
Advances in state estimation for lithium-ion batteries



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Agenda

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- Motivation in “non-consumer” applications
- Battery management systems
- The problem of state estimation
- Principle of particle filters
- Dual particle filter for state of charge and state of health estimation
- Results
- Conclusions

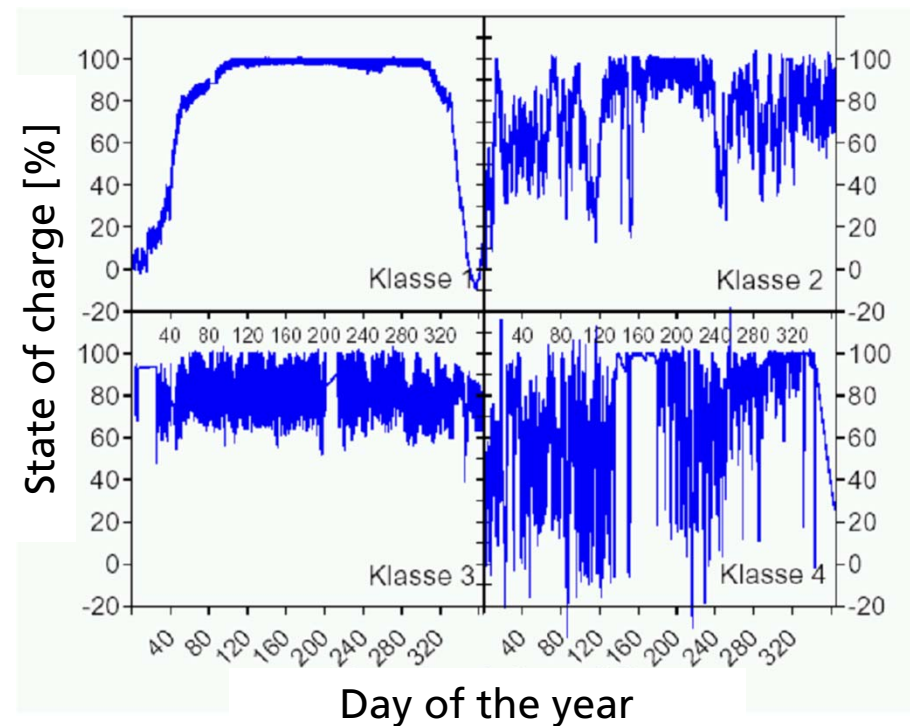


Motivation in non-consumer products

- Fluctuating renewable resources
- Frequently full charging not secured
- Partial cycling at different state of charge levels
- Precise state algorithms necessary for an optimized energy management

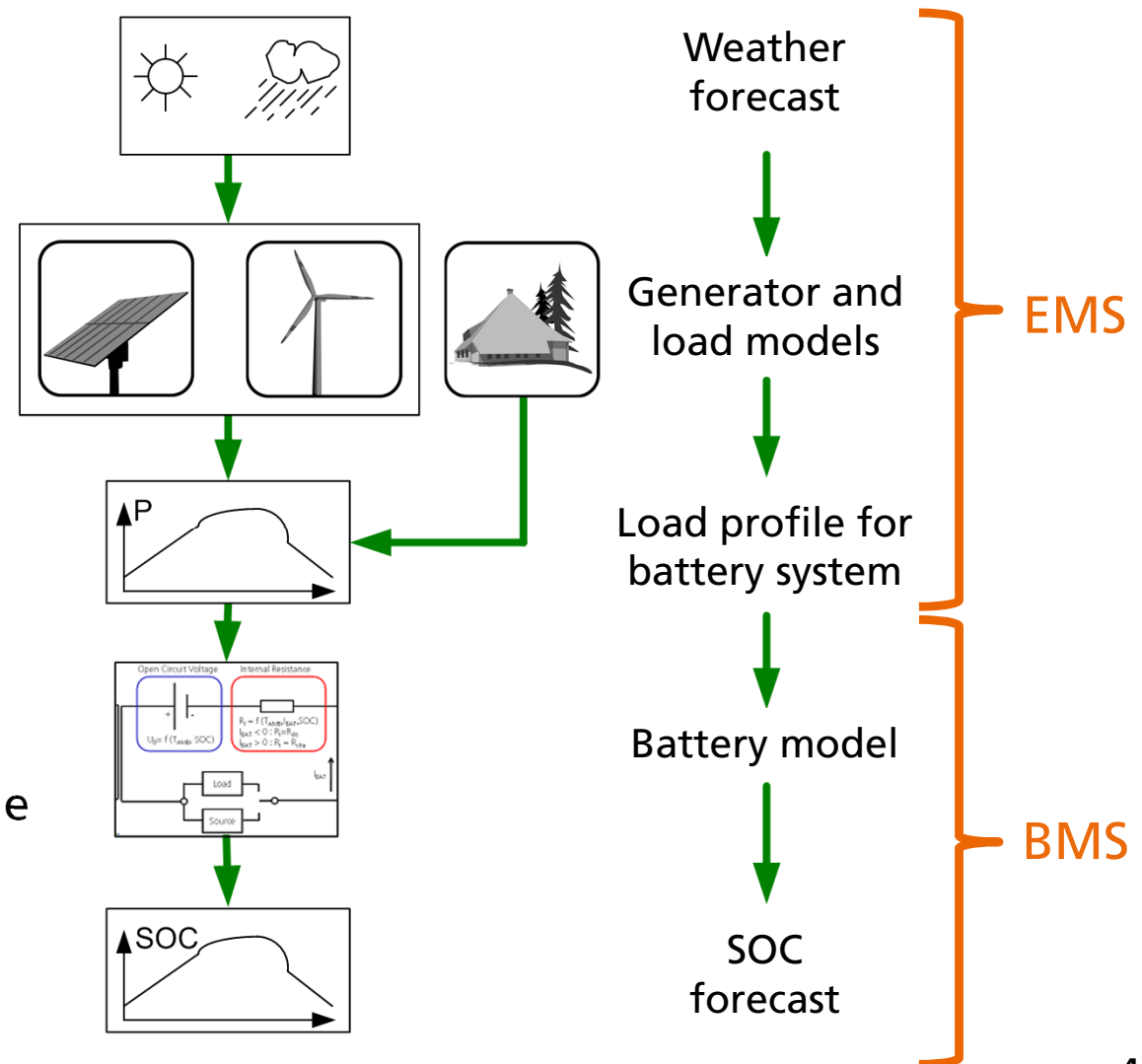


Example:
Storages in PV off-grid systems
Classification of operating conditions



Example power supplies: Smart battery management as part of an optimized energy management

