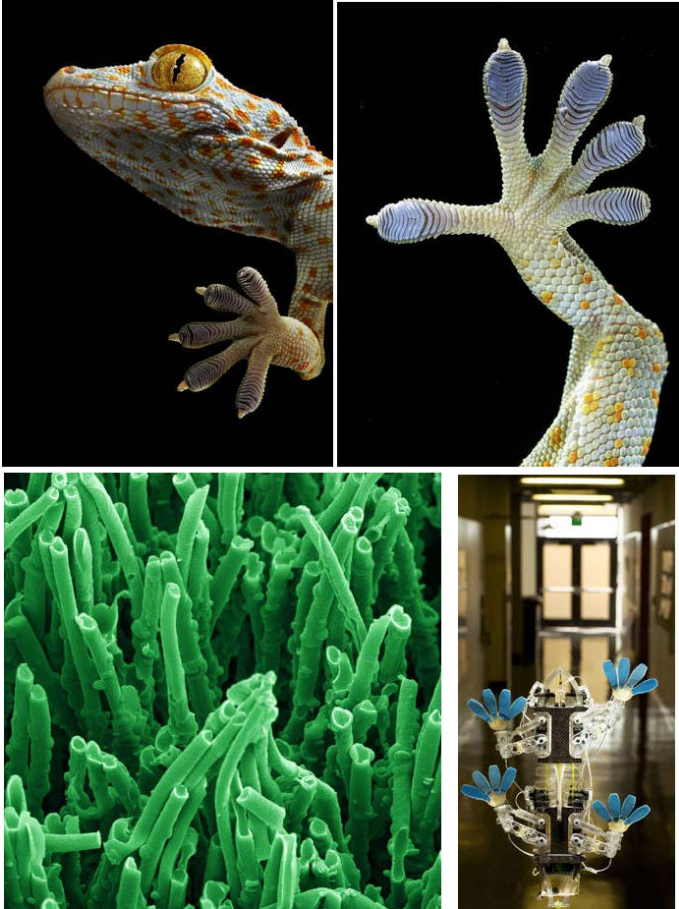
Biomimetics - Examples

Velcro, George de Mestral, 1948



Biomimetics - Examples

Gecko feet → Adhesion without glue



Principle: 6.5 million setae bind to substrate via van der Waals force → sum of little forces = Adhesion

Lotus effect → Self cleaning



Principle: microstructure and wax layer → non-sticky for water → dirt is washed away

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Fish Hydrodynamics – Swimming Modes



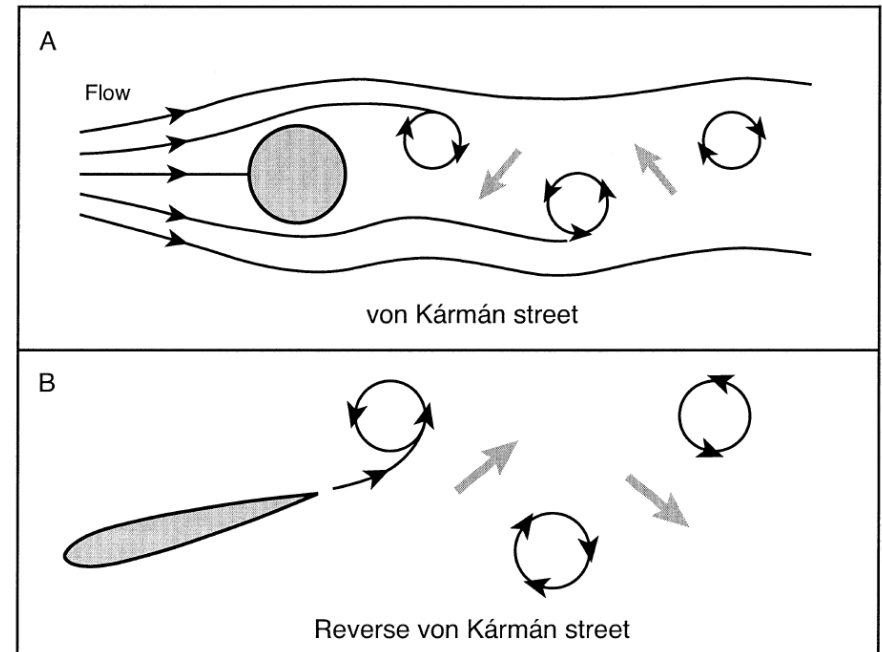
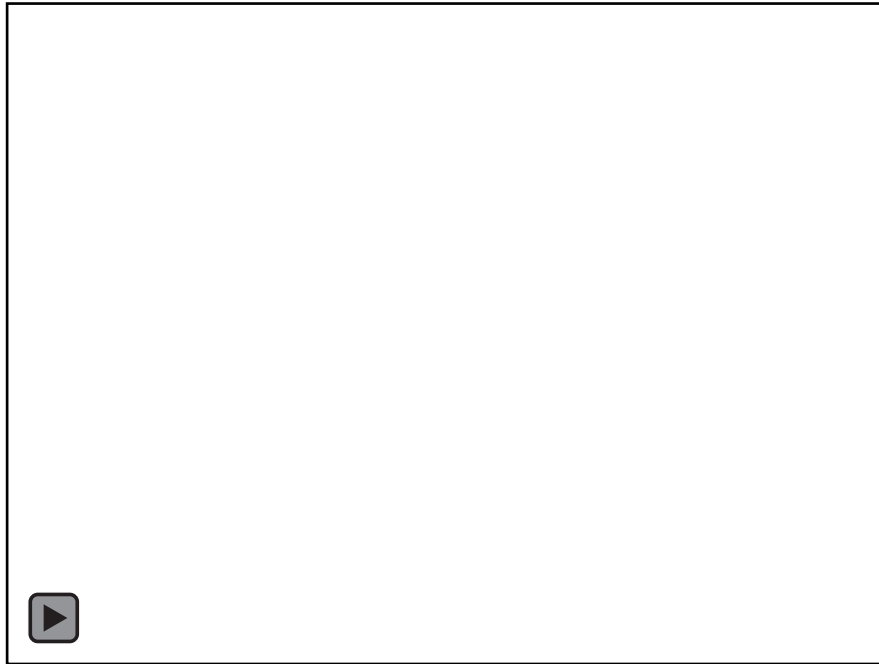
Truly undulatory
→ thrust contributions of good part of the body

Undulatory with
hydrofoil function
of tailfin

Oscillatory,
thrust from
(tail) fins only

Fish Hydrodynamics – Propulsion by Body and Tail

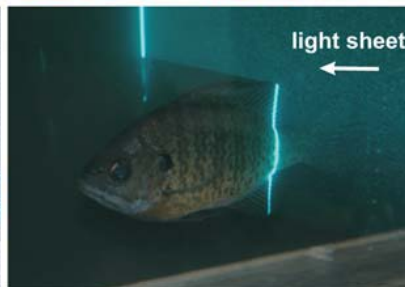
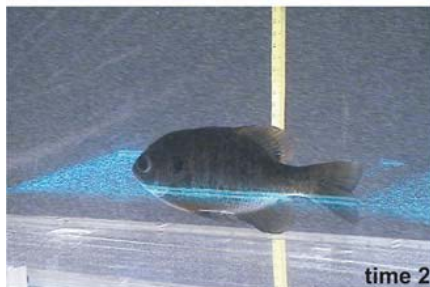
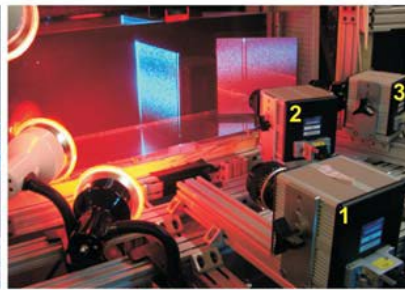
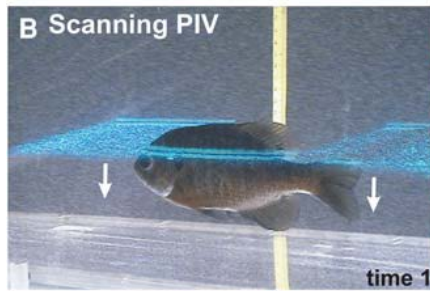
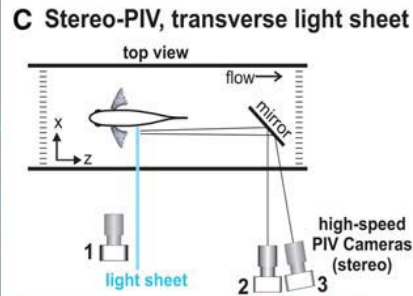
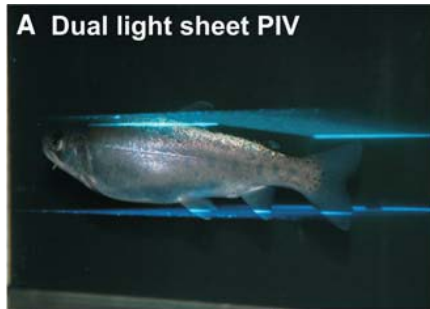
➤ Principle



