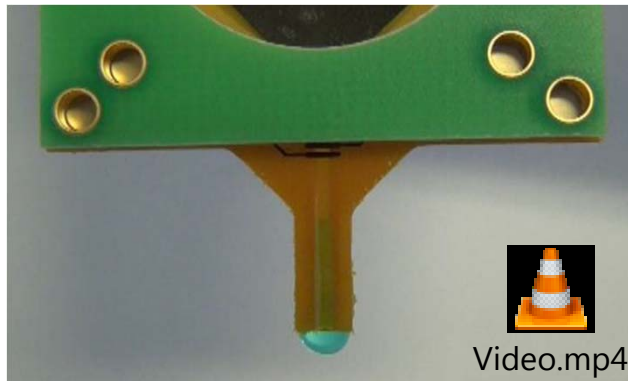

Integration of CNT-based actuators for bio-medical applications

Example printed circuit board CNT actuator pipette



Fraunhofer IPA, Germany
AIST Kansai, Japan

Besoncons, France
11.07.2014

Raphael Addinall
Raphael Neuhaus

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Fraunhofer IPA as part of the Fraunhofer-Gesellschaft

Europe's largest applied research organization



**Fraunhofer Institute
for Manufacturing Engineering
and Automation IPA**

- One of the largest single institutes of the Fraunhofer-Gesellschaft
- More than 50 years of experience
- Competent at implementing innovations into industry



German-Japanese Cooperation

**Fraunhofer Institute for
Manufacturing
Engineering and
Automation (IPA)**

Department Functional
Materials

**AIST Kansai
National Institute of
Advanced Industrial
Science and Technology
(AIST)**

Research Institute for Cell
Engineering



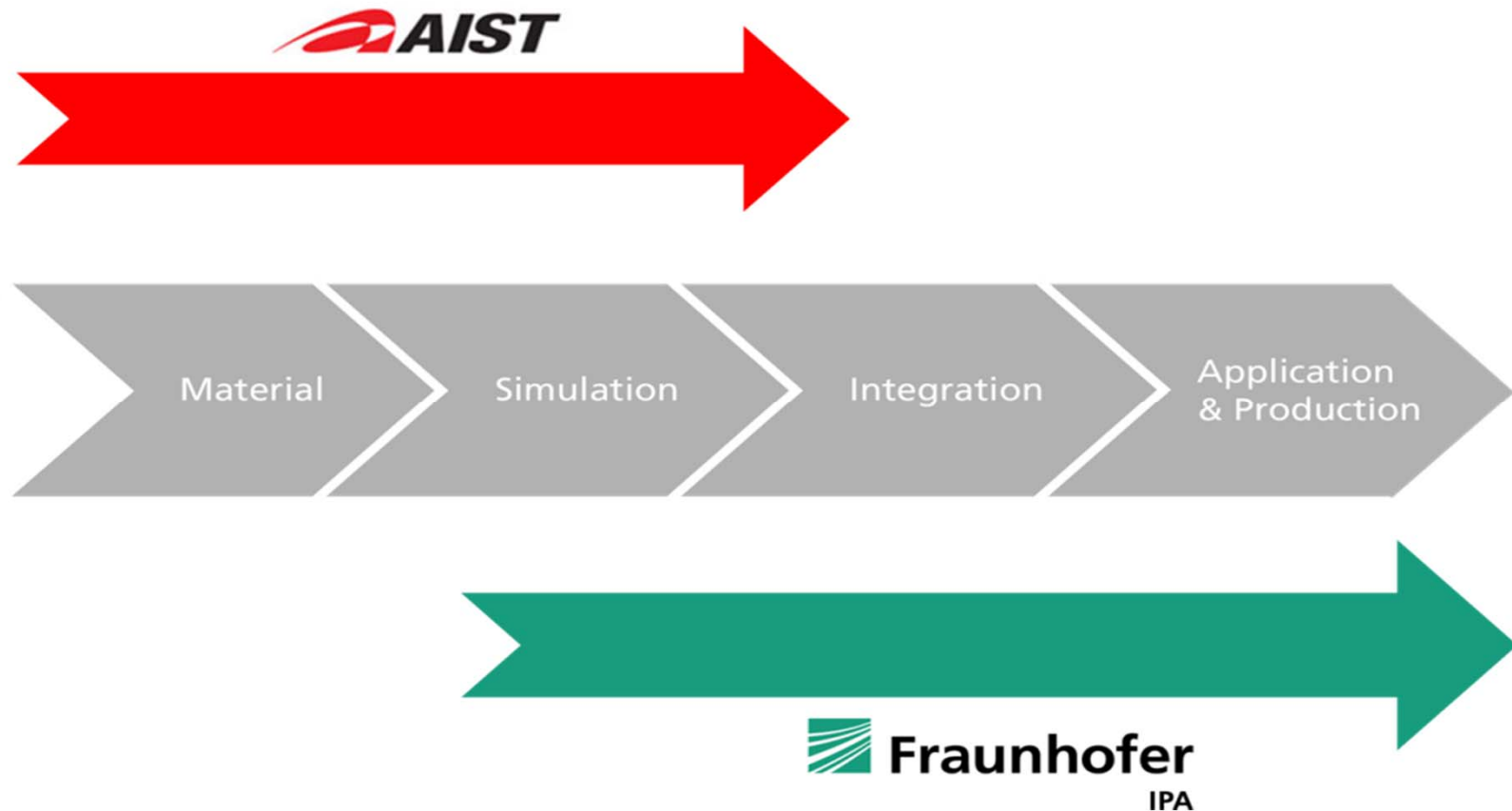
Picture source: <http://cio-perspectives.com>