- Communication interface between EMS and BMS
- Model based energy management
 - Load and generation management
 - Optimized operation of battery system
 - ➔ Control of energy fluxes
- Model based battery management
 - SOC prediction in dependence on load profile forecast
 - Efficiencies in dependence on load profile forecast
 - Information on aging



Battery management systems

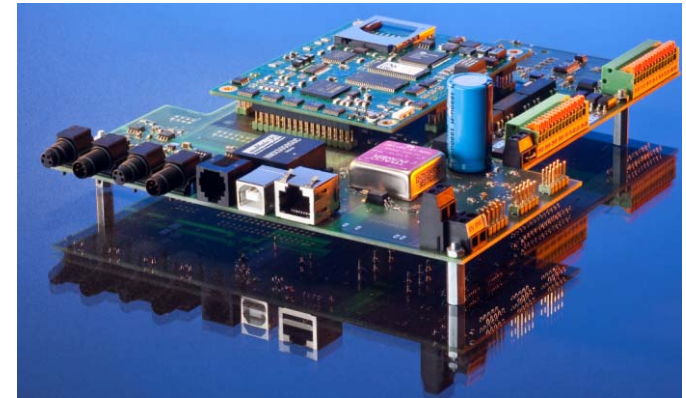
Motivation and objective

Objective:

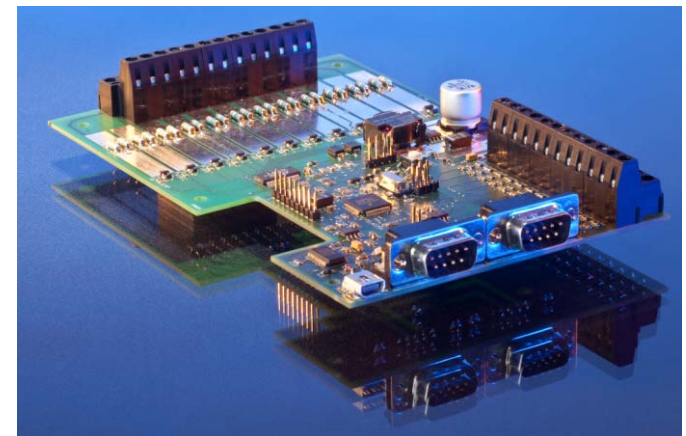
Lithium-ion cells have to be monitored and controlled, important issues are:

- Safety (e.g. overvoltage/undervoltage detection)
- Cycle and calendar life time
- State estimation
- Temperature/voltage monitoring
- High efficiency (well suited cell balancing, low energy consumption of the BMS)

