



Fraunhofer Institut
Informations- und
Datenverarbeitung

Josef Pauli

Karlsruhe

pauli@iitb.fraunhofer.de

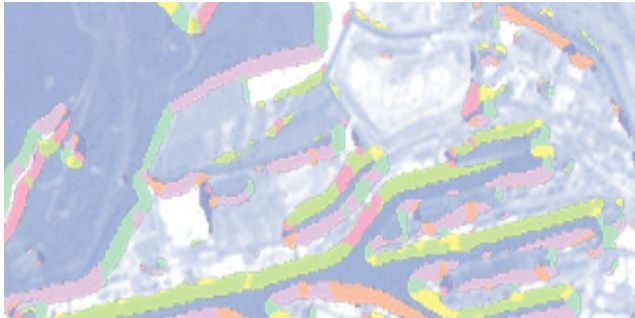
Business area

“Recognition Systems”

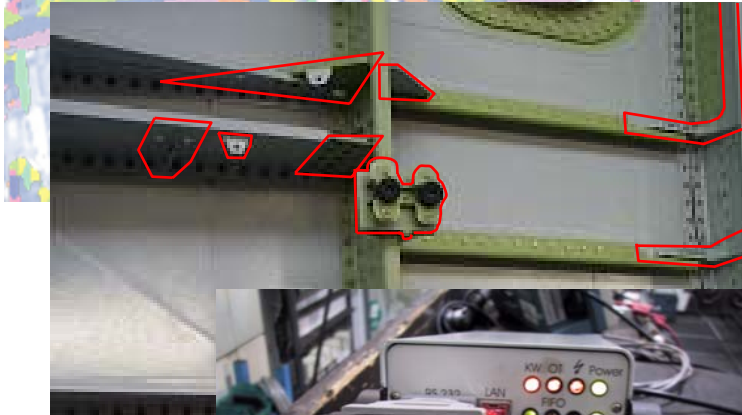
Business area “Recognition Systems” at IITB

Topics

- a. Image and signal processing
- b. Object/Situation recognition
- c. Assessment, Algorithm. learning
- d. Diagnosis of dynamical systems
- e. Embedded distributed systems