3



Complementary Workflow of AIST and Fraunhofer IPA

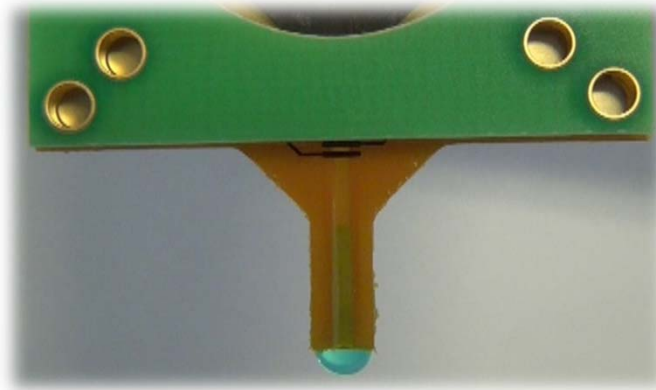
Sharing and complementing Expertise



4

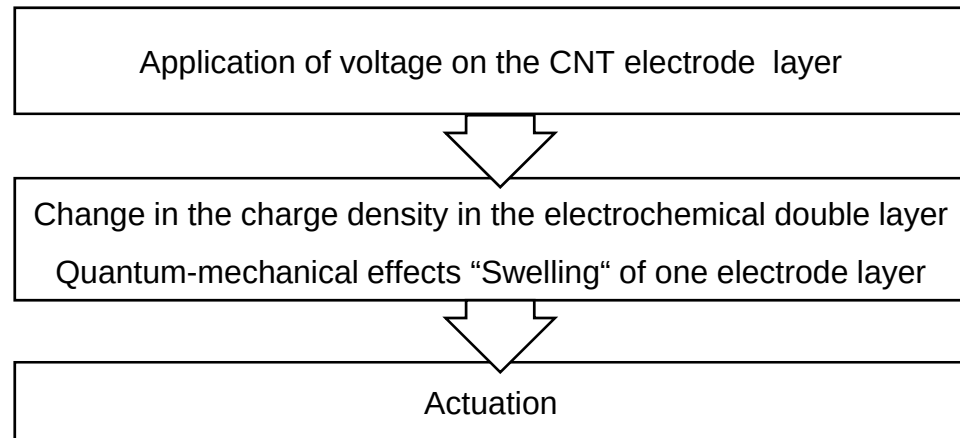
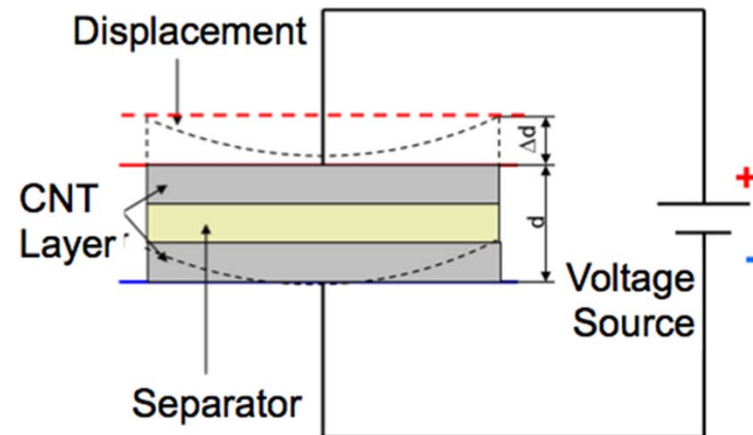
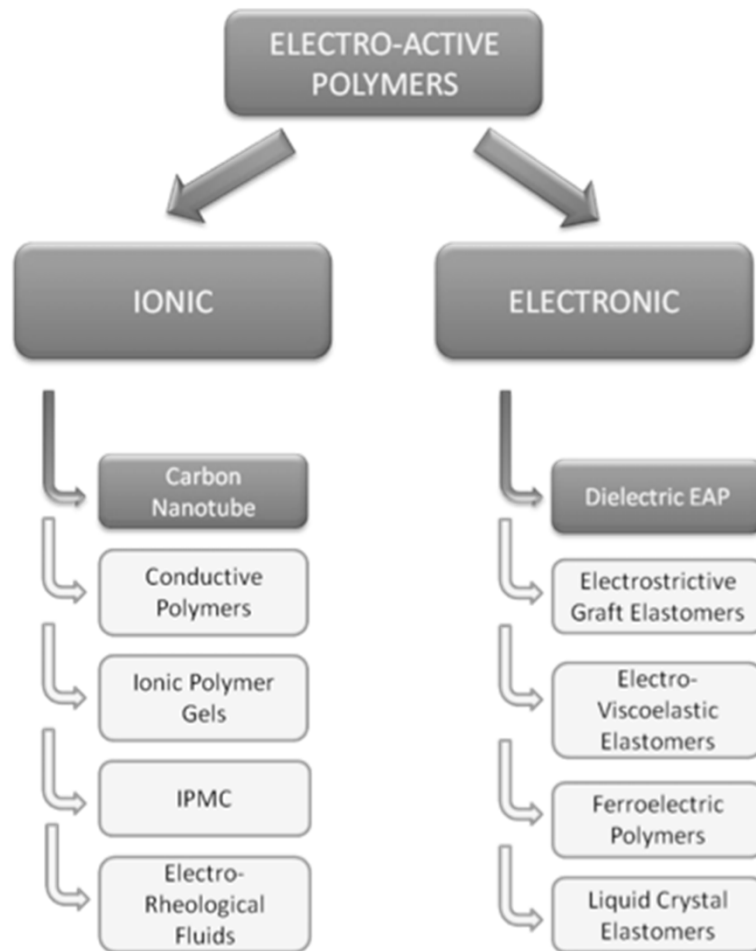
Overall aim of our collaboration

- **The need for integration:**
 - use actuator technology in a specific application
- **Exploring the design space and optimization:**
 - Finite element simulation of actuators – compare and predict actuator behaviour
- **Production technology:**
 - Both printed circuit boards and actuators



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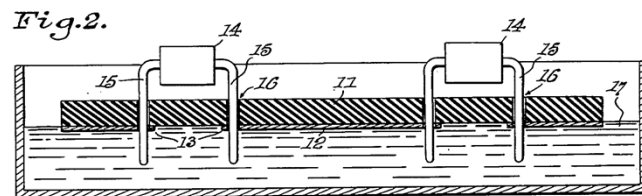
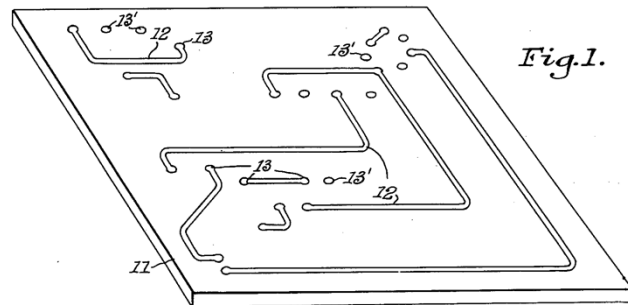
Actuators



6

Printed Circuit Board (PCB) Technology

July 31, 1956 M. ABRAMSON ET AL 2,756,485
PROCESS OF ASSEMBLING ELECTRICAL CIRCUITS
Filed Aug. 28, 1950

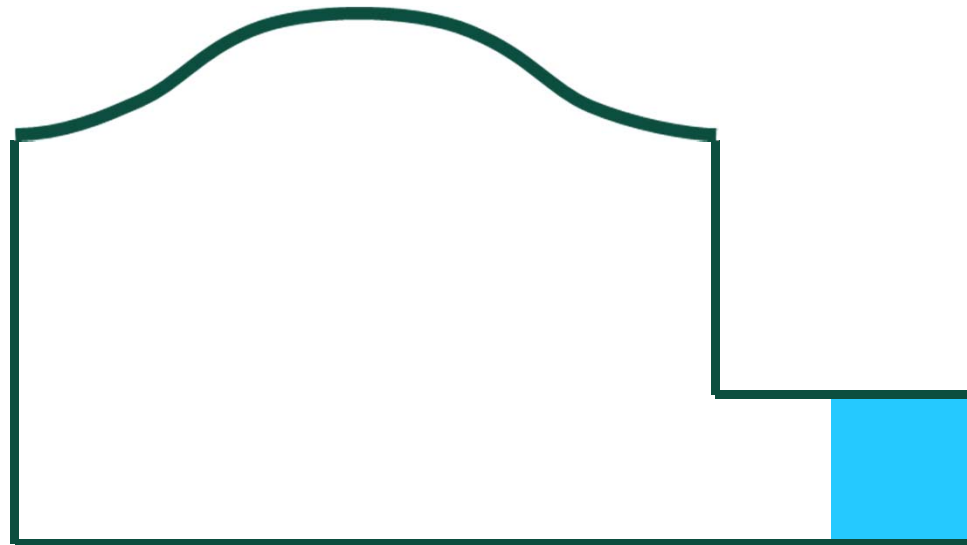


First patent-1956, M. Abramson et AL

- Standardized interfaces
(mechanical/electrical)
- Standardized production
- Easy handling
- Easy integration of driver electronics
- Integrated electrodes and connection leads