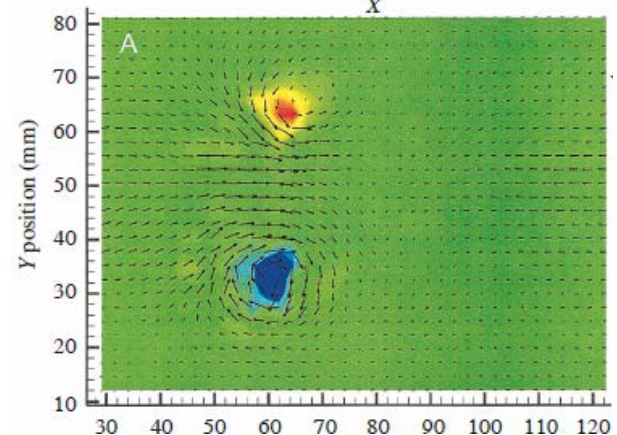
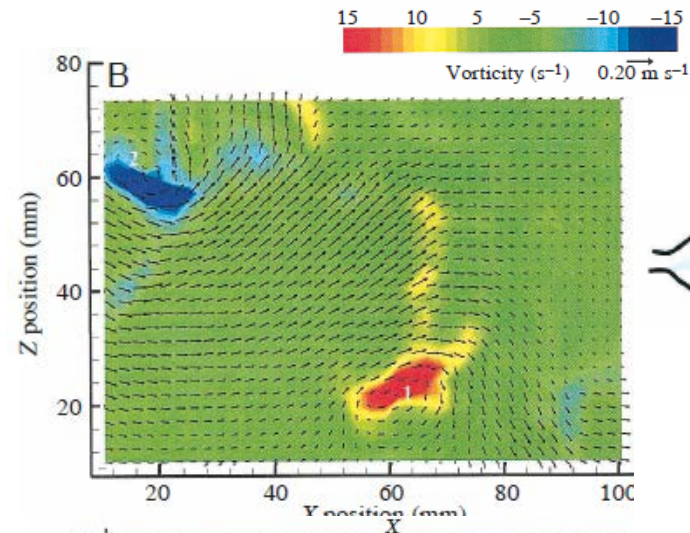
Drucker and Lauder (2002): Experimental hydrodynamics of fish locomotion: functional insights from wake visualization. In *Integrative and Comparative Biology*.

Fish Hydrodynamics – Propulsion by Body and Tail

➤ Flow Visualization



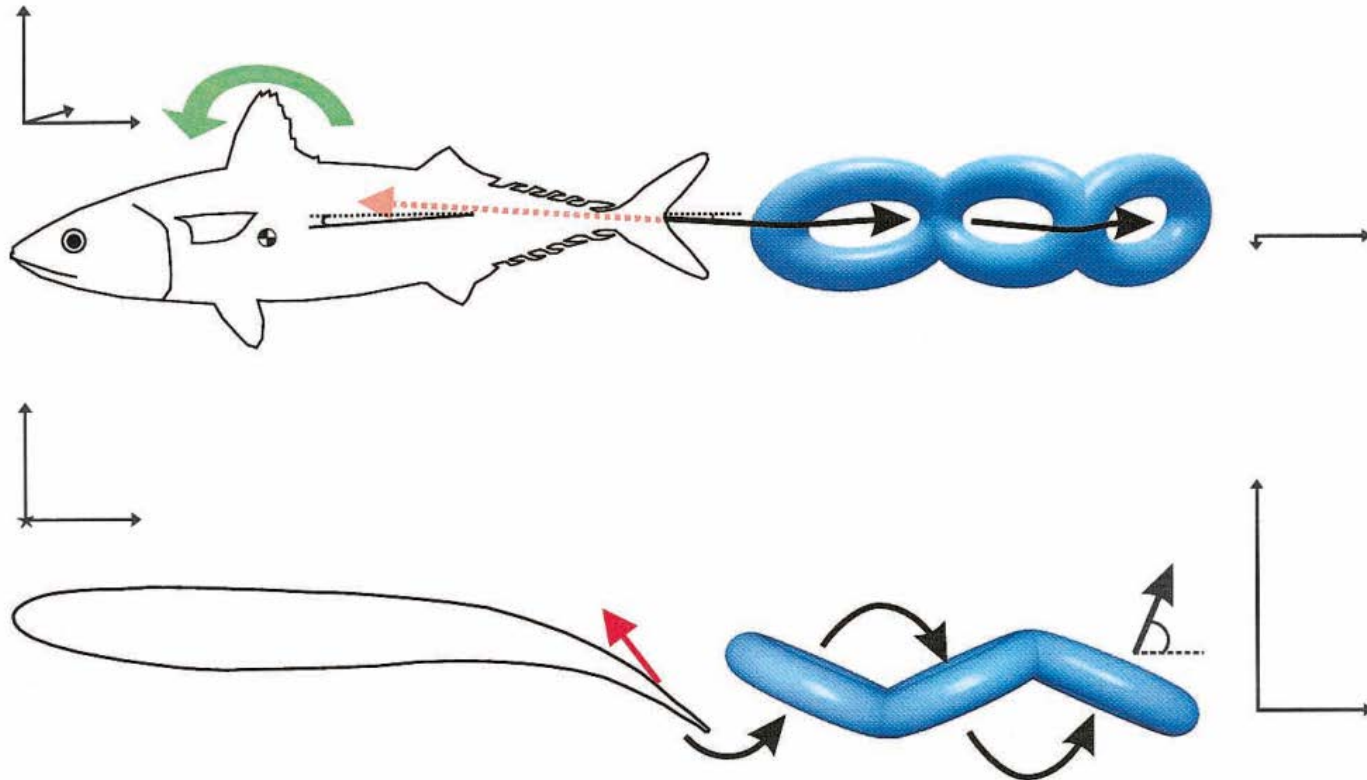
Lauder and Madden (2007): Fish locomotion: kinematics and hydrodynamics of flexible foil-like fins. In *Experiments in Fluids*.



Nauen and Lauder (2002): Hydrodynamics of caudal fin locomotion by chub mackerel, *Scomber japonicus* (Scombridae). In *Journal of Experimental Biology*

Fish Hydrodynamics – Propulsion by Body and Tail

➤ Model

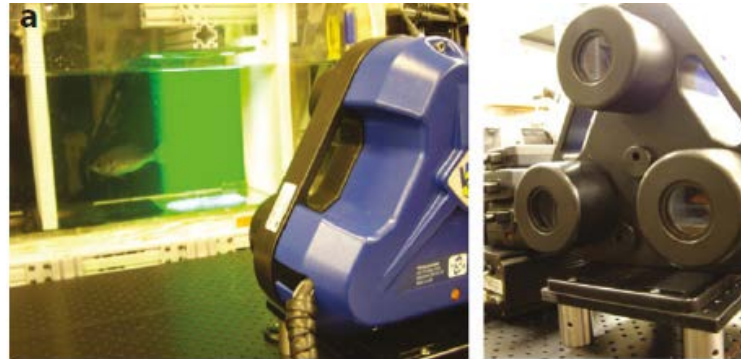


Nauen and Lauder (2002): Hydrodynamics of caudal fin locomotion by chub mackerel, *Scomber japonicus* (Scombridae). In *Journal of Experimental Biology*

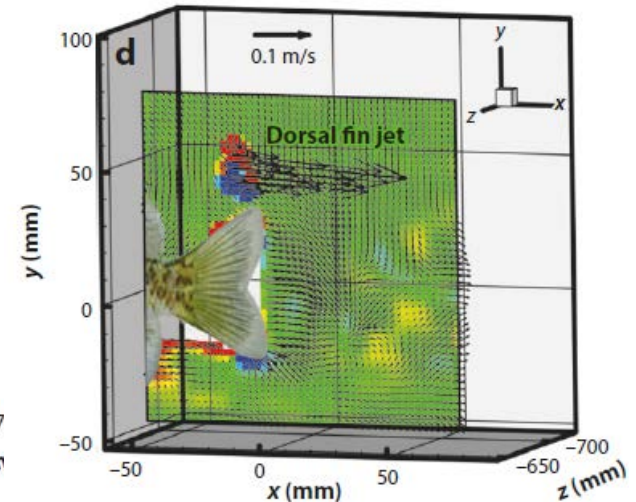
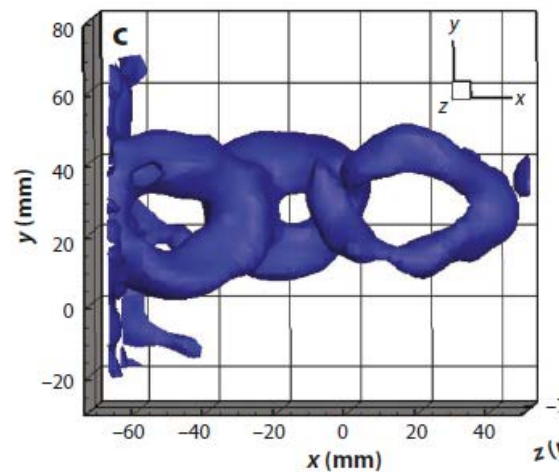
- most fish tails function as a distinct propeller
- series of linked elliptical vortex rings, each with central momentum jet flow → thrust !