Objective reachable
with high end battery management systems



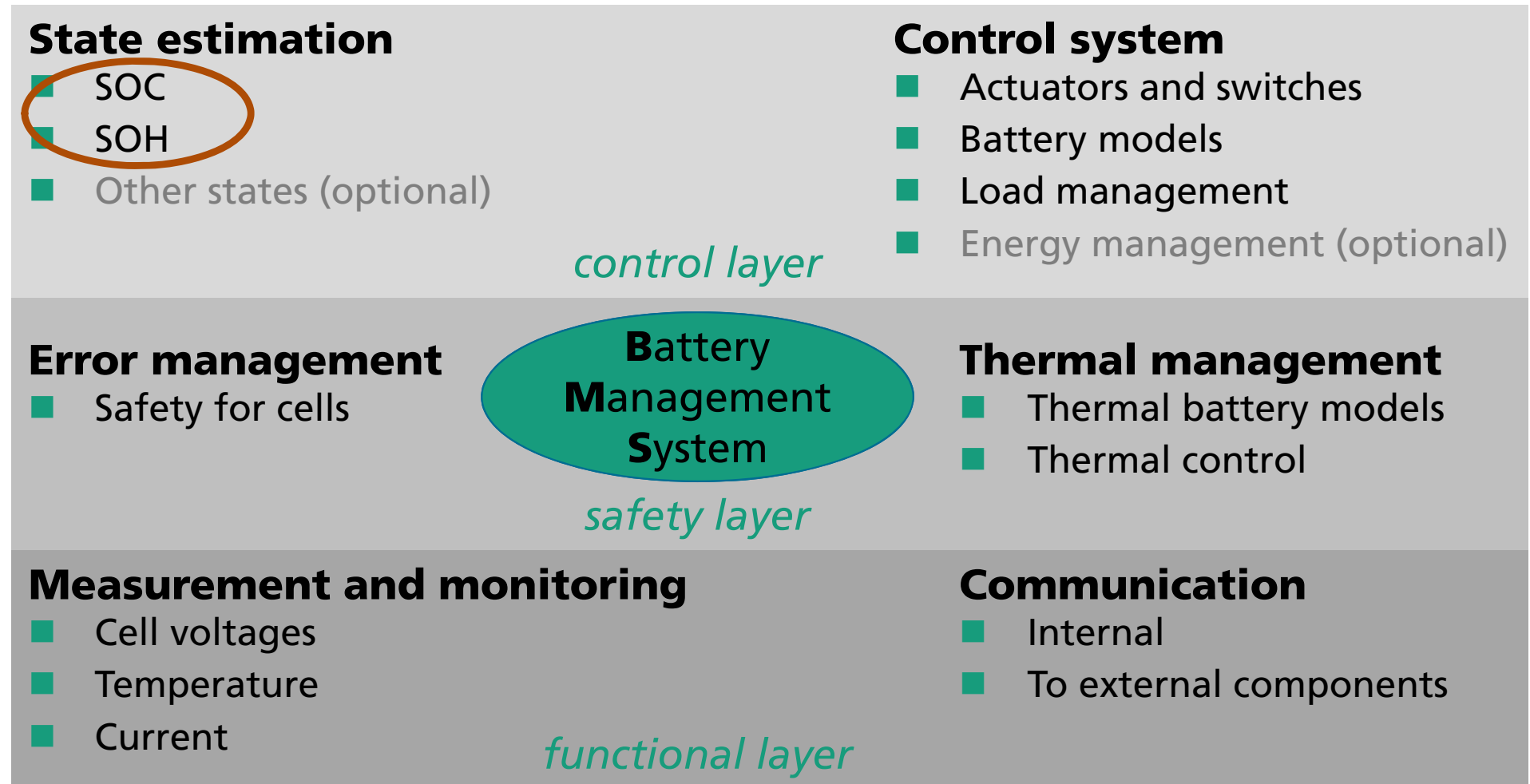
Central management unit



Module management unit 5

Battery management system

Overview and function blocks

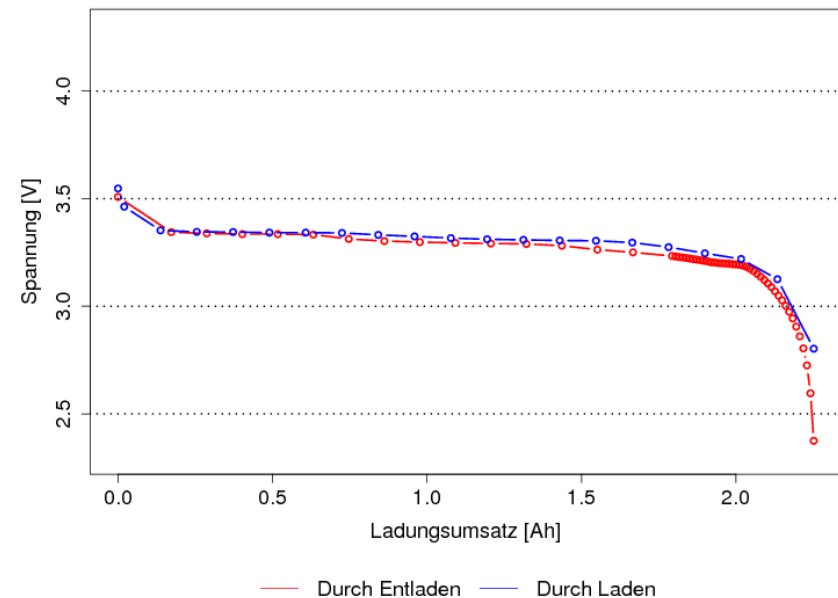
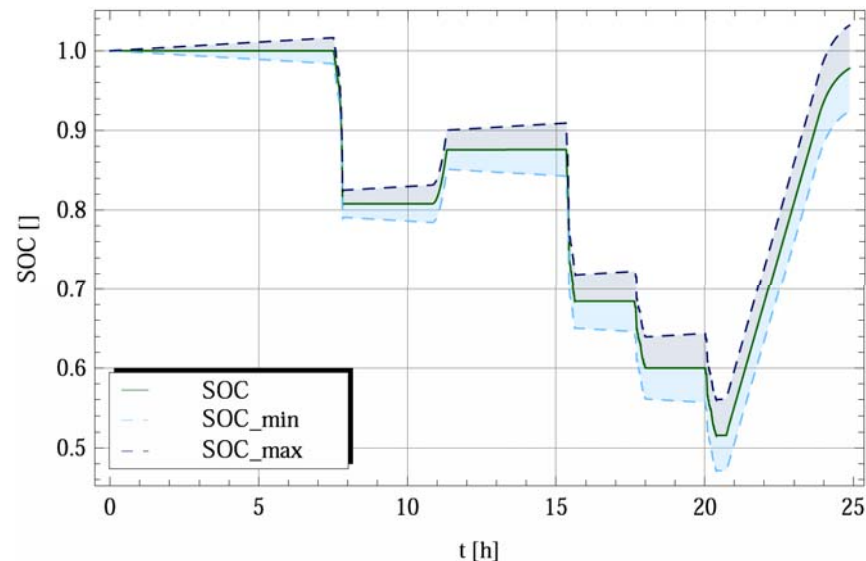


The problem of state estimation

- Inner states of the batteries need to be known for e.g.
 - Prognosis of the remaining run-time in an application
 - Estimations of power capability
 - The point in time for replacing the batteries
- Inner states cannot be measured directly:
 - Inner resistance
 - State of charge (SOC)
 - State of health (SOH)
- Procedures shall only use simple measurement values like terminal voltage, current and temperature

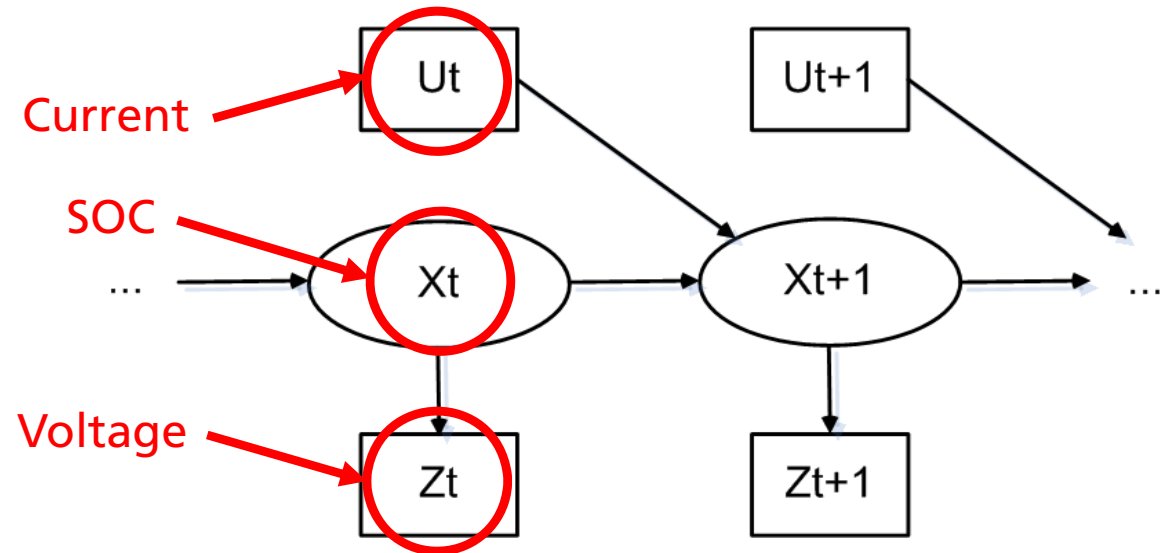
Example: State of charge estimation

- Ah counter: Integration of measurement errors
- Most conventional approaches:
 - Use of some kind of OCV correction in combination with Ah counting
 - ➔ Recalibration of the SOC value via OCV consideration needs resting phases
- Flat OCV characteristic with hysteresis for LiFePO_4



Introduction to Bayesian filters

Example SOC estimation



- Assumption of a Markov chain:

- It is imperative:

- Input U and Output Z are stochastically independent
- If X_t and U_t are known, then X_{t+1} will be independent from all previous states X_1, \dots, X_{t-1}
- U_t is statistically independent from X_1, \dots, X_t and U_1, \dots, U_{t-1}
- If X_t is known, Z_t will be independent from all other variables

- Bayesian filtering equation: $P(x_t) = \eta^{-1} P(z_t | x_t) \int P(x_t | x_{t-1}, u_{t-1}) P(x_{t-1}) dx_{t-1}$