Principle: Displaced Volume

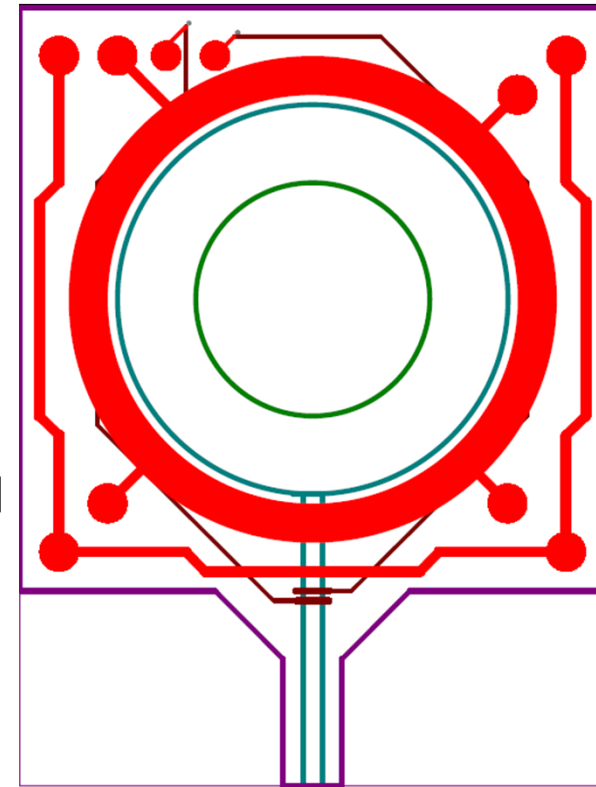
Overall aim

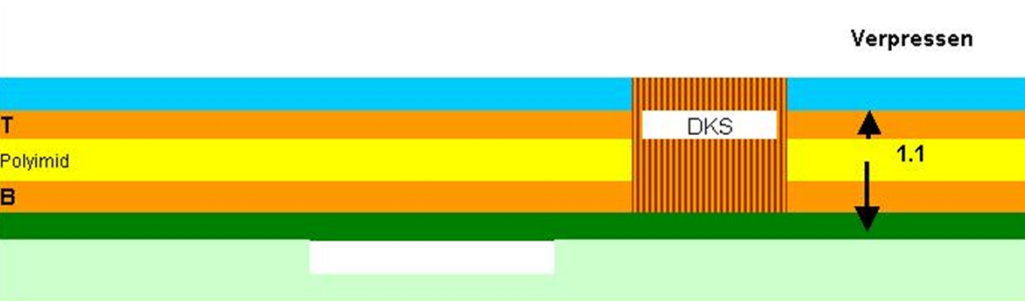
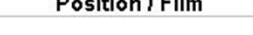


Design aim for actuation: $> 100 \mu\text{m}$ in center, $> 10 \mu\text{l}$ displacement

CAD PCB Design

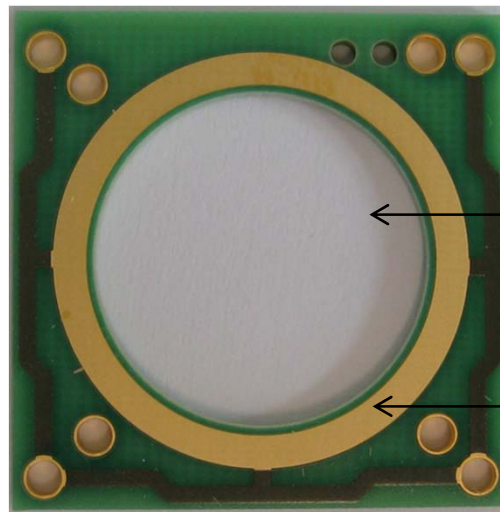
- 2D CAD design on several layers
- Layer stack:
- PCB boards made of standard FR4 material
- 50 µm polyimide foil or PTFE



		Verpressen	Material	Position / Film	
T	B		Deckfolie		63
			Cu: 18µ -> 35µ		35
			Polyimid: AP8525		50
			Cu: 18µ -> 35µ		35
			Noflowpreg		50
			FR4 Kern 1,5mm		1500
Arbeitsablauf:					Kürzel:
Source of layer stack: Contag AG, Berlin					

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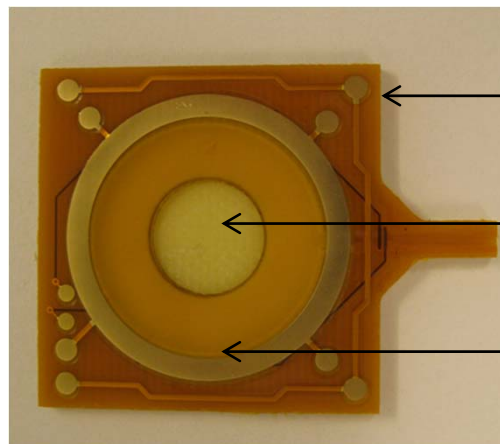
Printed circuit board (PCB) Design



← Holes/vias with and without metallisation

← Mill any inner geometry

← Etch any electrical trace geometry into copper



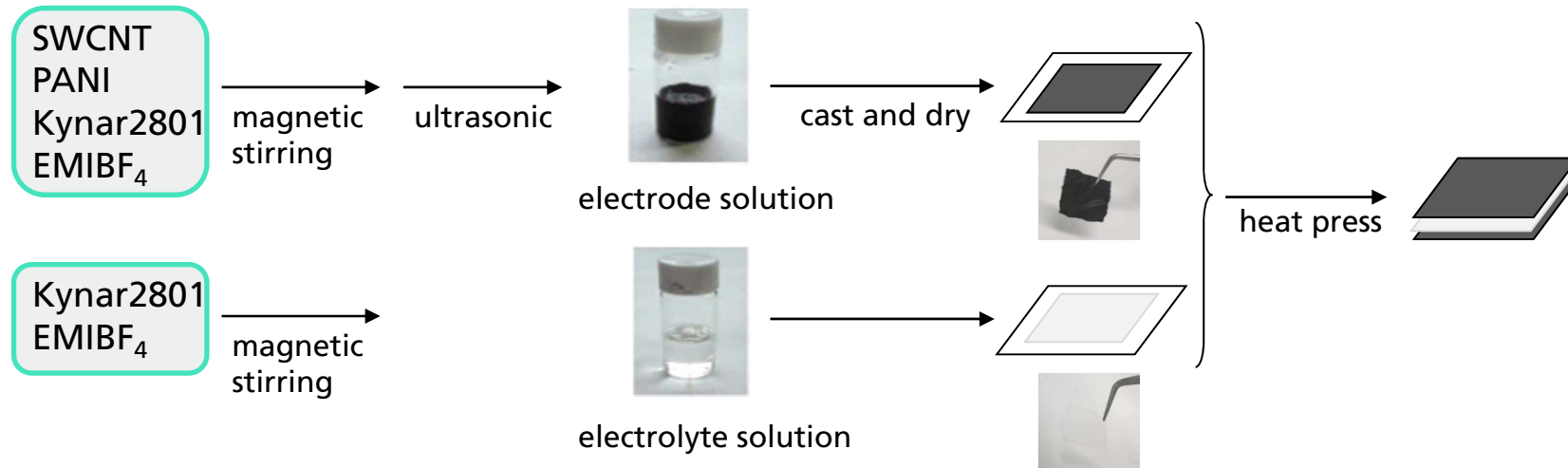
← Nickel/gold plating

← Lower stiff layer

← Flexible Membrane ring

10

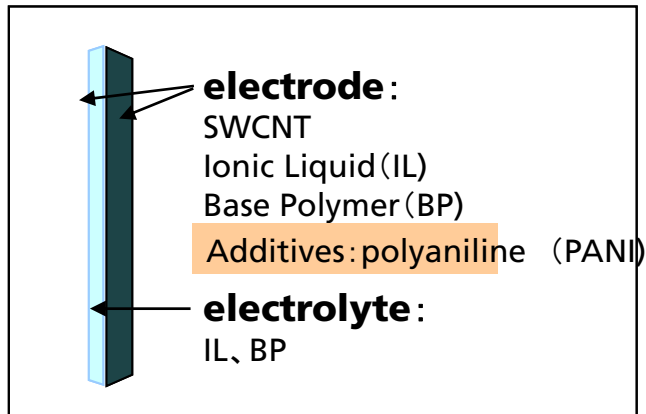
Fabrication process of the three-layered actuator