Fish Hydrodynamics – Propulsion by Body and Tail

- Proof of Model
- Volumetric (3D) PIV



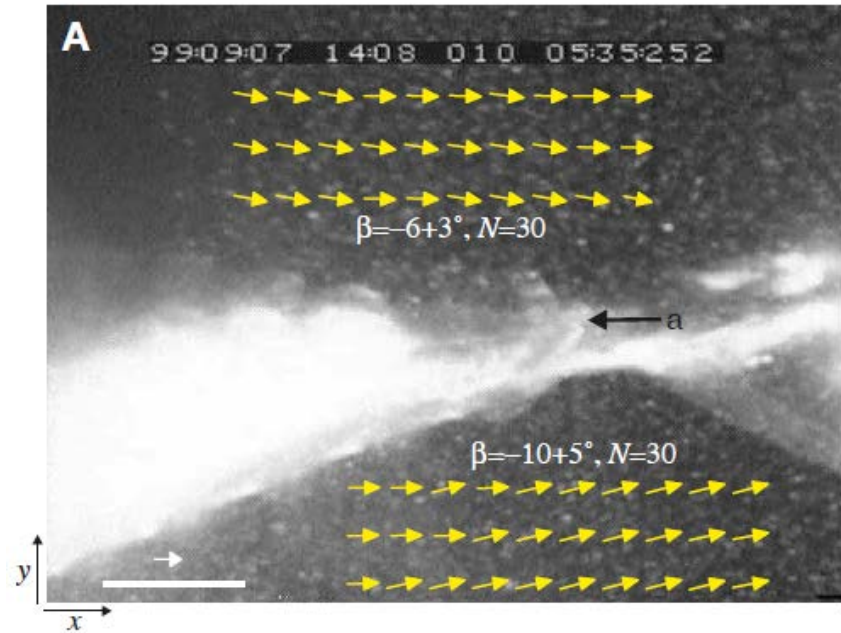
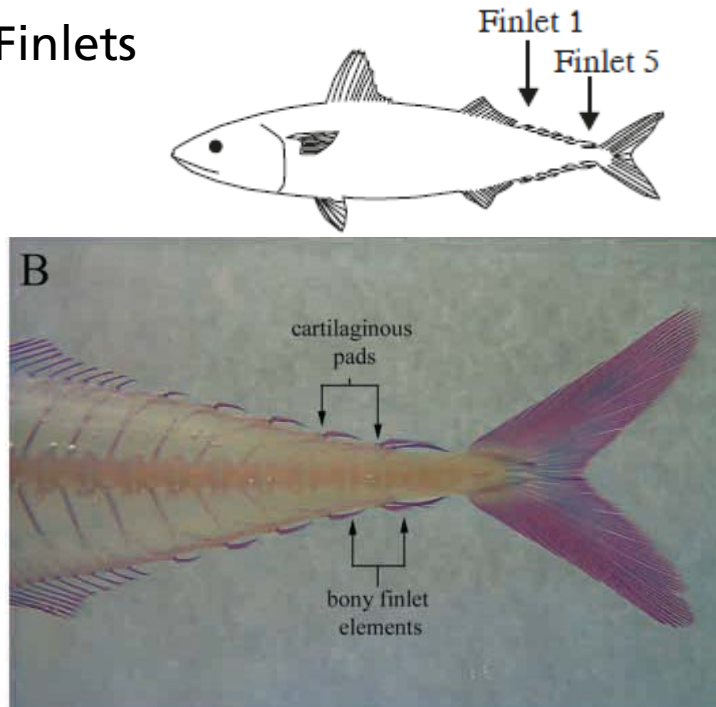
Flammang, et al. (2011):
Volumetric imaging of fish locomotion. In *Biology letters*.



- 3D structure of the linked-chain pattern of vortex rings shed by the tail
- strong wake flows shed by the dorsal and anal fins interact with tail (caudal) fin flows

Fish Hydrodynamics – Propulsion by Body and Tail

➤ Finlets



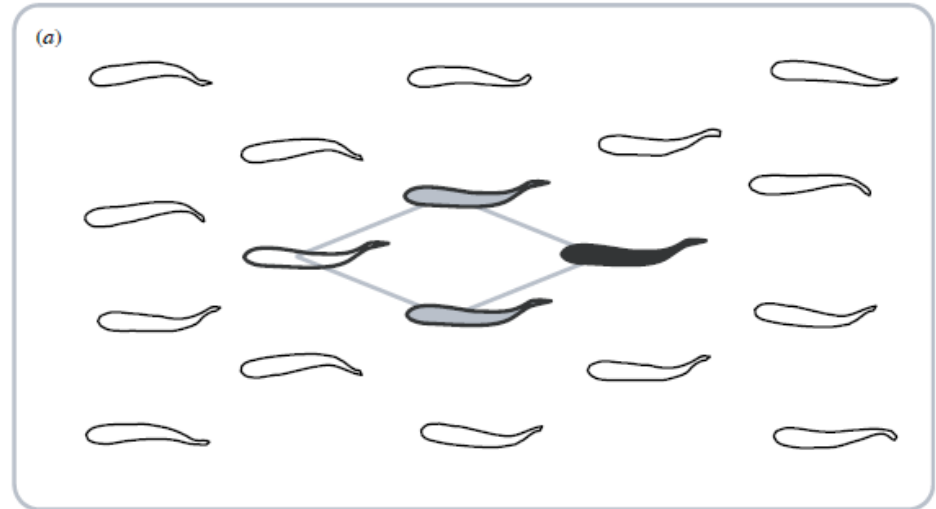
Nauen and Lauder (2001): Locomotion in scombrid fishes: visualization of flow around the caudal peduncle and finlets of the chub mackerel *Scomber japonicus*. In *Journal of Experimental Biology*.

Nauen and Lauder (2002): Hydrodynamics of caudal fin locomotion by chub mackerel, *Scomber japonicus* (Scombridae). In *Journal of Experimental Biology*.

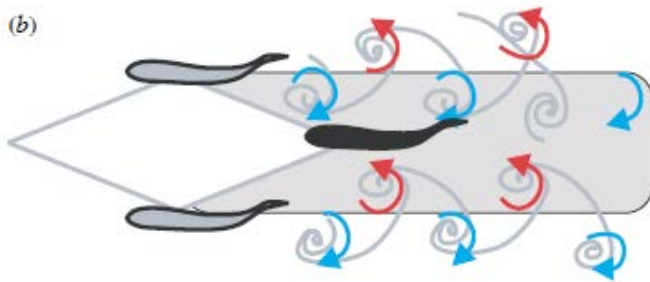
- hydrodynamic effect on local flow during steady swimming
- Vortex generators: to delay boundary layer separation → drag reduction!

Fish Hydrodynamics – Propulsion by Body and Tail

➤ Fish Swarms



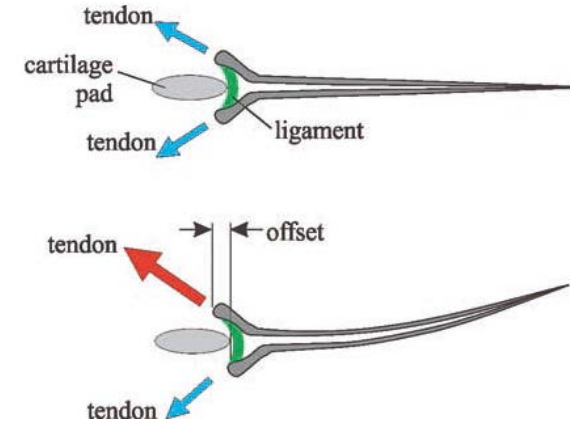
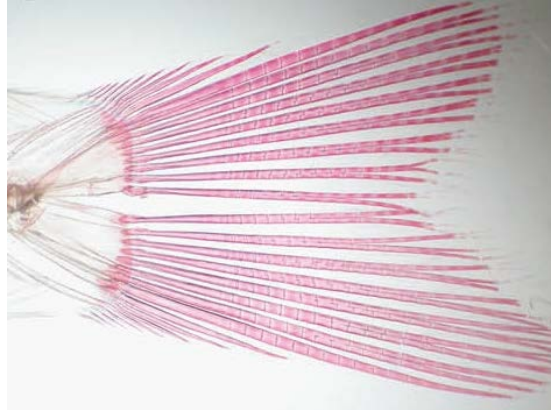
Liao (2007): A review of fish swimming mechanics and behaviour in altered flows. In *Philosophical Transactions of the Royal Society B: Biological Sciences*.



- Diamond shape swarm formation benefits individual hydrodynamics
 - swimming in reduced relative flow
 - harnessing the energy of vortices

Fish Hydrodynamics – Propulsion by Fish Fins

➤ Morphology



Alben, et al. (2007): The mechanics of active fin-shape control in ray-finned fishes. In *Journal of The Royal Society Interface*.

➔ Base Muscles allows sliding motion actively bend each fin ray and control the surface shape



Aqua Ray



FESTO

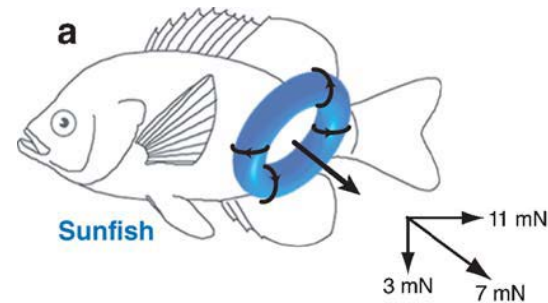
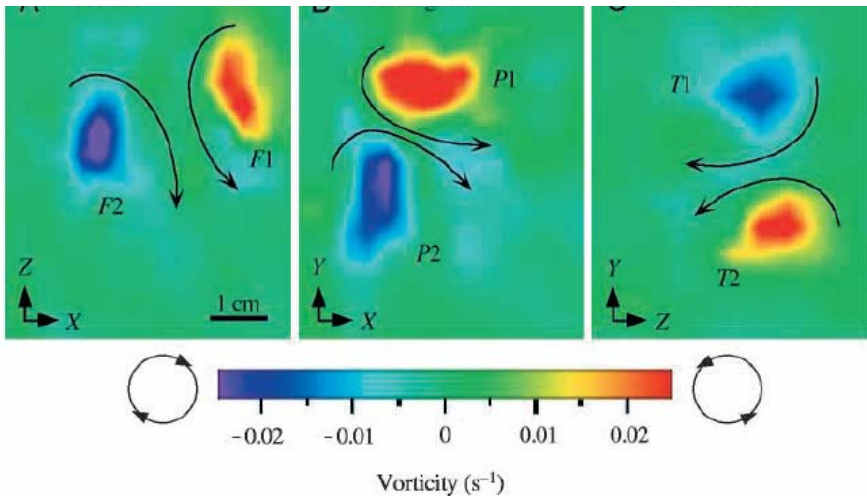
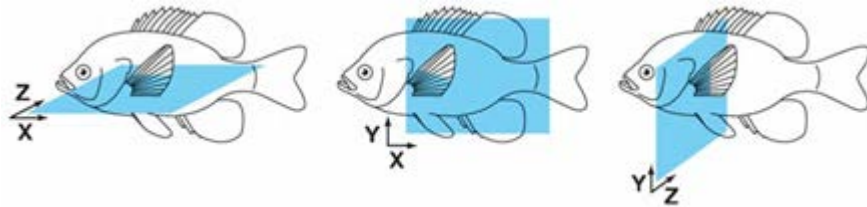


FinGripper Finger

FESTO

Fish Hydrodynamics – Propulsion by Fish Fins

➤ Model



Drucker and Lauder (1999): Locomotor forces on a swimming fish: three-dimensional vortex wake dynamics quantified using digital particle image velocimetry. In *Journal of Experimental Biology*.