Security



Safety



Object recognition and tracking from mobile platforms

Contents at a glance

1. Screening
2. Data fusion
3. Geocoding
4. Tracking



1. Screening

Detection of regions of interest

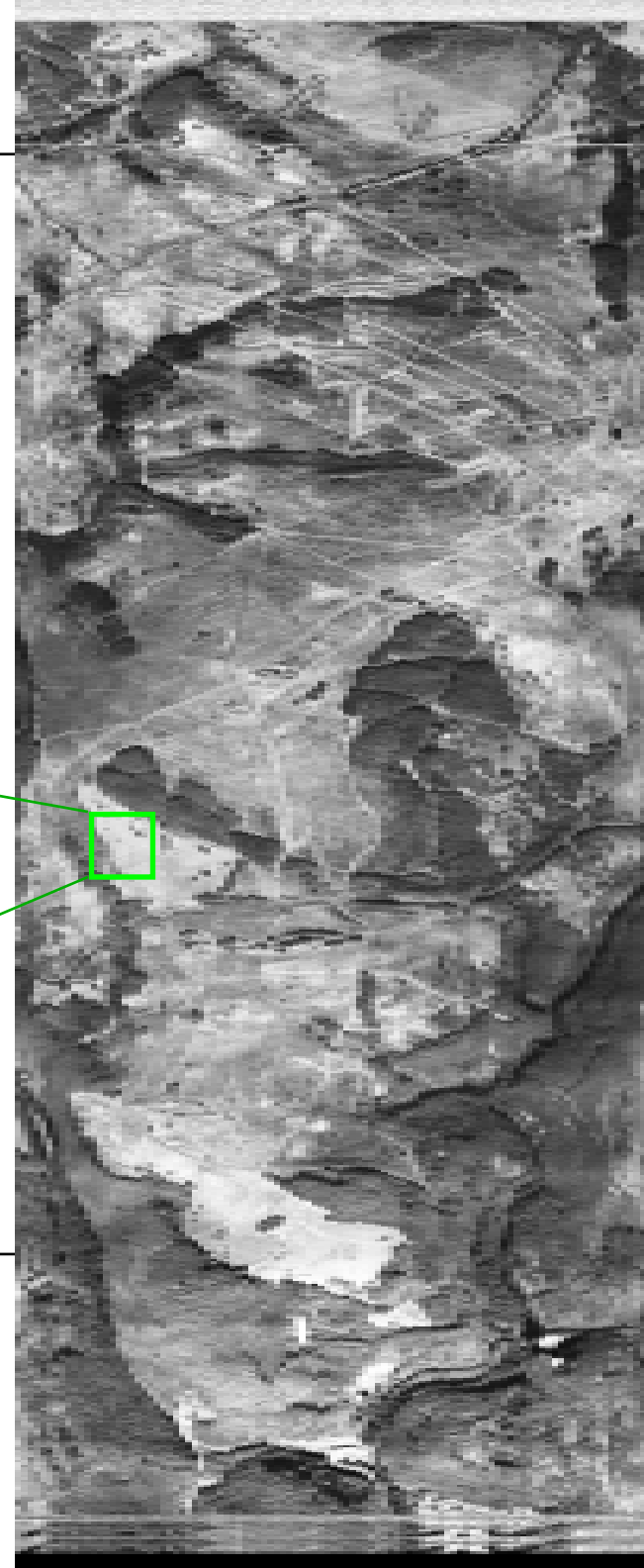
Infrared-Linescanner

Image dimension

- 12.000 x 240.000 pixels



Zoom-Window



Regions of interest built up from individual target hypotheses



Correcting a phantom image



Correcting a phantom image



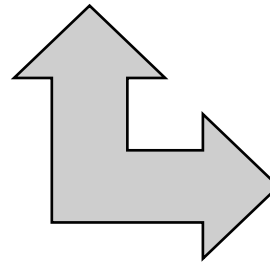
2. Data fusion

Fusion of slanted view and orthophoto



Slanted view

Projective