【Characteristic data of PANI】

20 wt% polyaniline on carbon black
particle size: ca. 40 nm
conductivity: 40 S/cm
BET surface area= 690 m²/g

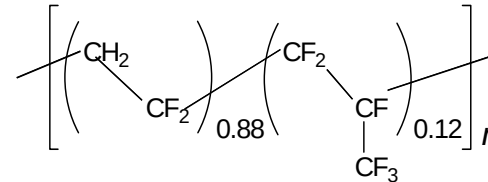
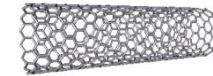
【Structure of nanocarbon polymer actuators (three-layered) and components】



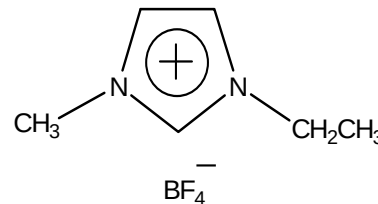
- stable and long-life actuation **in air**
- low voltage drive (within $\pm 3V$)
- easy fabrication by a casting method

SWNTs: Single-walled carbon nanotubes by HiPco method

BP: PVDF-HFP(kynar2801)



IL: EMIBF₄



Electrode:SWCNT/PANI(50/50)-2IL

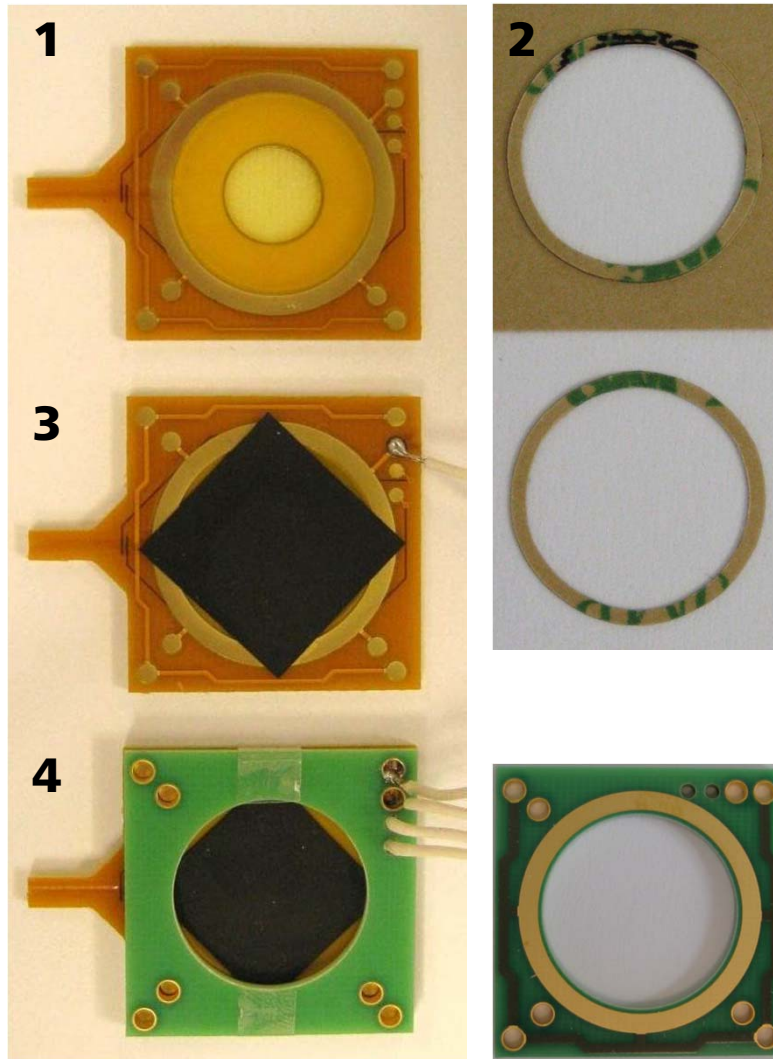
components: **SWCNT/PANI**/kynar2801/EMIBF₄=**50.7 mg/50.6 mg**/80.6 mg/240.9 mg
(**11.99 wt%/11.97 wt%**/19.06 wt%/56.98 wt%)

Electrolyte: kynar2801/EMIBF₄

components: kynar2801/EMIBF₄=200.4 mg/200.1 mg
(50.04 wt%/49.96 wt%)

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Integration & connection methods



Mechanical:

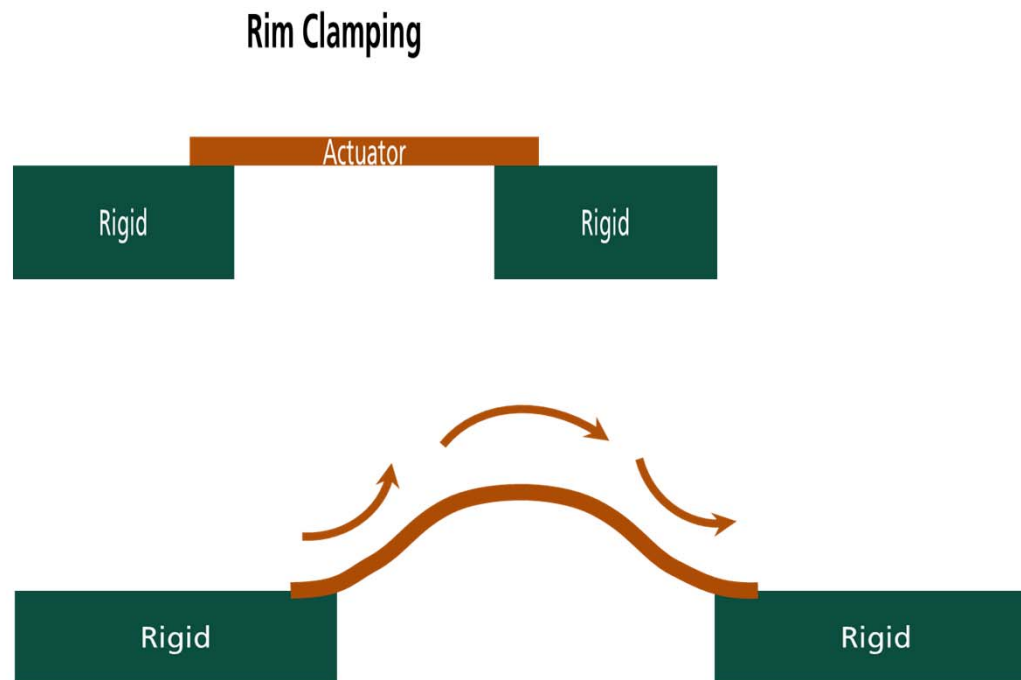
- Gluing (Epoxy, „super glue“, etc.)
- Tape (3M Double sided) laser cut