- each fin-beat cycle → formation of a single vortex
- at low speeds only pectoral fin
- at higher speeds added tail, dorsal & anal fin and linked vortex chain

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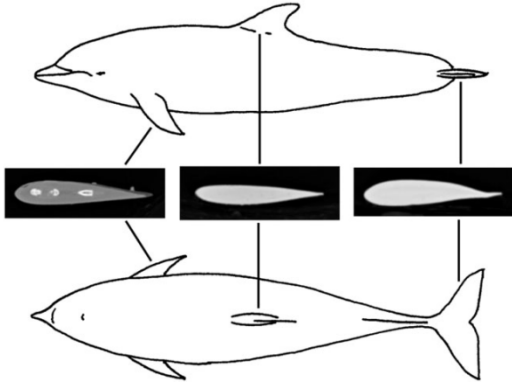
3

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- Flow Sensing in Seal Whiskers
- Drag Reduction in Shark Skin

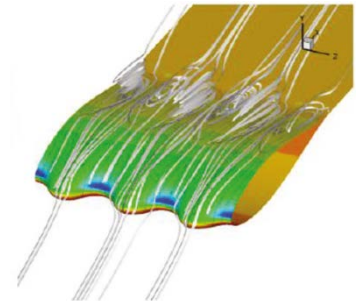
Flow Control – Introduction

➤ Streamlining



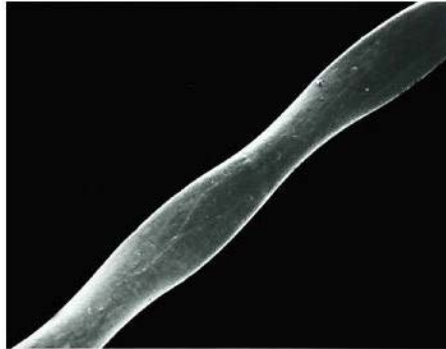
Fish, et al. (2008): Hydrodynamic flow control in marine mammals. In *Integrative and Comparative Biology*.

➤ Humpback Whale Tubercles

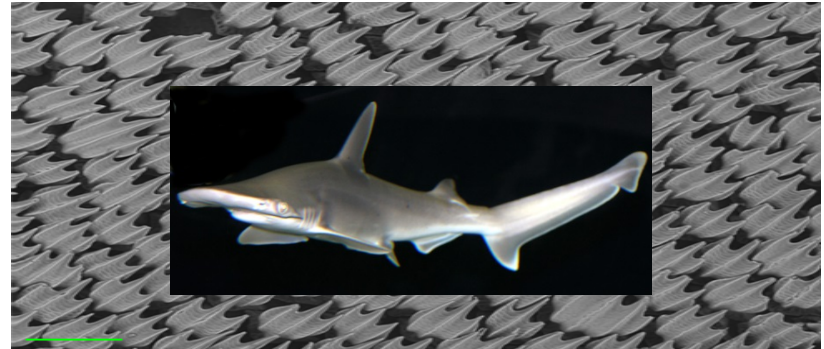


Fish, et al. (2008): Hydrodynamic flow control in marine mammals. In *Integrative and Comparative Biology*.

➤ Seal Whiskers



➤ Shark Skin



Flow Control – Flow Sensing With Seal Whiskers

Hanke, Oeffner, et al. (2010): Harbor seal vibrissa morphology suppresses vortex-induced vibrations. In *Journal of Experimental Biology*.

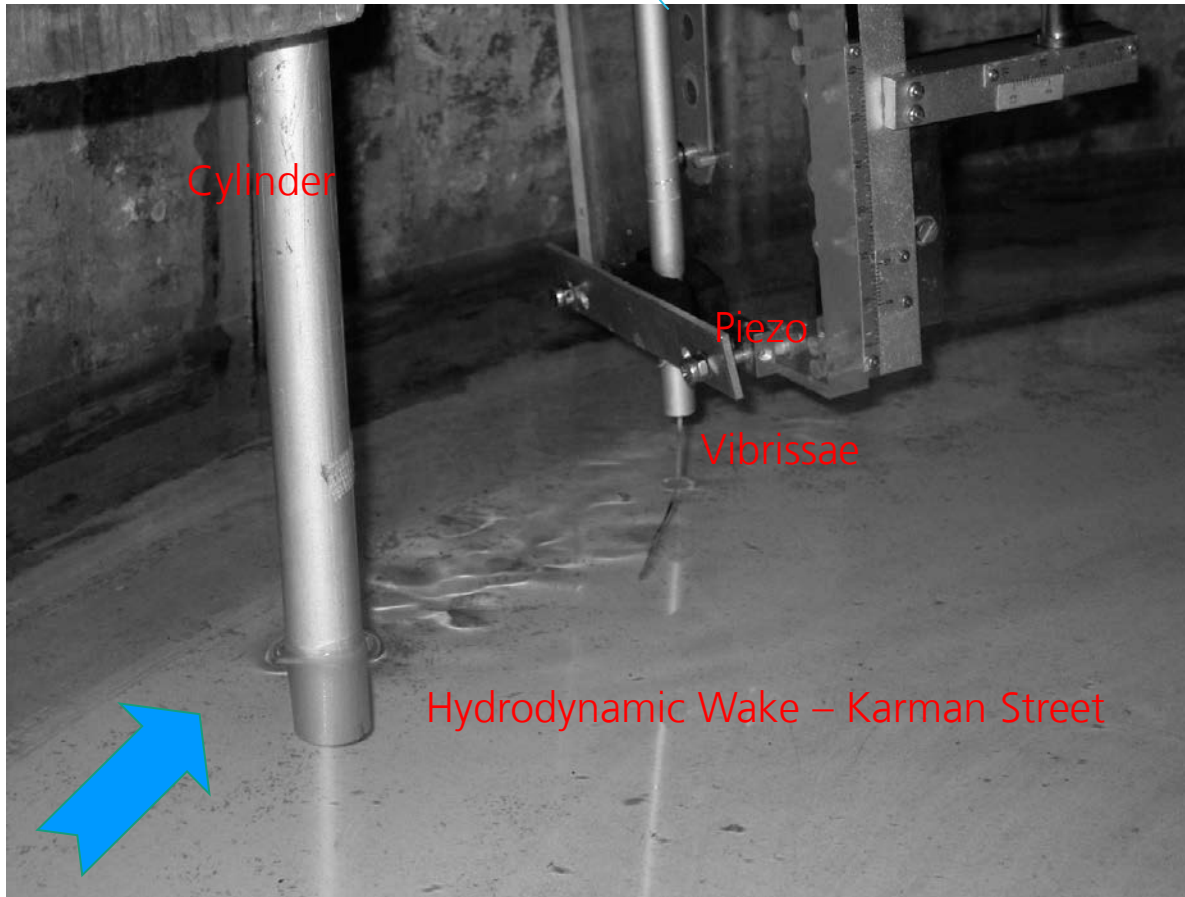
Miersch, Oeffner, et al. (2011): Flow sensing by pinniped whiskers. In *Philosophical Transactions of the Royal Society B: Biological Sciences*.



- Detect hydrodynamic wake with isolated vibrissae?
- Difference between sea lion and seal? Why has seal special shape?