- A typical filter of this family is the Kalman filter

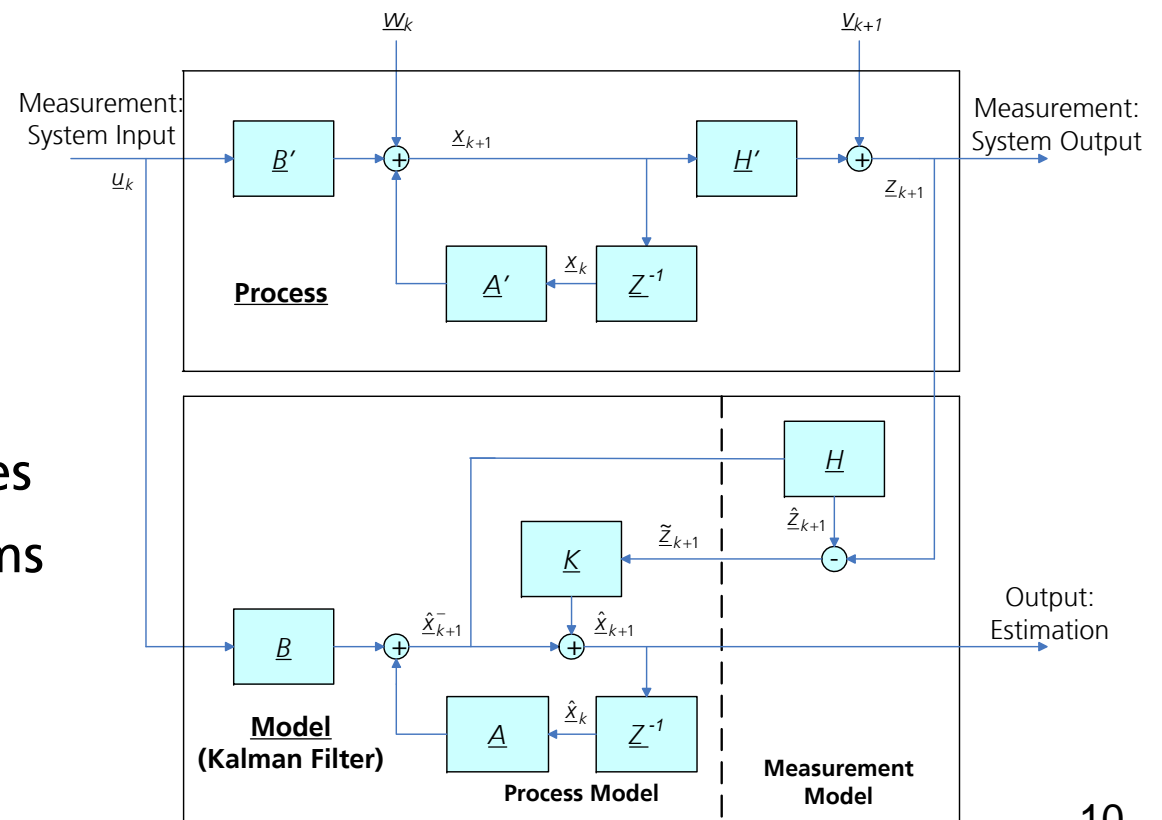
Kalman filter approach

Example: State of charge determination

- Recursive stochastic state estimator
- More insensitive against measurement errors
- No resting phases necessary for recalibration of SOC
- Fast identification of starting values
- Improved performance for aged batteries

Drawbacks:

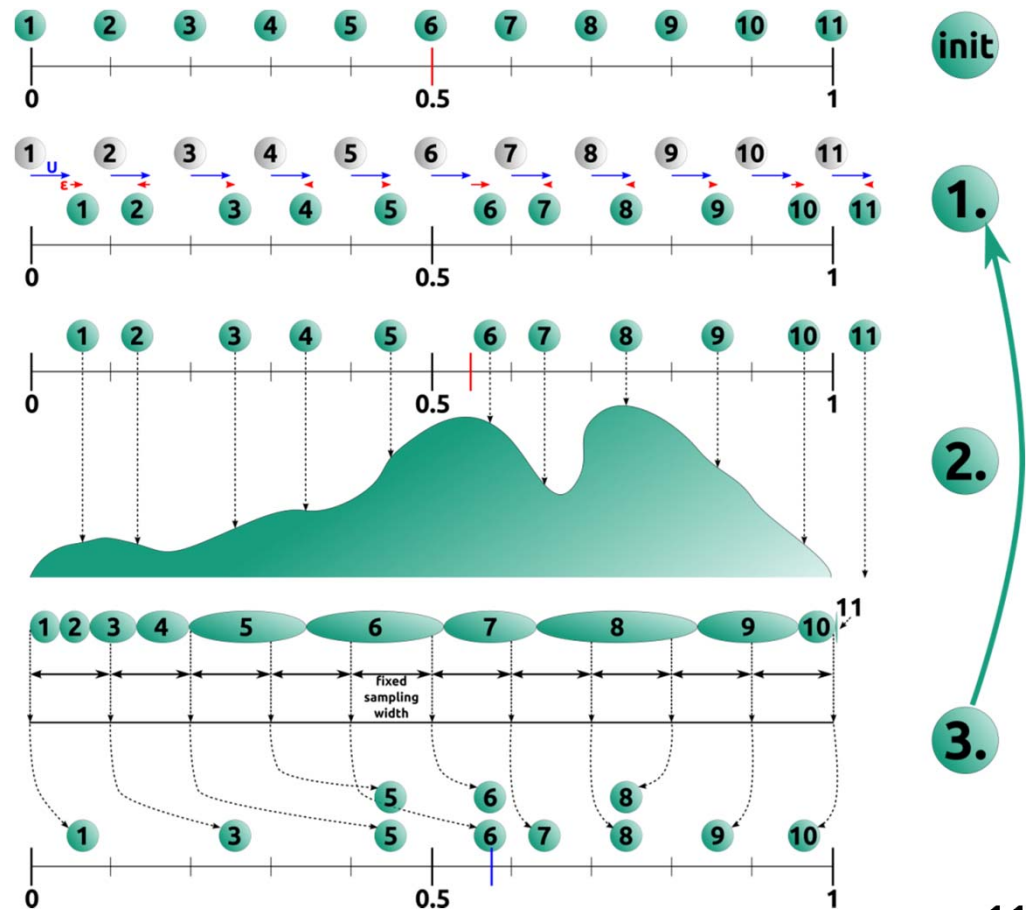
- Optimal estimator only for processes with Gaussian noises
- Suitable only for linear systems
- For non-linear systems: Extended or Unscented Kalman Filter