transformation



Orthophoto



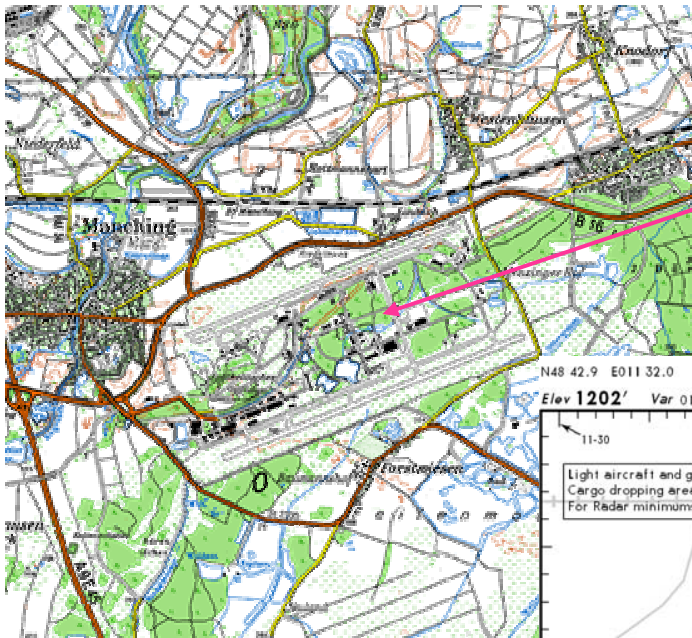
Fusion of slanted view and orthophoto

**Overlay of slanted view
and projected (warped)
orthophoto**

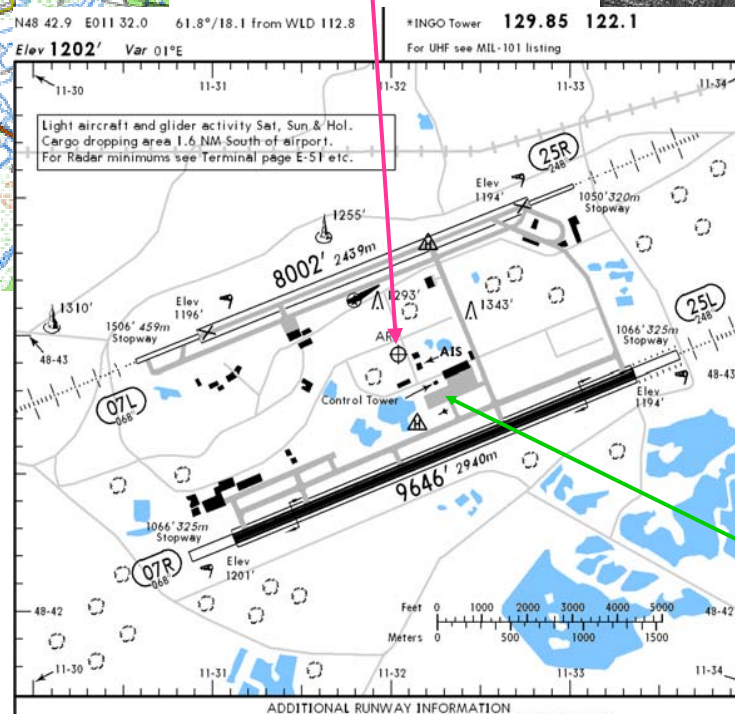


3. Geocoding

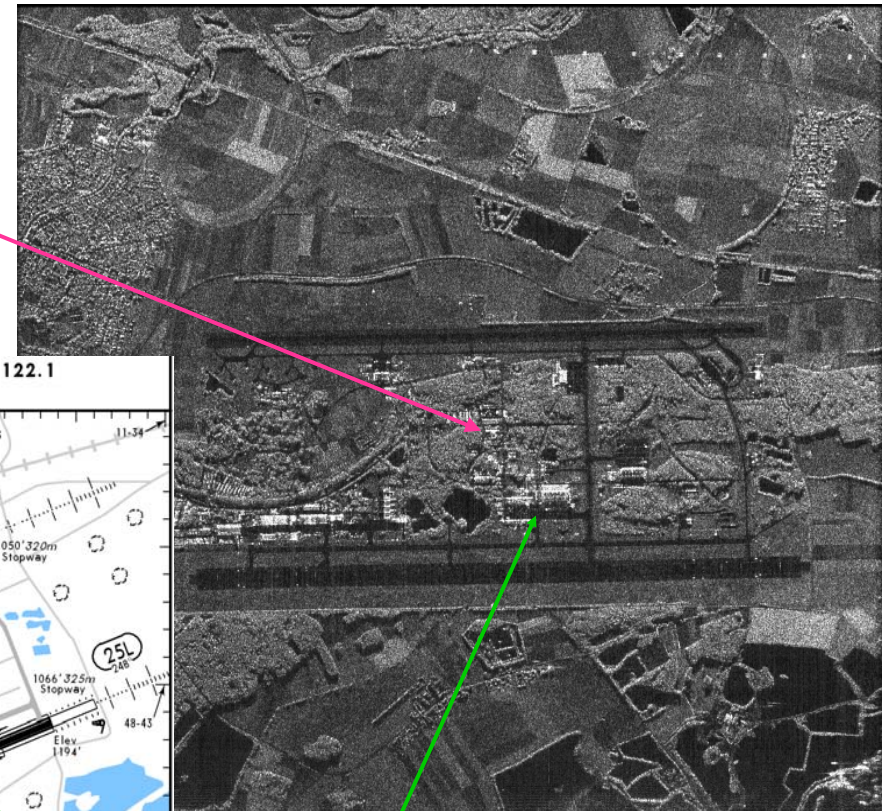
Corresponding sites between image and maps



Topographical map



Special map for pilots



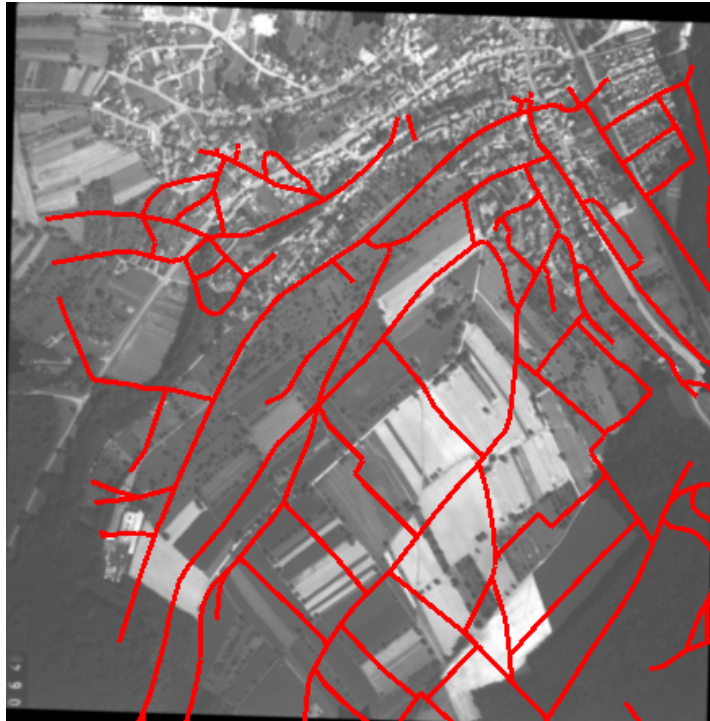
SAR-image



Automatic geocoding of IR-image



Fine-tuning of the image-to-map transformation



4. Tracking

Stabilizing and mosaicking of images (from helicopter)