Flow Control – Flow Sensing With Seal Whiskers

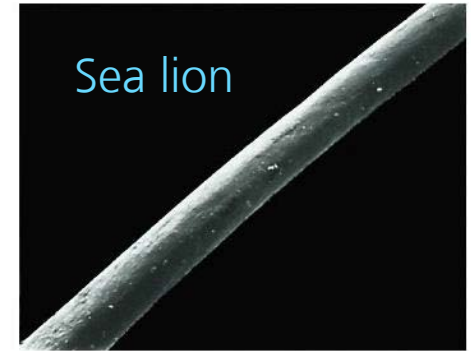
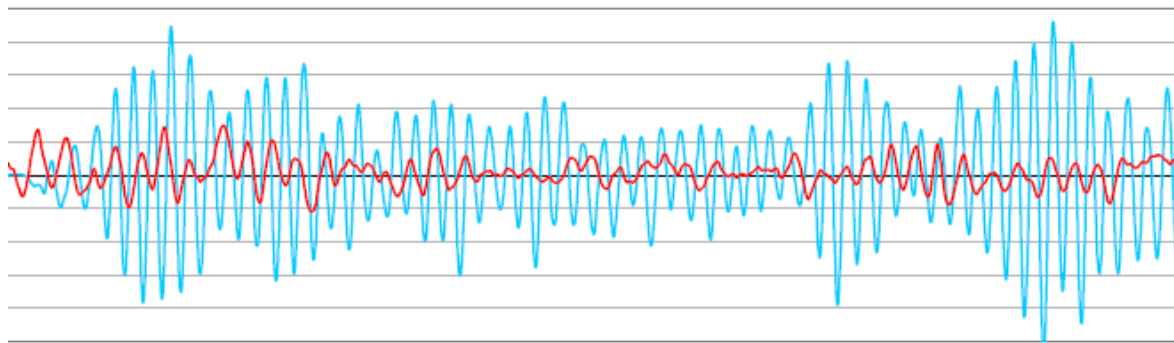
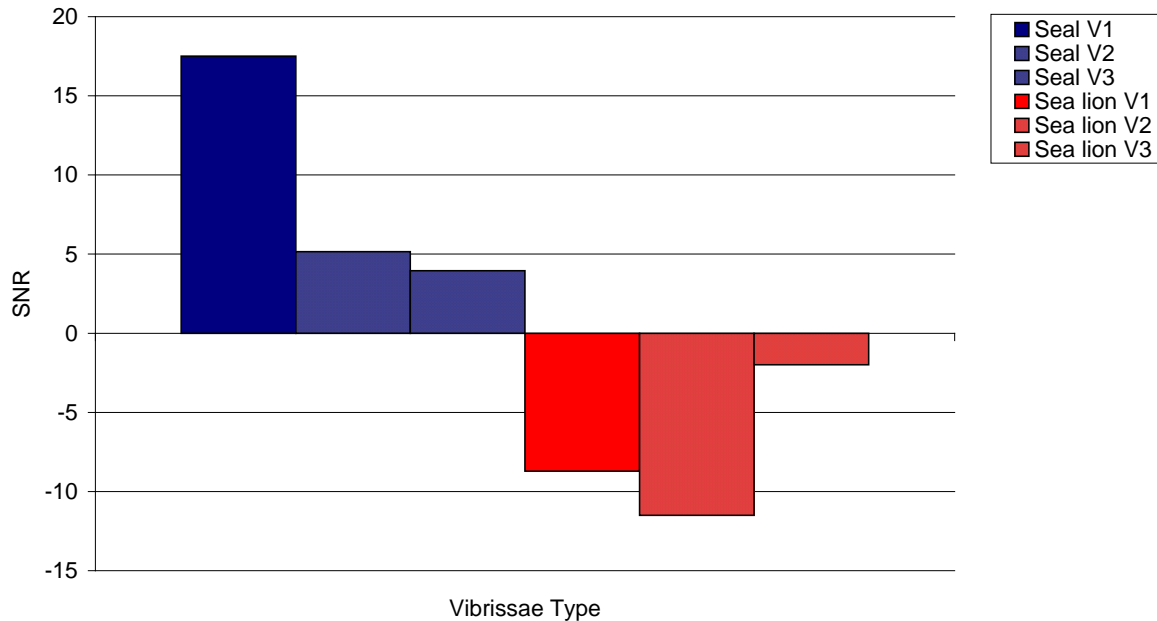
➤ Setup



- Measure frequency of Karman Street
- Compare to calculated Frequency
- Determine SNR
- Compare seals and sea lions vibrissae

Flow Control – Flow Sensing With Seal Whiskers

➤ Results



➤ High noise (self-oscillation)

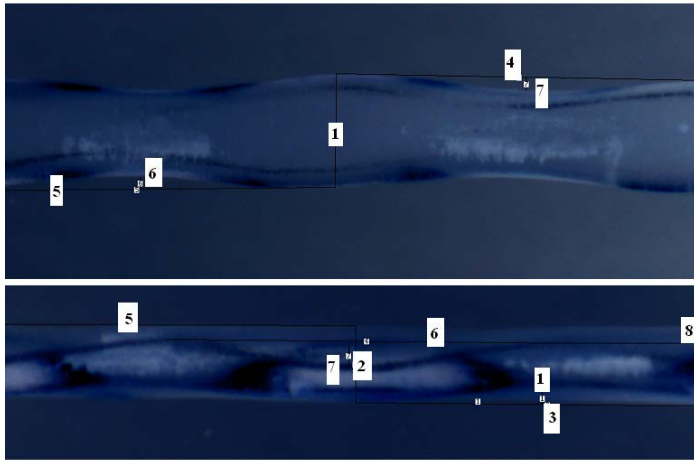


- Low noise (self-oscillation)
- Reduces vibration
- Also reduces drag?

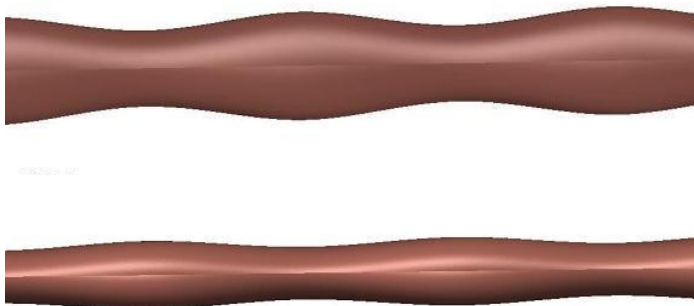
Flow Control – Flow Sensing With Seal Whiskers