Electrical:

- Soldering, Reflow soldering
- Conductive glues or glue tapes
- Non-standard: Low temperature solders
- Clamping with top electrode (PCB)

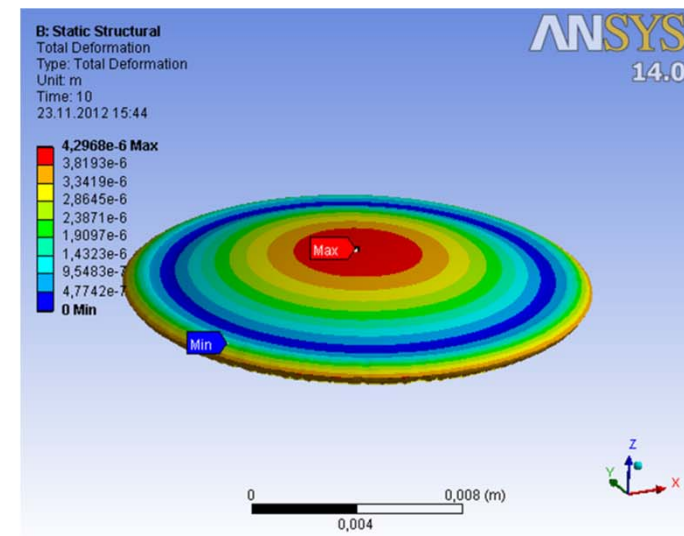
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Positioning of actuator to PCB (no soft intermediate layer)



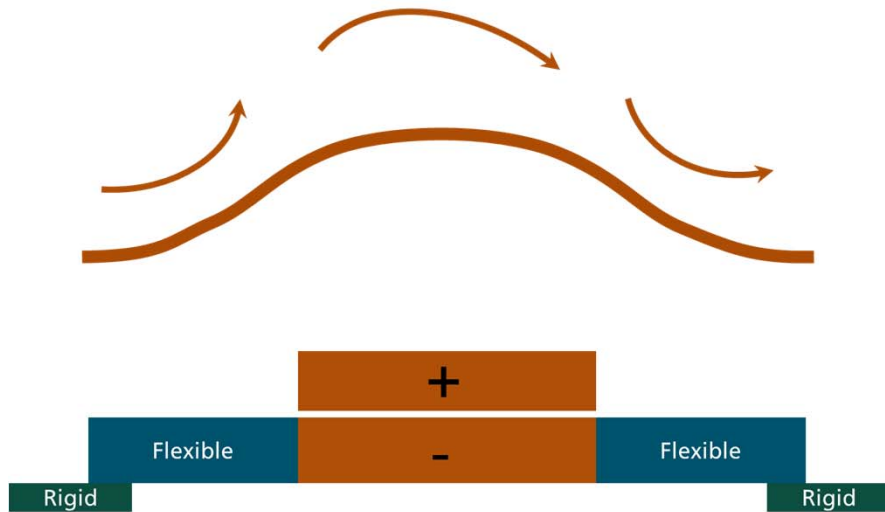
Rim Clamping: Non-constant Curvature

Soft to hard - rim clamped actuator

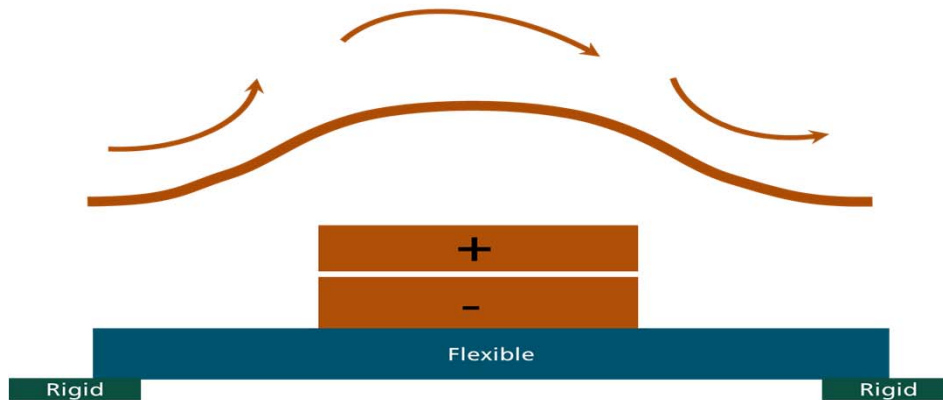


Positioning of actuator to PCB (with soft intermediate layer)