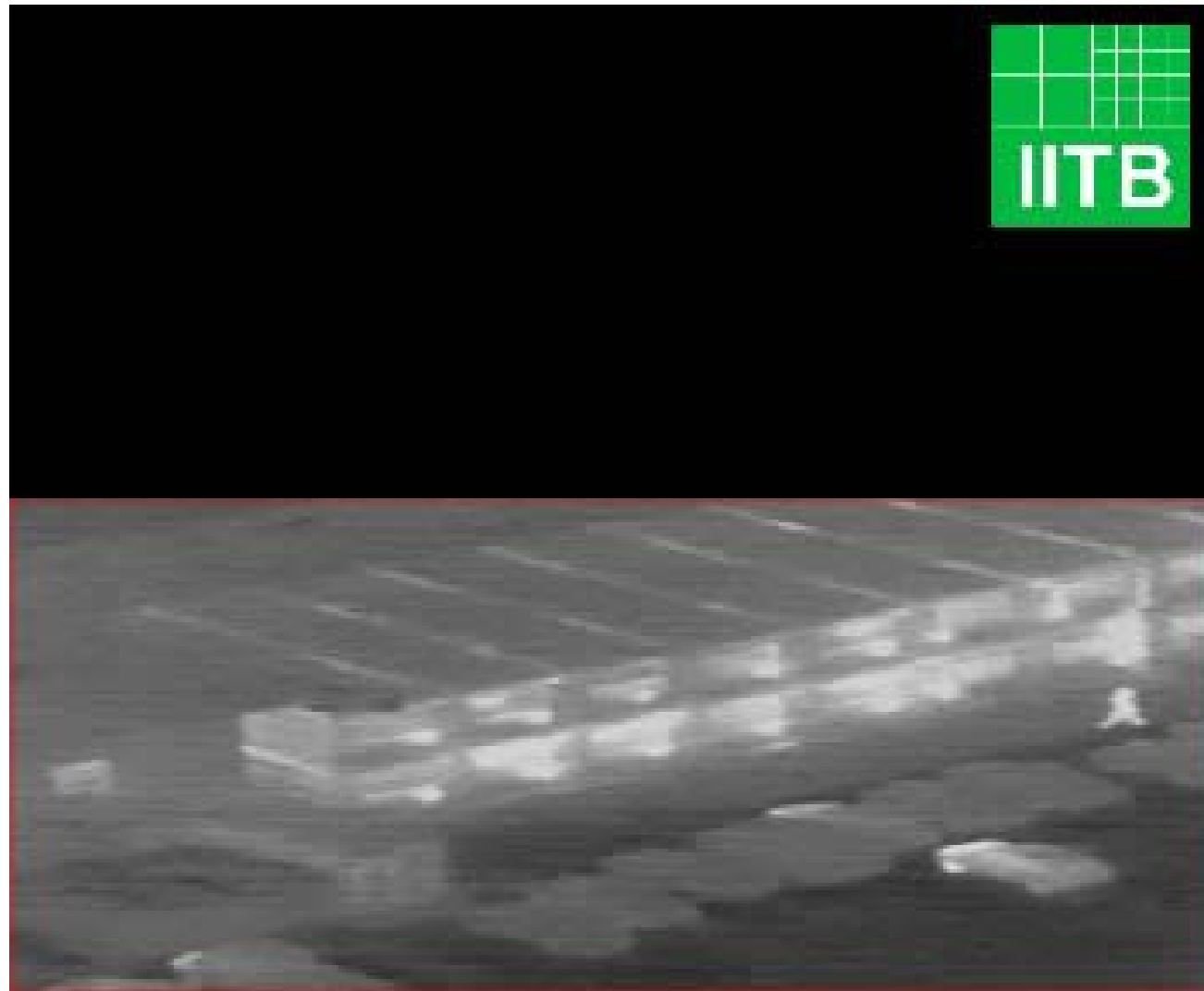
Ground surveillance and people tracking (from helicopter)



Ground surveillance and people tracking (from helicopter)