➤ CFD

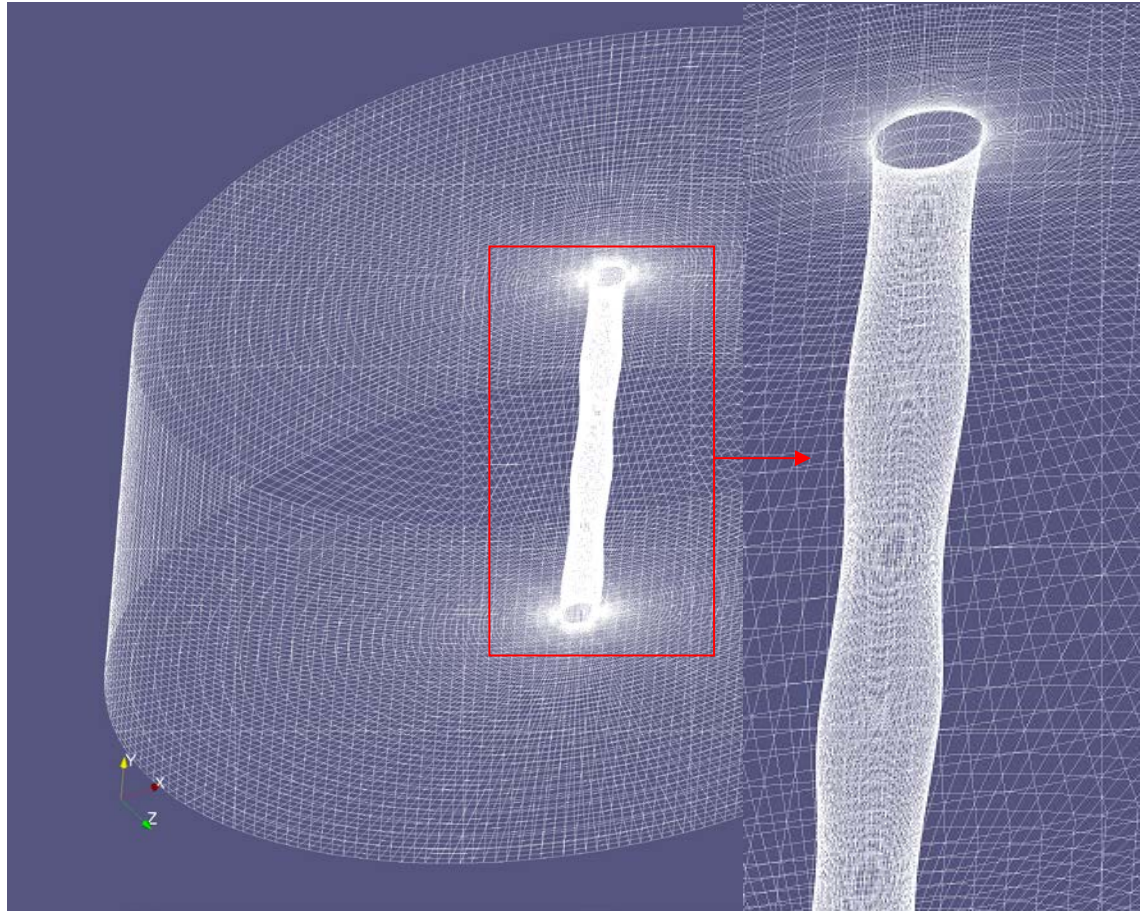
1) Microscopy Images



2) Transfer to CAD Model

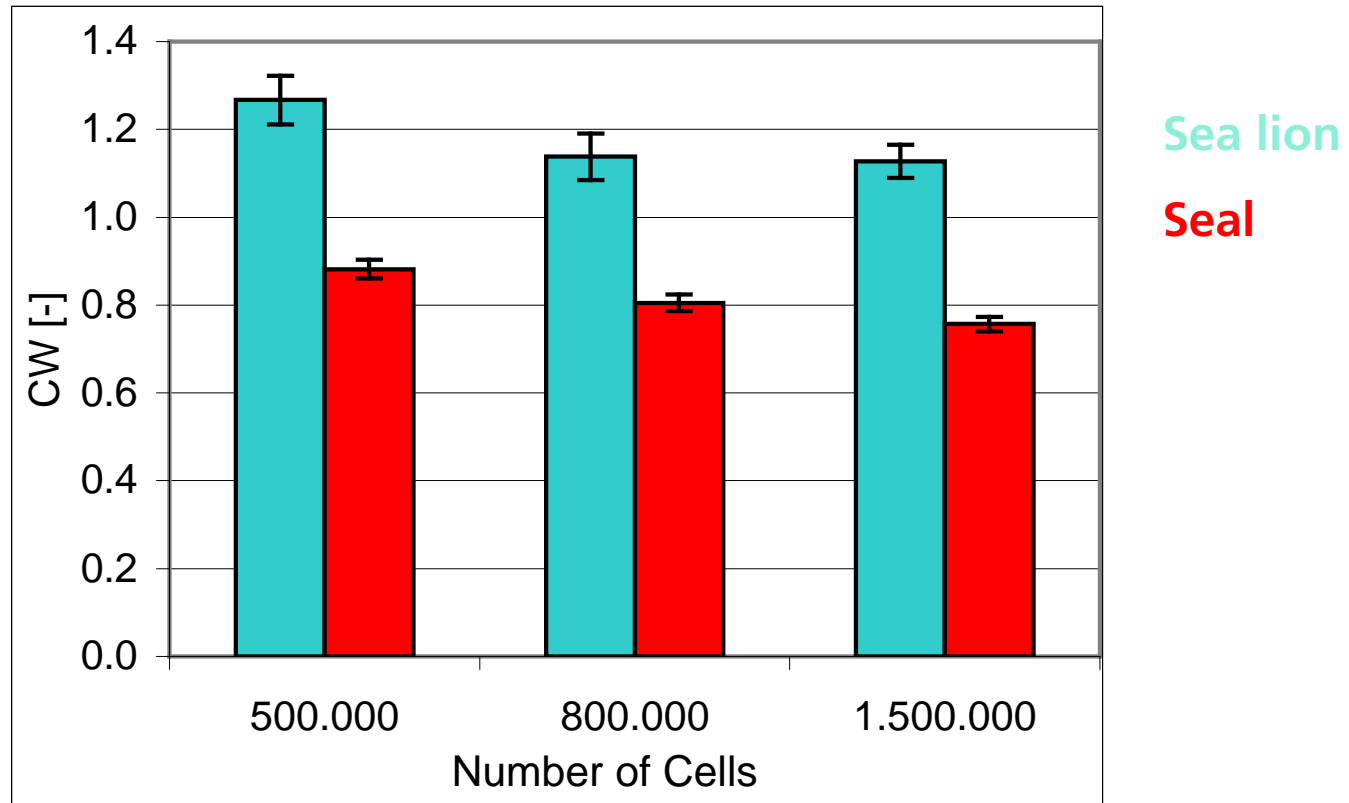


3) CFD Mesh



Flow Control – Flow Sensing With Seal Whiskers

➤ Results – Drag Coefficient

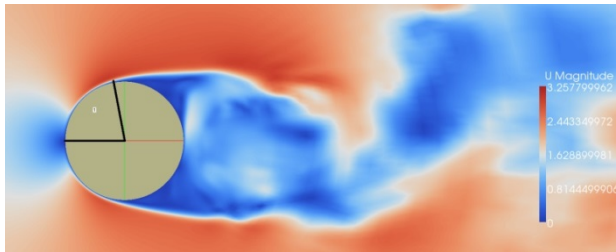


- C_D Seal about 30% reduced
- Undulated Structure minimizes drag!

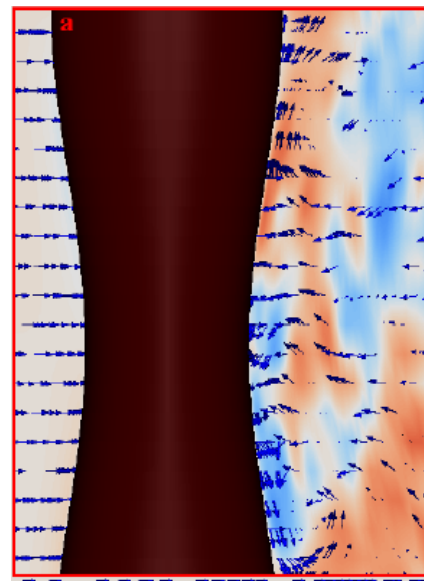
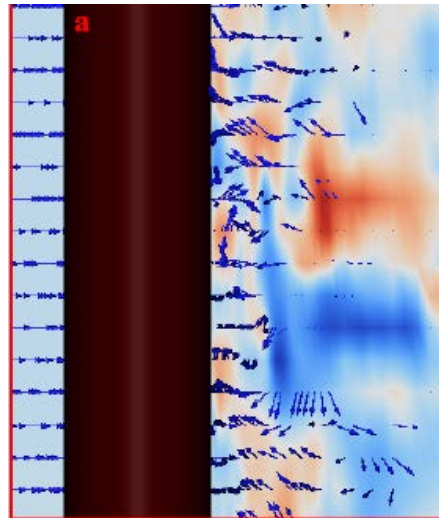
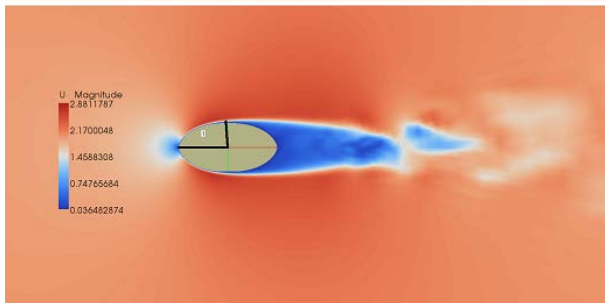
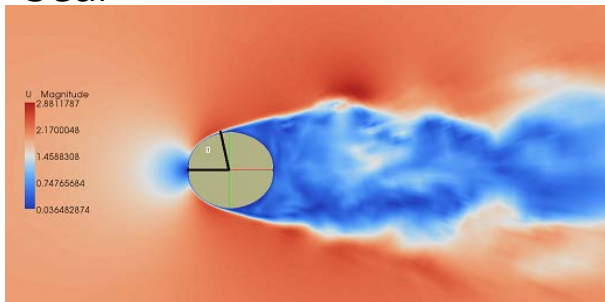
Flow Control – Flow Sensing With Seal Whiskers

➤ Results – Flow Visualizations

Sea lion



Seal

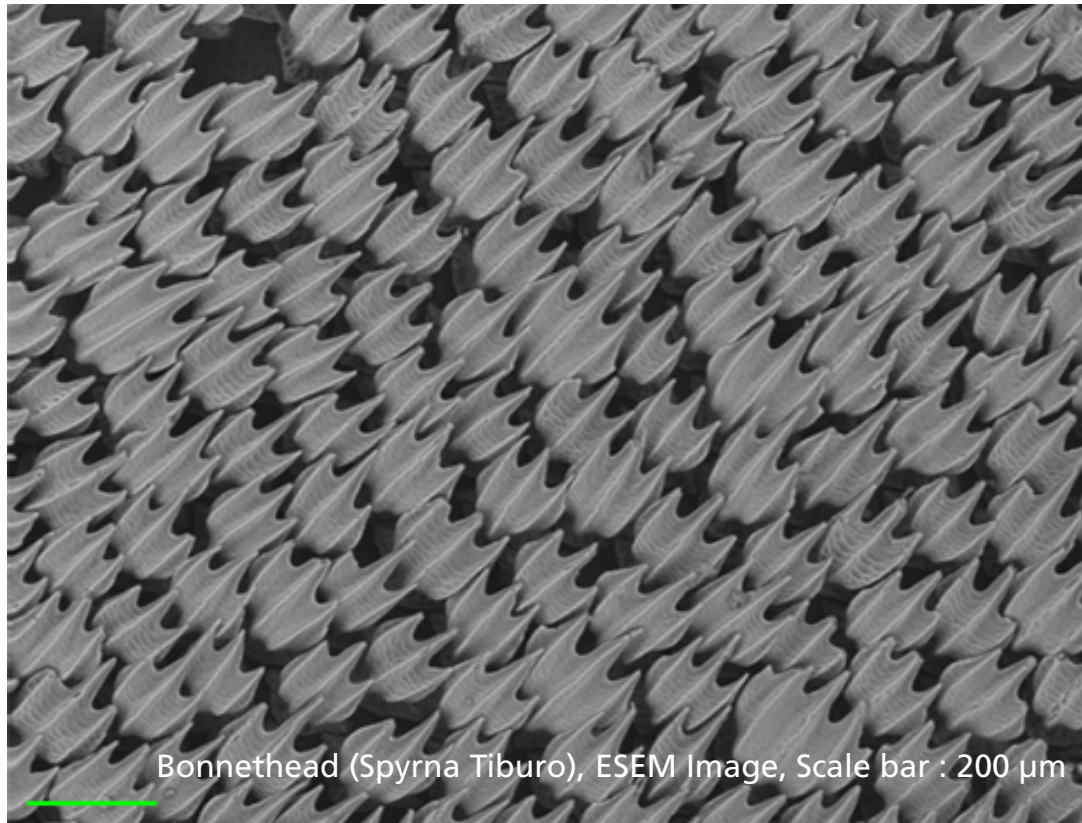


- trailing wake in average smaller, no periodical shedding
- reduced vortex-induced vibration (self-oscillation)
- reduced drag

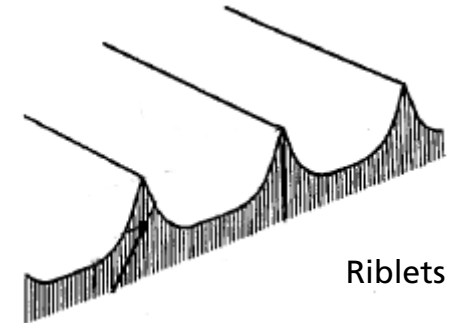
Flow Control – Hydrodynamic Function of Shark Skin

Oeffner and Lauder (2012): The hydrodynamic function of shark skin and two biomimetic applications. In *The Journal of Experimental Biology*.