Particle filter approach

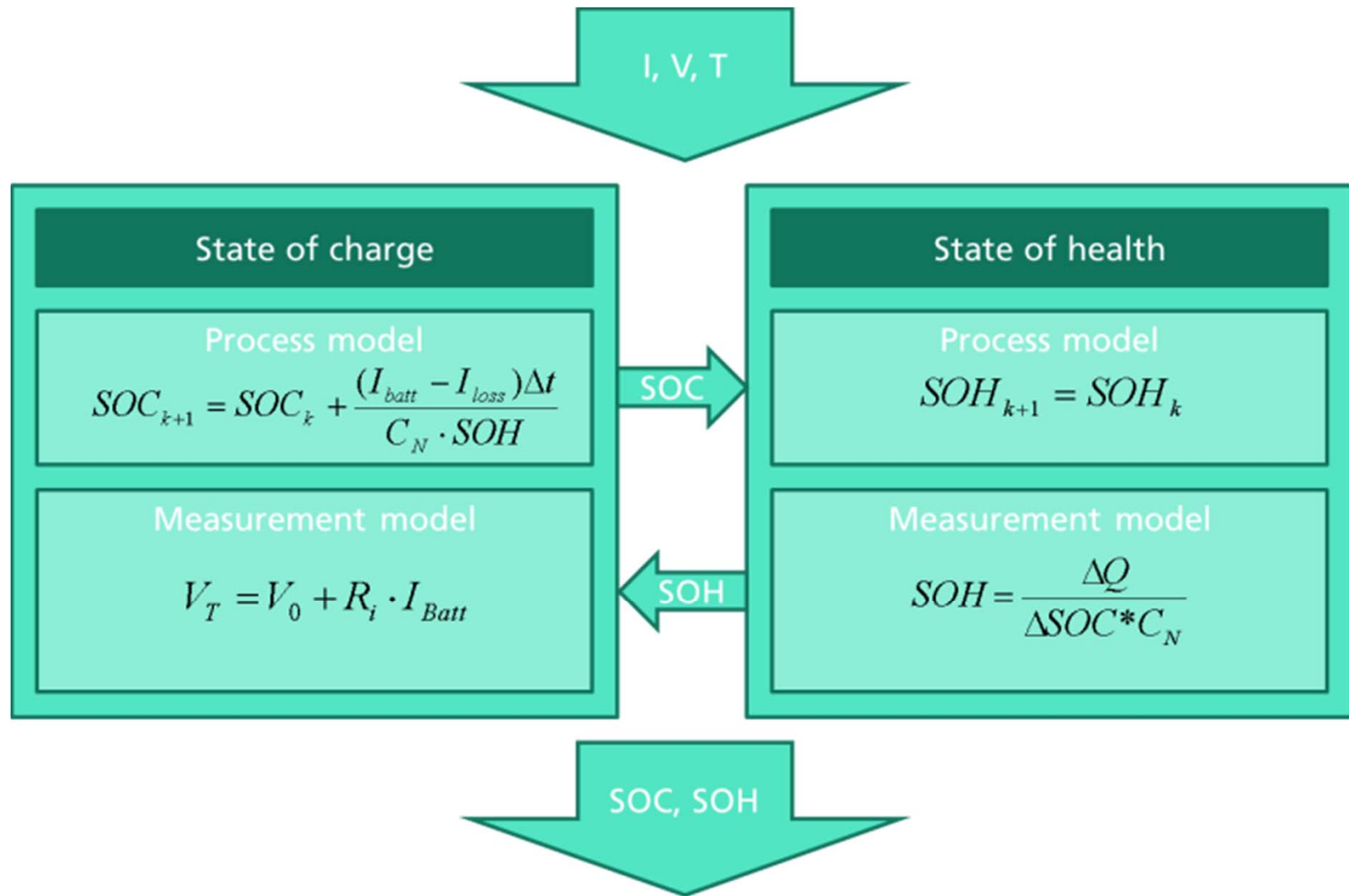
Introduction

- All probability density functions are approximated by samples (Monte Carlo method)
- Offers possibility to deal with any kind of distribution by approximating the respective probability density function by a set of particles or samples
- Offers possibility to use multimodal distributions