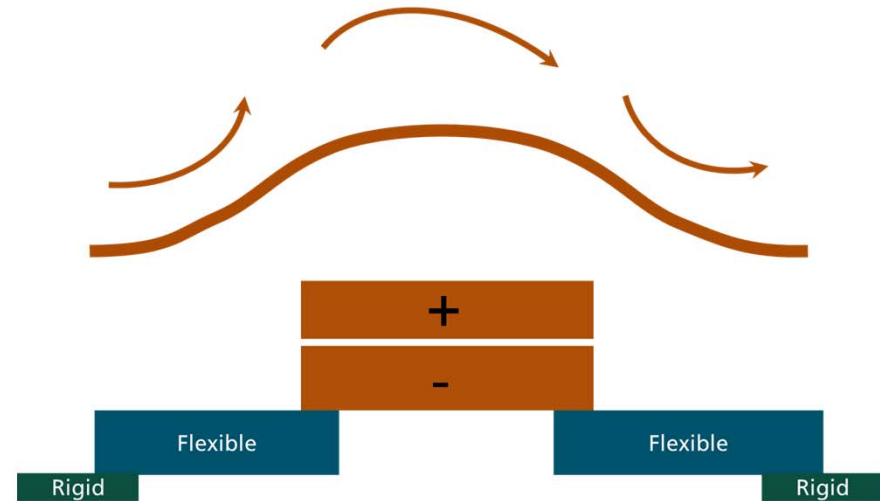
Setup with Passive Flexible Layer



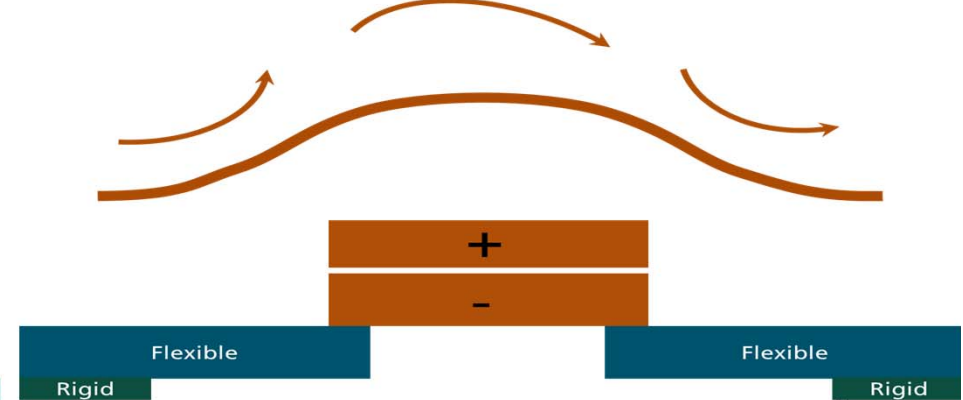
Closed Membrane Setup



Setup with Passive Flexible Layer 2



Open Membrane Setup



Tensile Test Data and Digital Material Models

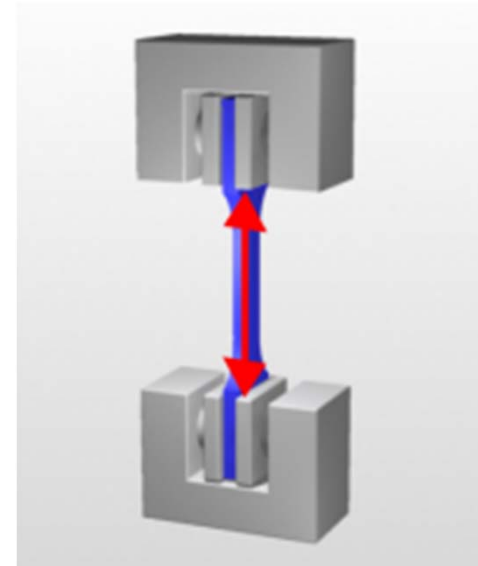
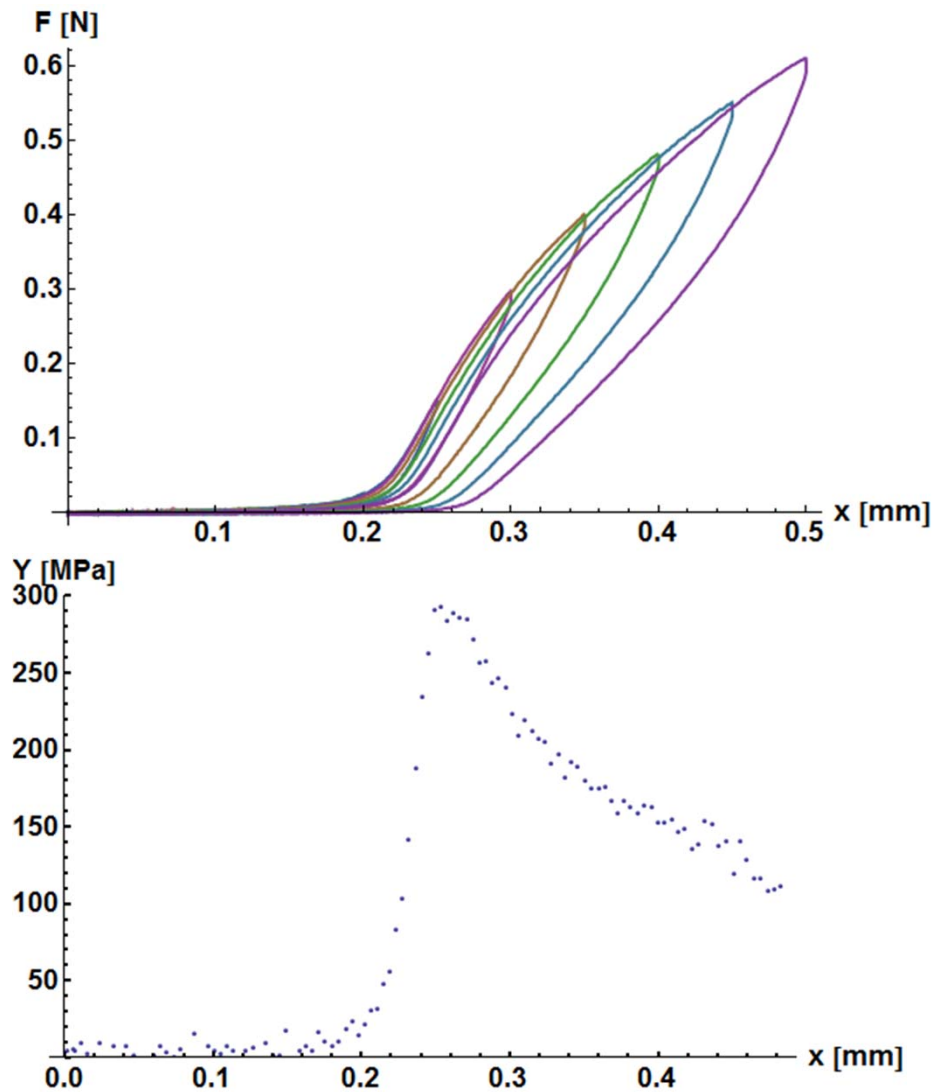
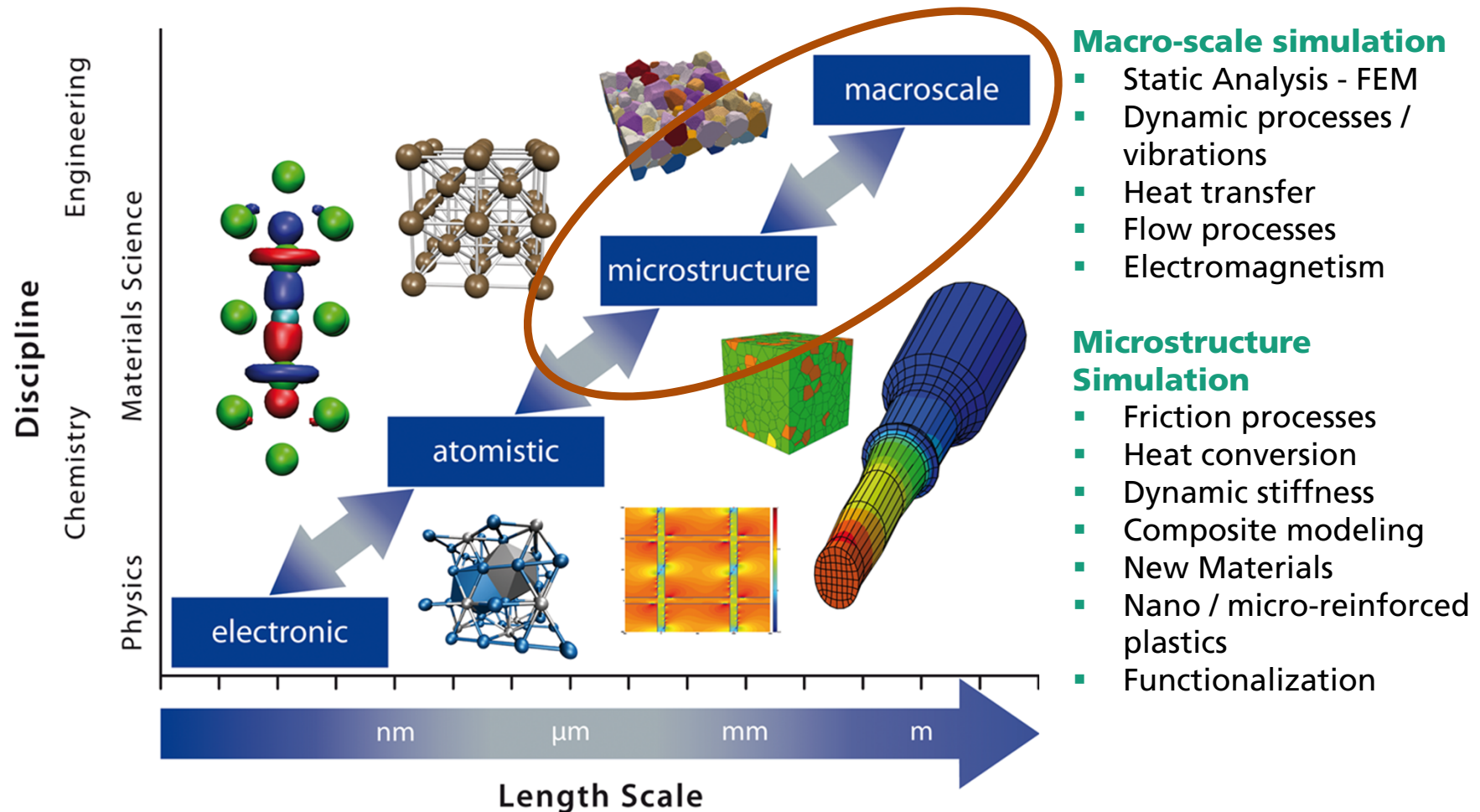