Shark Skin



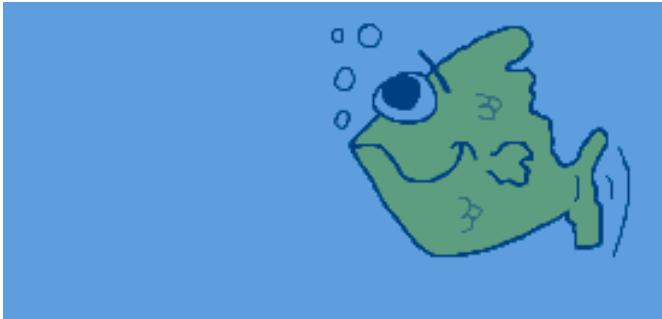
Biomimetic products



Flow Control – Hydrodynamic Function of Shark Skin

➤ Two types of drag

Rigid object



Moving object



- glides through water without changing shape and speed
 - ❑ e.g. gliding shark
 - ❑ e.g. aircraft/ship with riblets

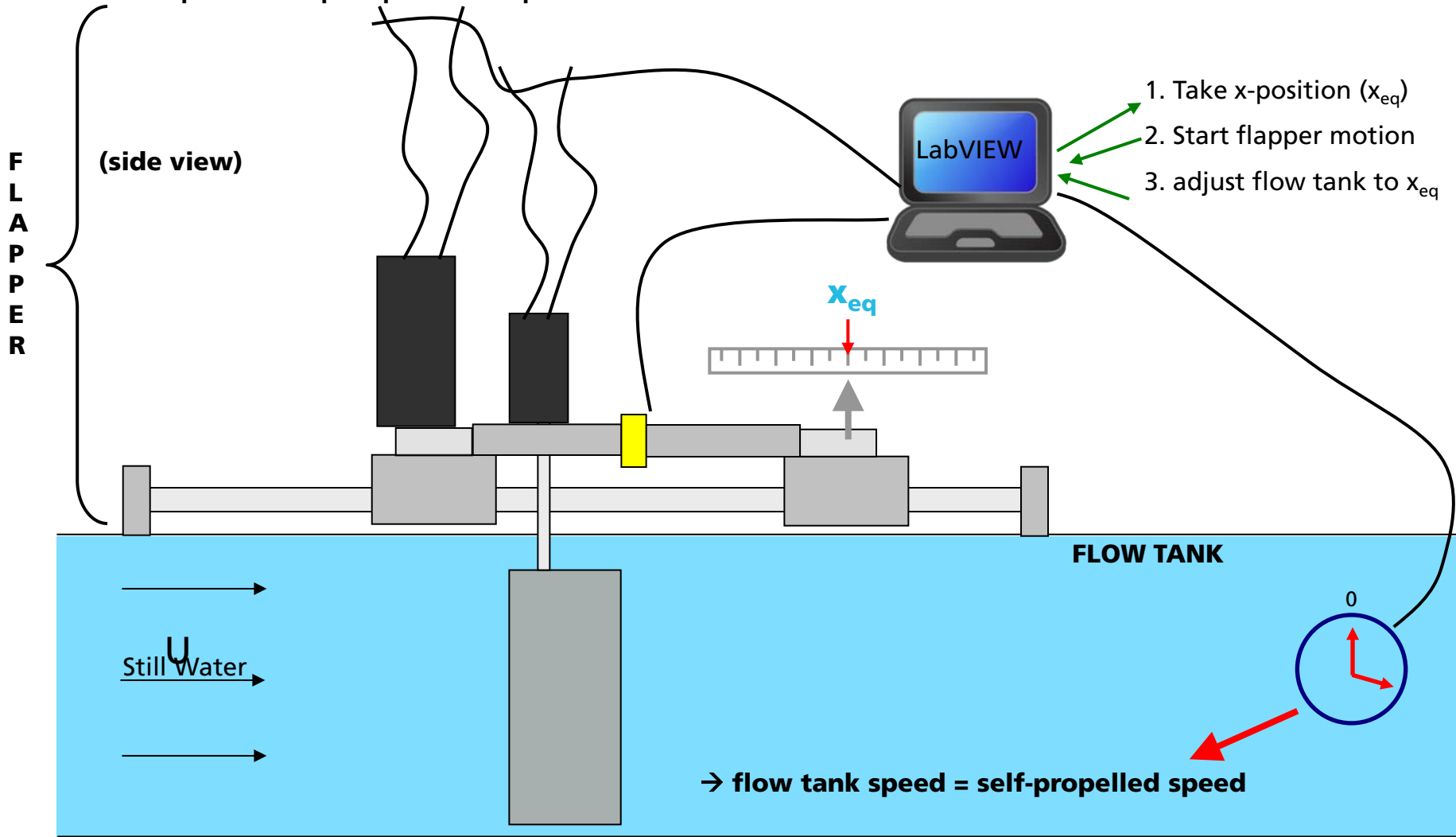
➤ **Static Drag**

- moves through water and is constantly changing shape and speed
 - ❑ e.g. swimming shark
 - ❑ e.g. swimming human (wearing swimsuit)

➤ **Dynamic Drag**

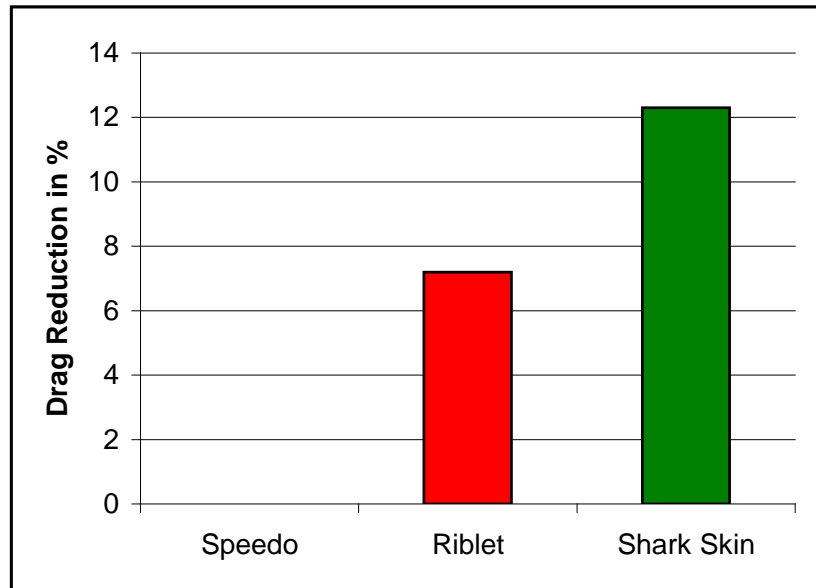
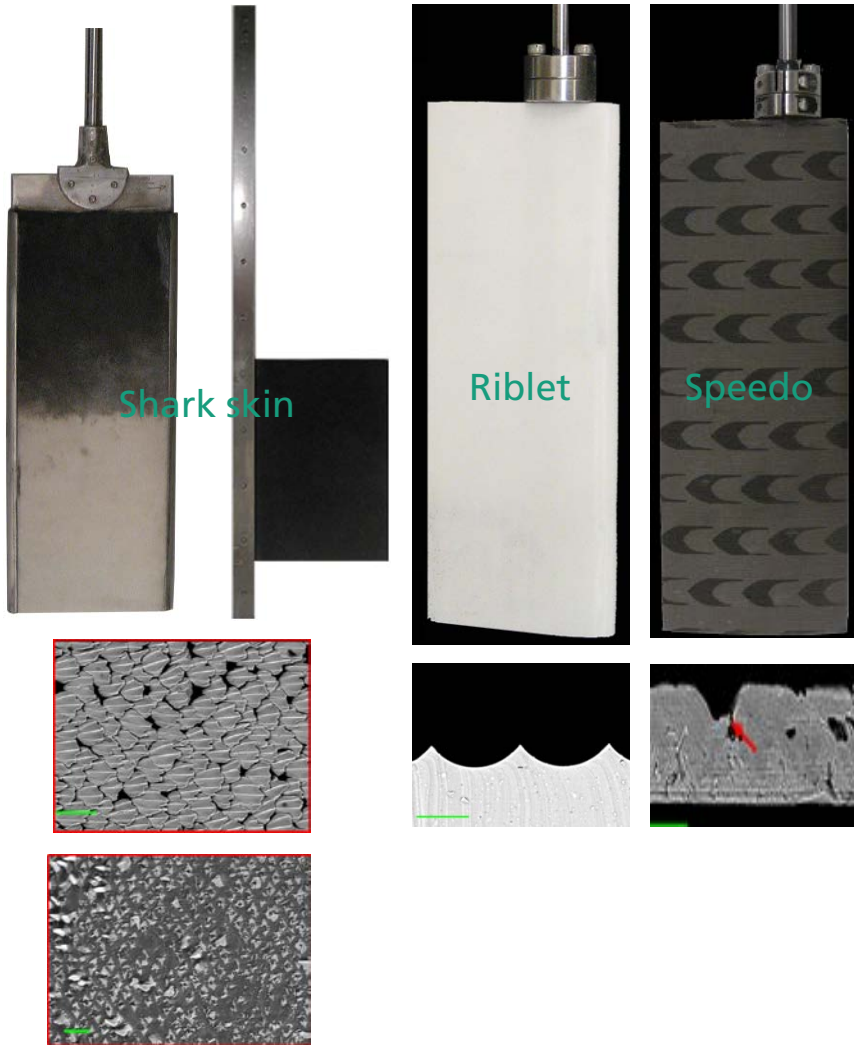
Flow Control – Hydrodynamic Function of Shark Skin