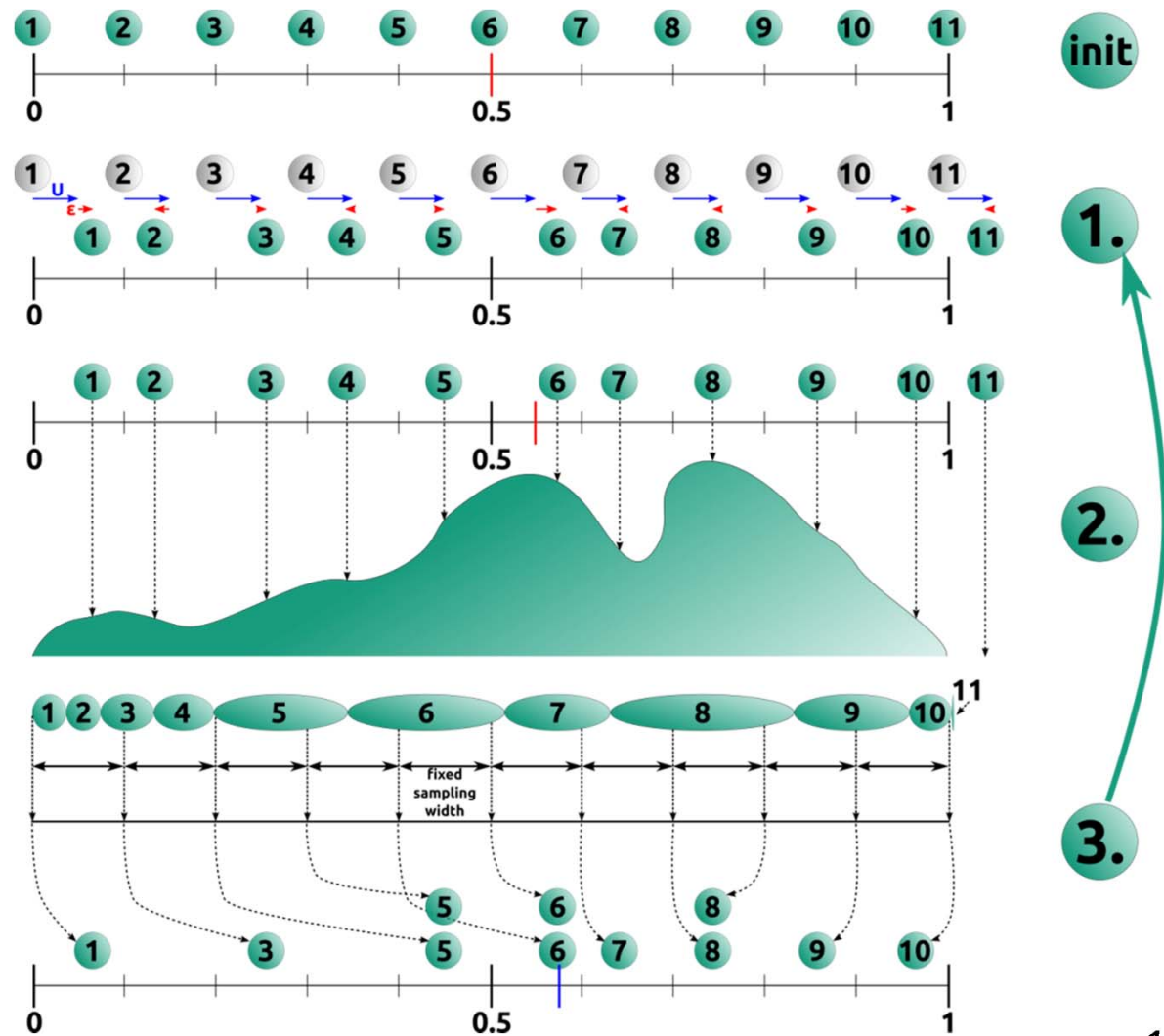
Dual particle filter

State of charge and state of health estimation



Particle filter

Example “State of Charge” estimation



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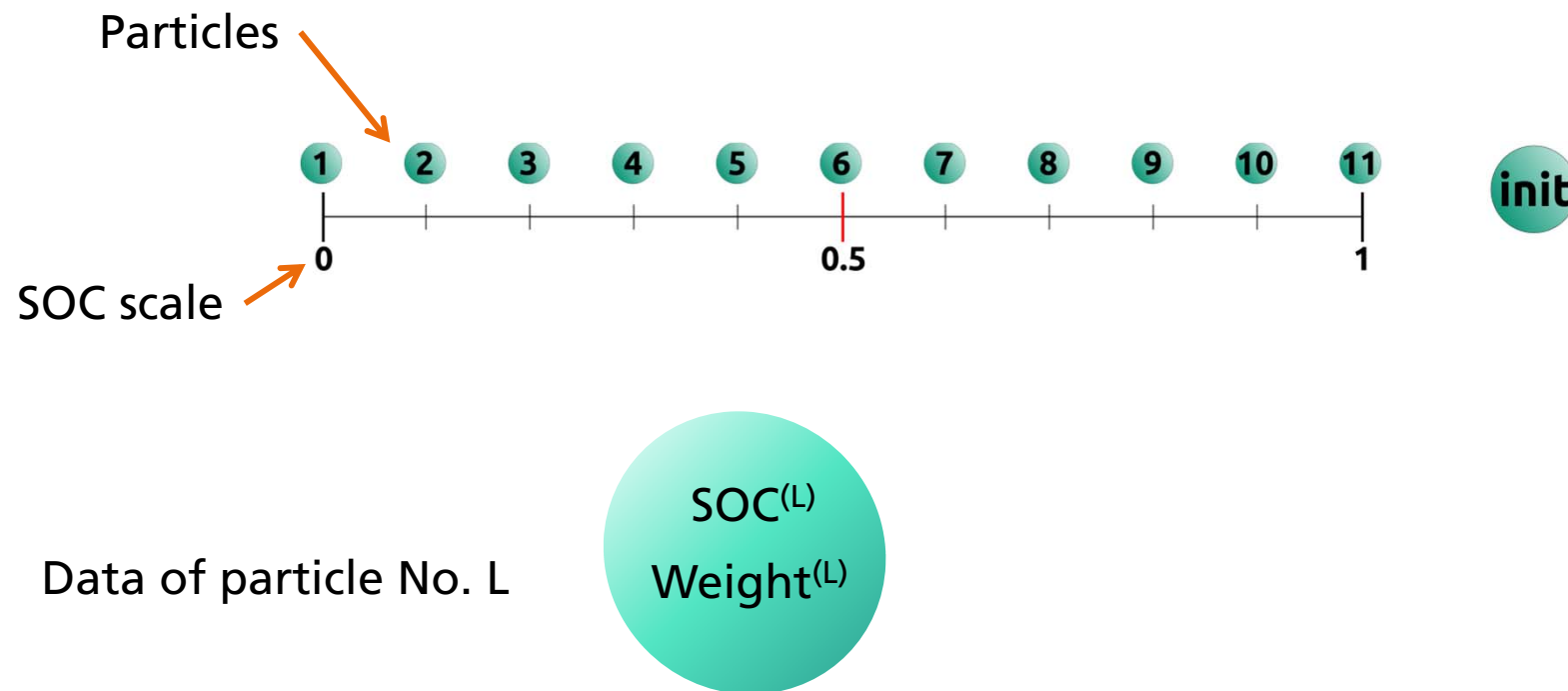
Particle filter