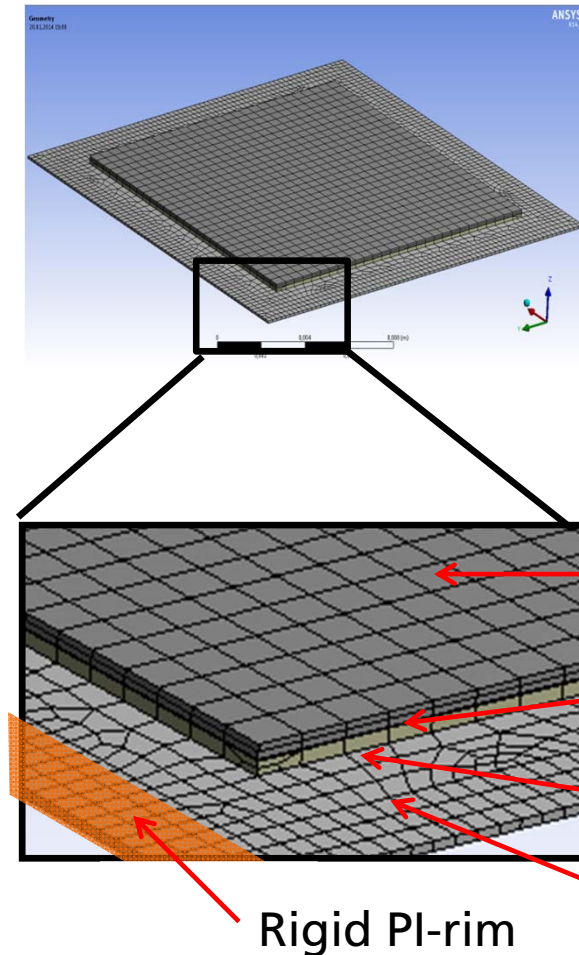
Image source: Zwick
(Software)

Simulation

Multi-scale simulation



Meshing of electrode, separator and polyimide layers



- Using material parameters depending on strain
- Estimation of Young's Modulus
- Fitted E modulus found to be 42MPa
- To match the measured actuation force

Upper electrode

Electrolyte separator

Lower electrode

Rigid PI-rim

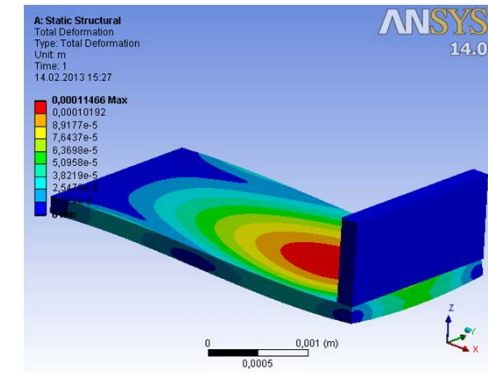
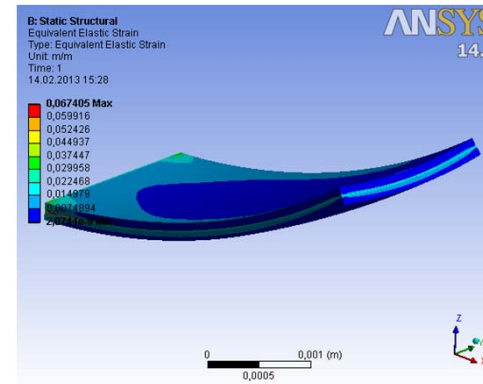
Flexible polyimide layer

Matching Experimental Data and Linear Elastic Theoretical Model

1) Match effective strain 0.9 % by displacement

2) Match Young's Modulus with force

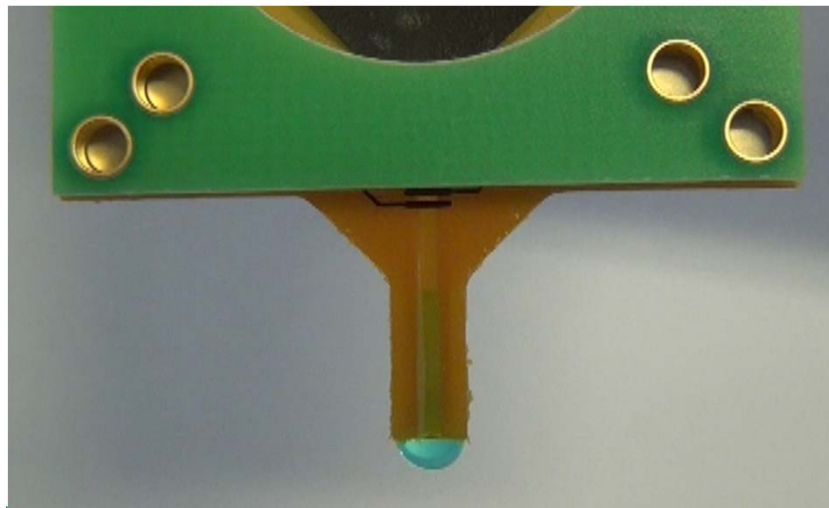
(Poisson's Ratio 0.35; fixed 70 MPa for electrolyte layer)



P2 Electrode Thickness	P6 Actuator Width	P3 Electrolyte Layer Thickness	P4 Young's Modulus	P7 Deformation Probe Z Axis	Corresponding AIST actuator measurement	P1 Force Reaction Z Axis	Corresponding AIST actuator measurement
μm	mm	μm	MPa	mm	mm	mN	mN
90	2	7.5	350	1.21		22.5	
90	2	7.5	100	1.21		6.5	
105	2	7.5	42	1.06	1.15	3.7	3.87
173	2	7.5	42	0.66	0.53	10.0	9.43

Actuation Test of Pipette

Pipette number	Actuator number	Actuator thickness	Membrane inner radius	Cut to shape	Top electrode connection	Glue	Actuation	Comment
P5	X	323 μm	6 mm	no	Counter PCB	Epoxy	70 μm	Large droplet
P9	VII	323 μm	6 mm	no	Counter PCB	Epoxy	50-70 μm	V fast current discharge 0.03A reached in <10sec
P11	V	271 μm	7 mm	no	Counter PCB	3M ring type laser cut		Operation for fluid level change, tested small droplet