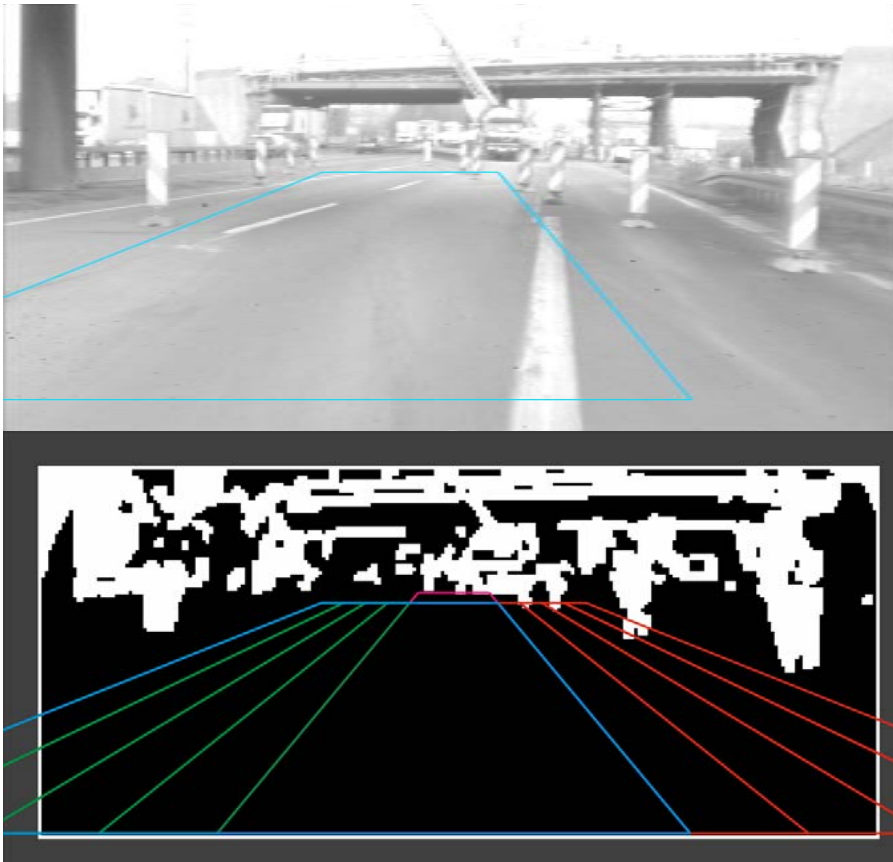


Ground surveillance and people tracking (from helicopter)

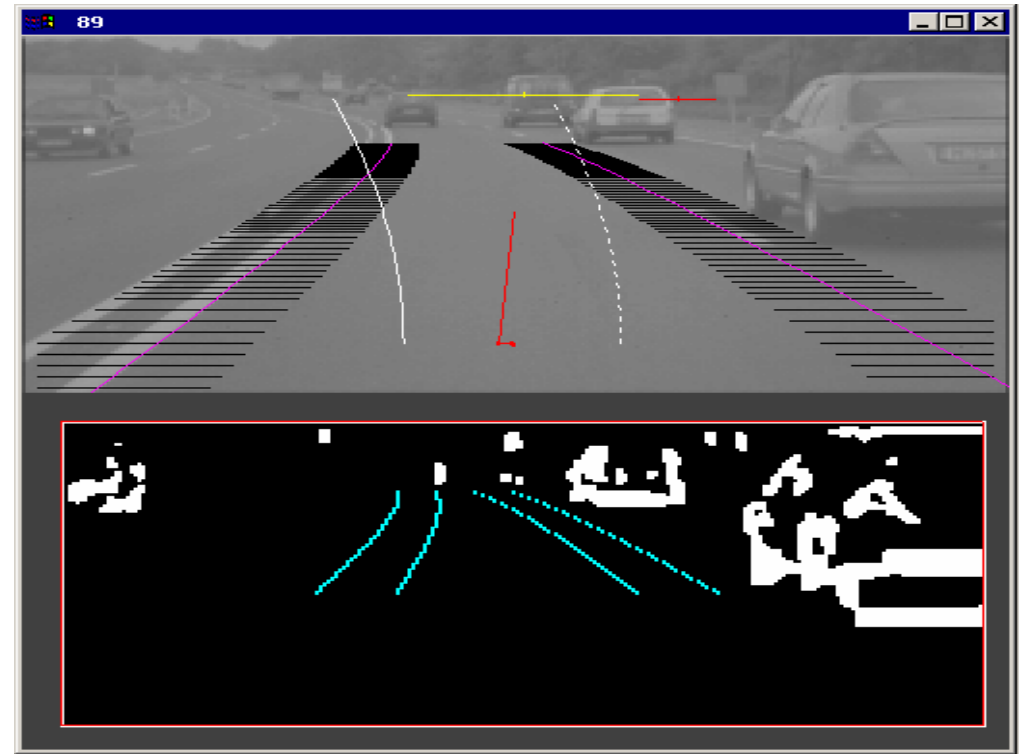


Driving assistance (camera-equipped car)

Free space detection



Relative motion detection



Discussion