Example “State of Charge” estimation

Initialization: No preliminary information

→ SOC unknown

→ Particles have been uniformly distributed over the entire SOC scale



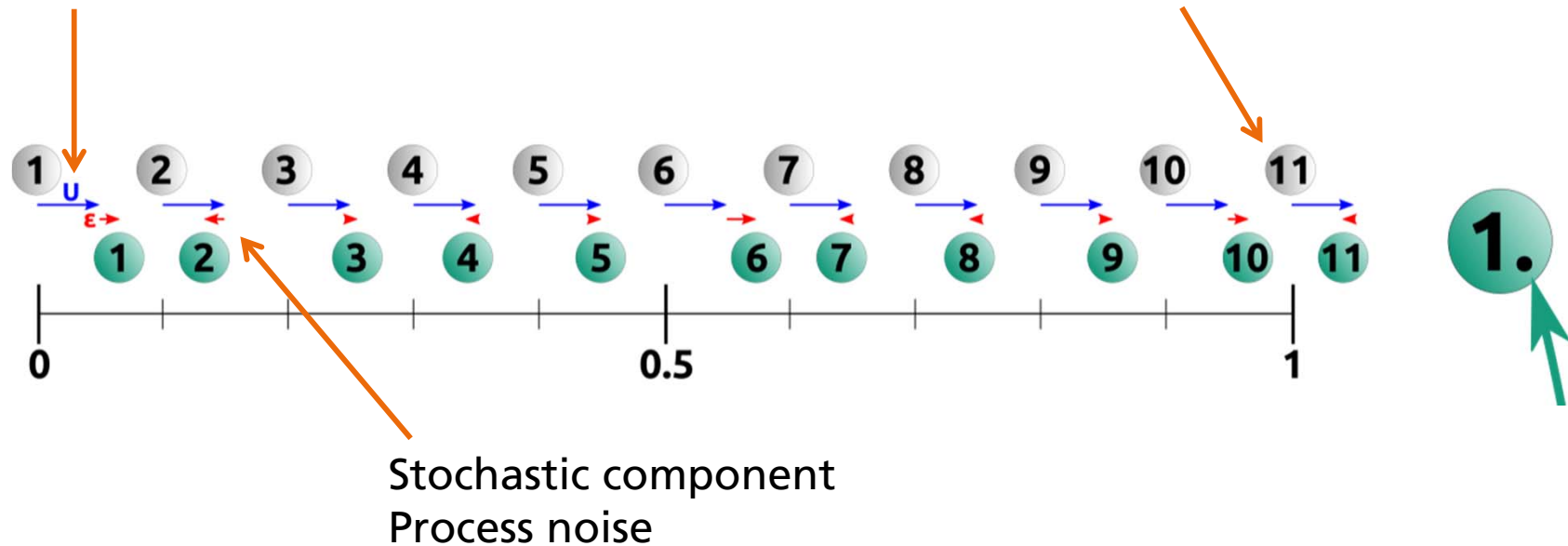
Particle filter

Example “State of Charge” estimation

1. Step: Use of the process model, diffusion

Deterministic component
 $\Delta t * I \rightarrow \text{Ah counting}$

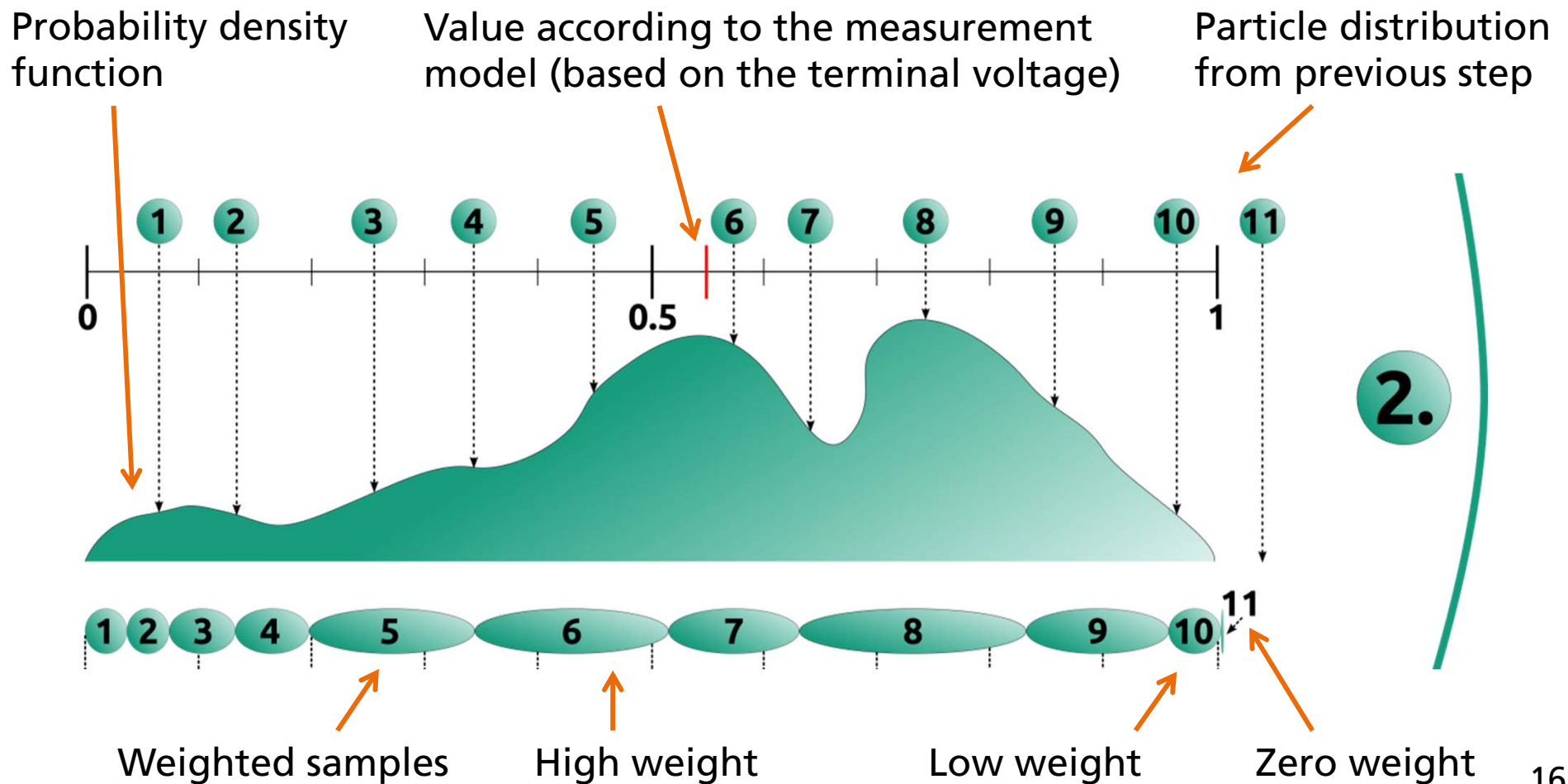
Grey: SOC-“position” of the
initial step or the previous step