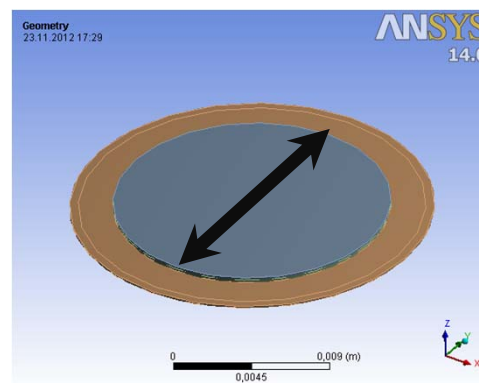
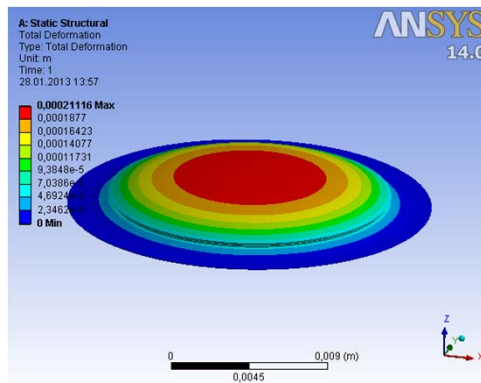


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Design Space and Parameter Tuning: Open Membrane

Young's modulus for electrode layer	42 MPa
Young's modulus for electrolyte layer	70 MPa
Flexible layer thickness (passive layer)	0.05 mm
Flexible outer radius	20 mm
Thickness of actuator electrode	150 μm
Thickness of electrolyte layer	15 μm

Actuator diameter (with 1 mm glue ring)	P7 Deformation Probe Z Axis
mm	μm
10	167
12	190
14	208
16	211
18	199



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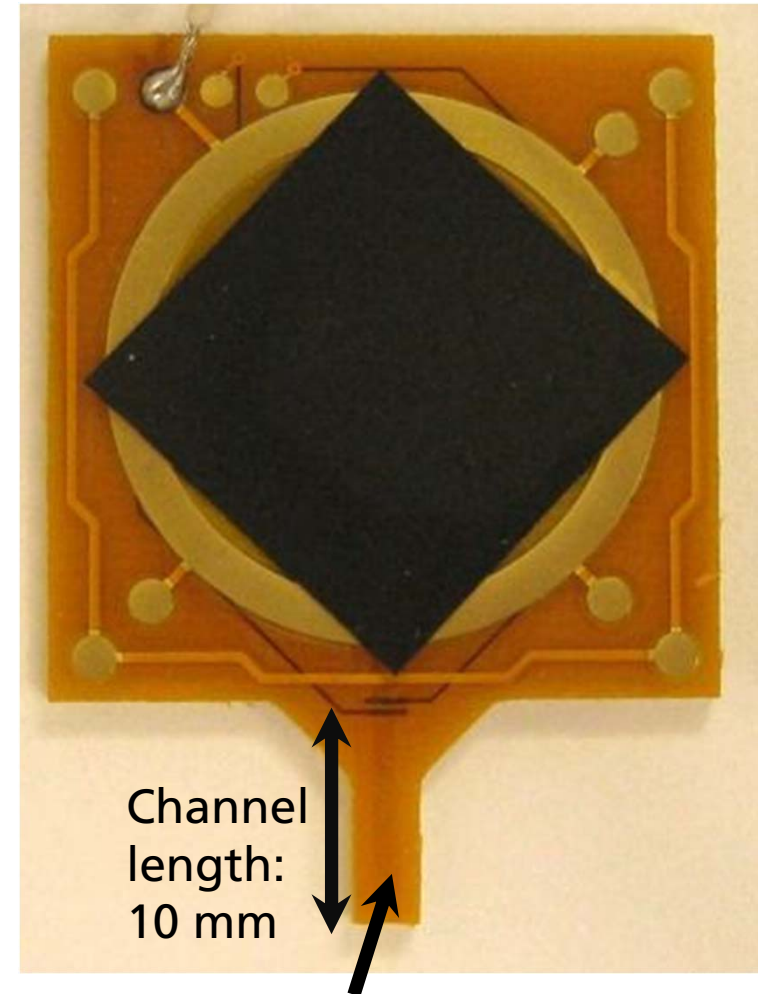
End result - Pipette Features

- **Fluidic**

- Nominal fluid and actuation volume 10 μl (up to 20 μl - single droplet)
- Resistive upper fluid level detection.

- **Electrical specifications**

- Driving voltage 2 V
- Capacity 0.23 F
- Peak current 0.21 A
- Charging time (10 % to 90 %): 4.1 s



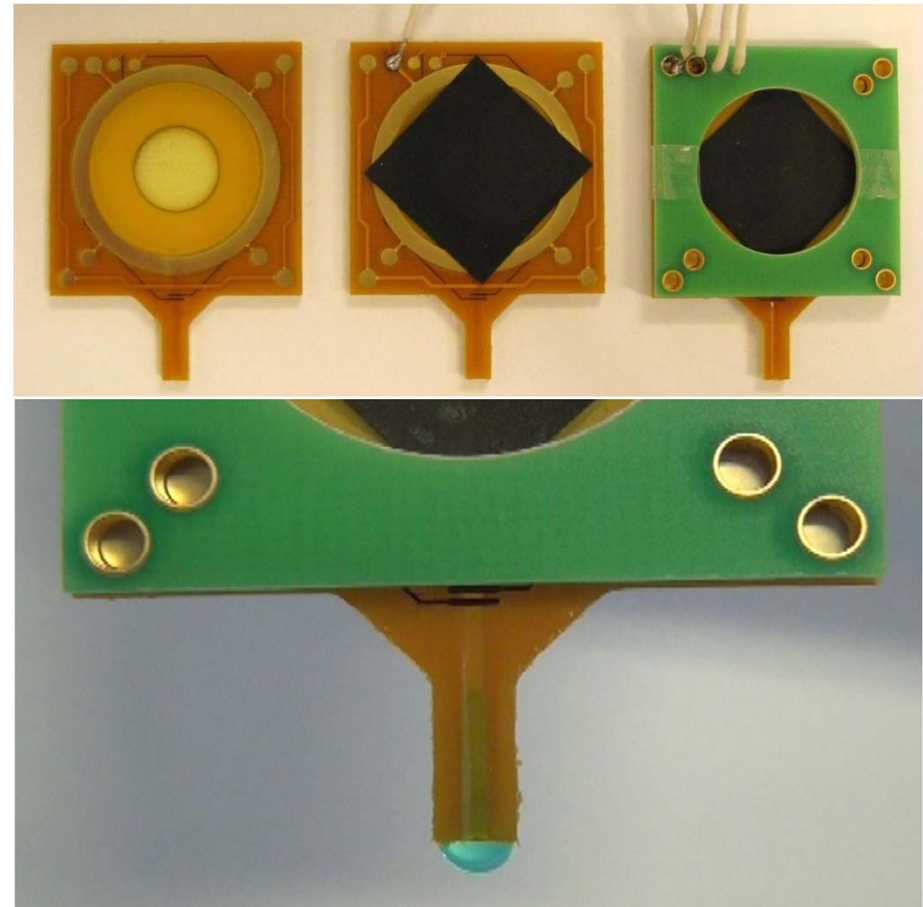
Channel width/height: 1 mm

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German-Japanese Cooperation – First Joint Development

2012 –Pipette with CNT actuator

- Simulation of actuation and geometry
- Material development and processing
- Electrical contacting and system integration
- Construction and engineering of Pipette based on PCB board
- Showed at Nanotech 2013



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Team Kick-Off Meeting Osaka – March 2013



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Thank you very much for your attention



Raphael Addinall
Department Functional Materials

Raphael.addinall@ipa.fraunhofer.de

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