➤ Setup – Self propelled Speed



Flow Control – Hydrodynamic Function of Shark Skin

➤ Materials and Results

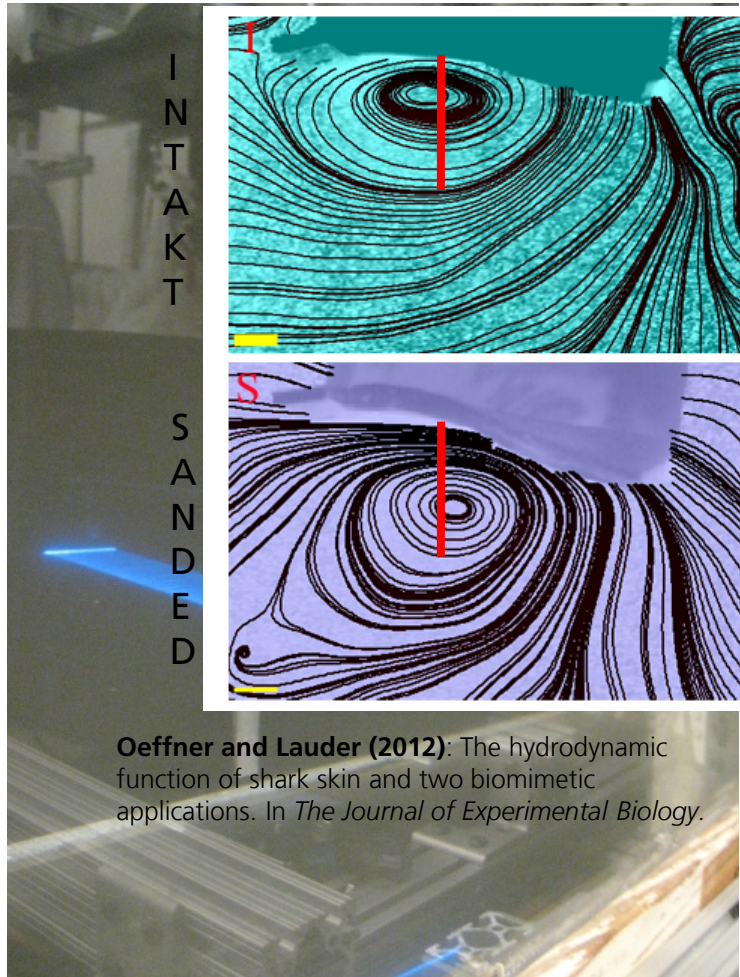


Drag Reduction:

- Speedo: 0%
- Riblet: 7.2%
- Flexible Shark Skin: 12.3%

Flow Control – Hydrodynamic Function of Shark Skin

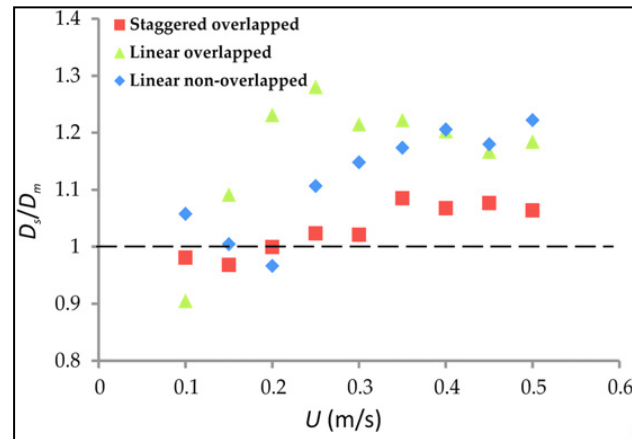
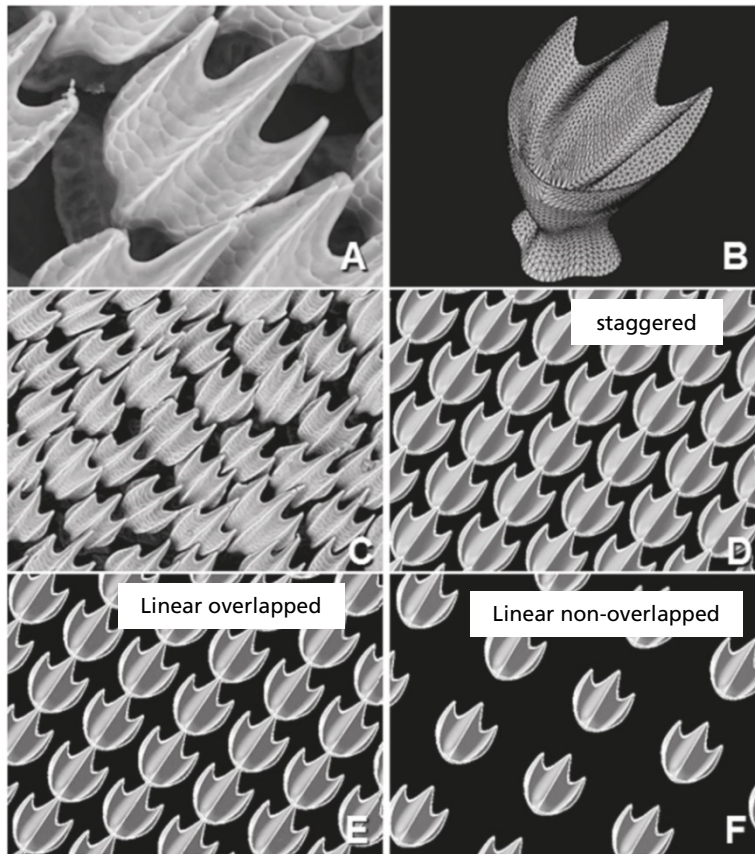
➤ PIV Experiments



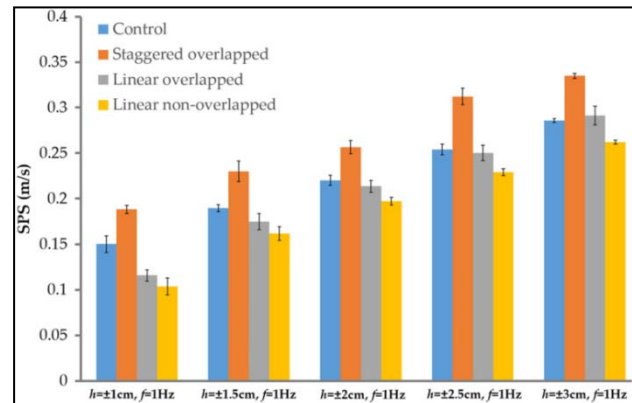
- Vortices generate suction forces
- Shark skin makes vortex to stay closer to surface
- suction forces are fully utilized
- optimal thrust production / drag reduction!

Flow Control – Hydrodynamic Function of Shark Skin

➤ Biomimetic Shark Skin



Static Drag Reduction
($D_{\text{Control}}/D_{\text{biomimetic}}$)



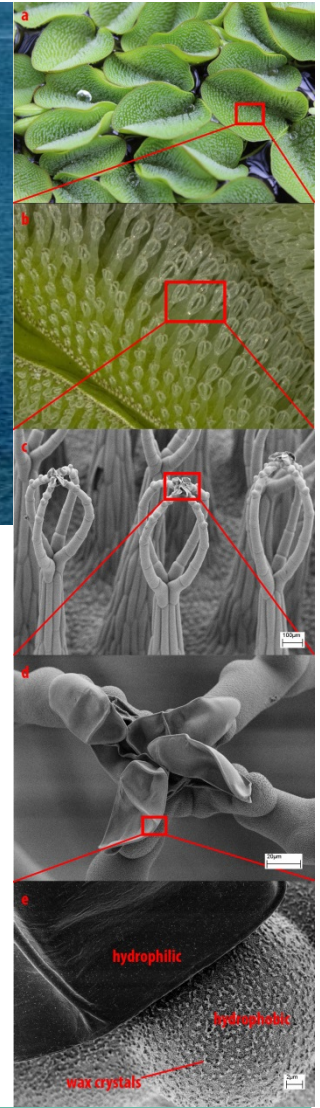
Dynamic Thrust (Drag)

Wen, et al. (2014): Biomimetic shark skin: design, fabrication and hydrodynamic function. In *The Journal of experimental biology*.

Wen, et al. (2015): Hydrodynamic function of biomimetic shark skin: effect of denticle pattern and spacing. In *Bioinspiration & Biomimetics*.

- Nature optimized fish for biological / dynamic motion
- Not as effective to stiff human-made technology (robots, ships, planes..)

Biomimetics - Salvinia Effect



Koch and Barthlott (2009): Superhydrophobic and superhydrophilic plant surfaces: an inspiration for biomimetic materials. In *Philosophical Transactions of the Royal Society of London A: Mathematical, Physical and Engineering Sciences*.

- Principle: hydrophobic surfaces + complex nano- and microstructure traps air when submerged in water for up to several weeks
- Biological Function: floating plant mats maintain function within air-layer
- Biomimetic Application: Applied to ship hull → ship would float on air-layer → Drag reduction of up to 30 %.

Questions

???