Particle filter

Example “State of Charge” estimation

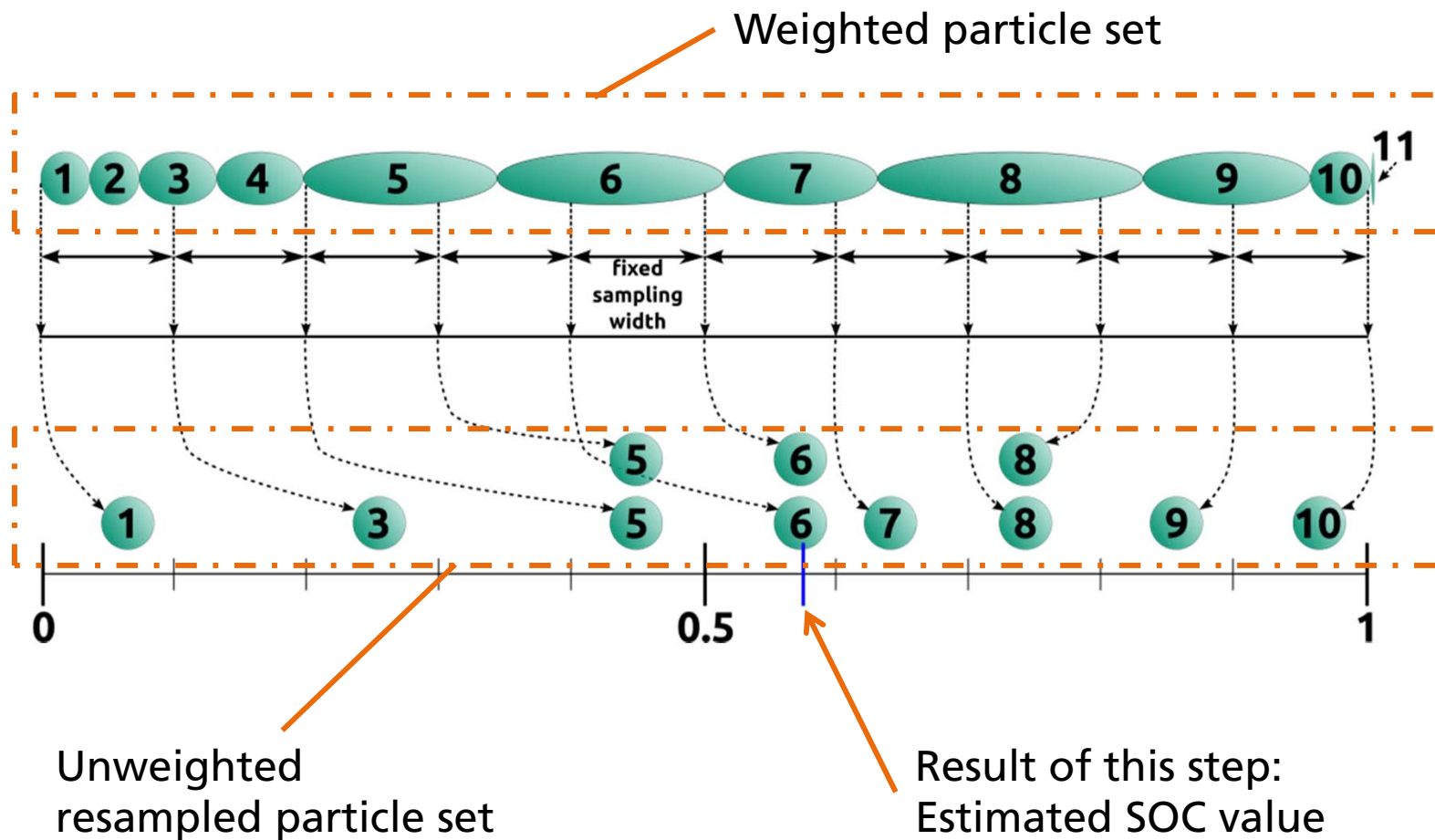
2. Step: Use of the measurement model, weighting



Particle filter

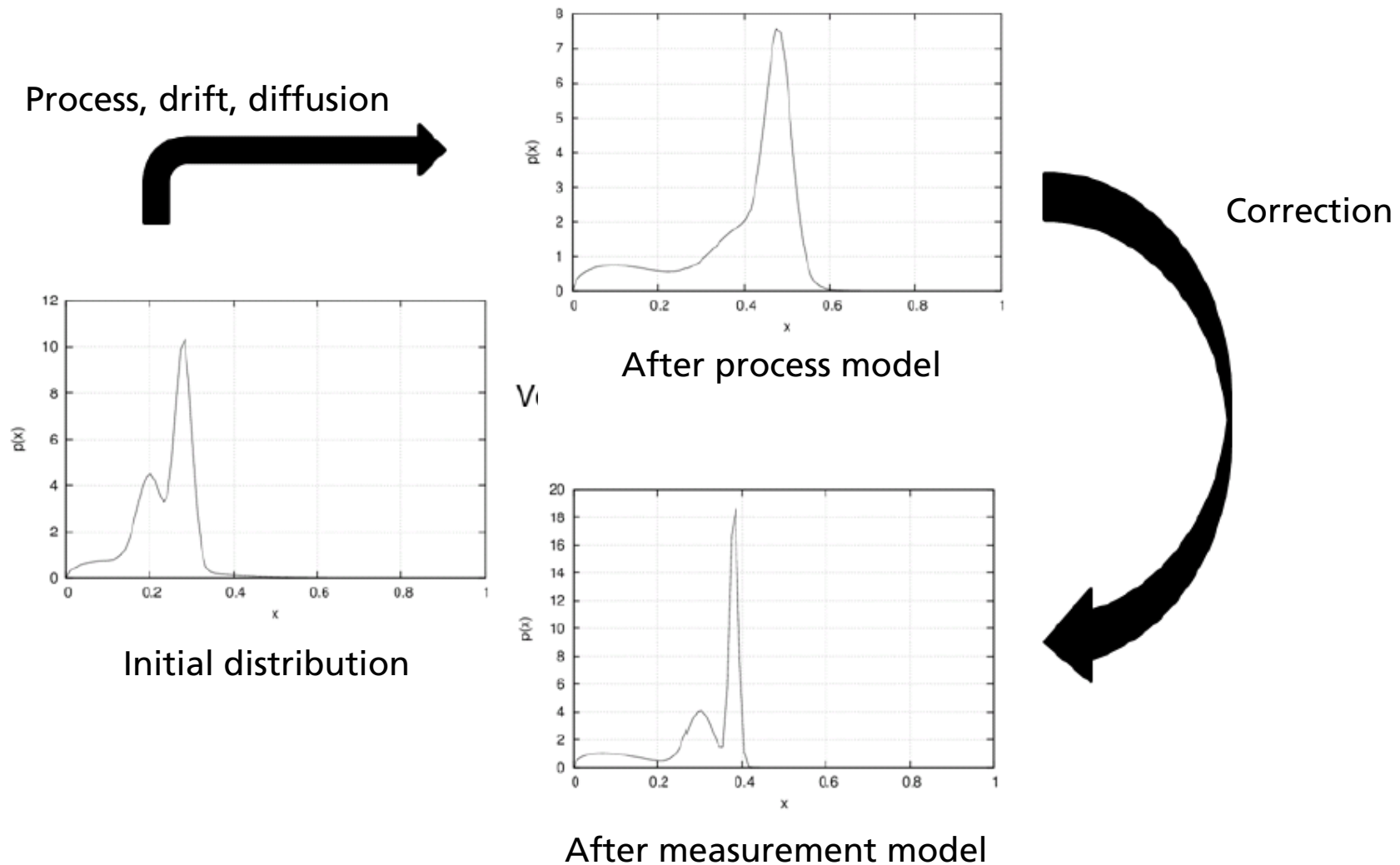
Example "State of Charge" estimation

3. Step: Low variance resampling



Particle filter

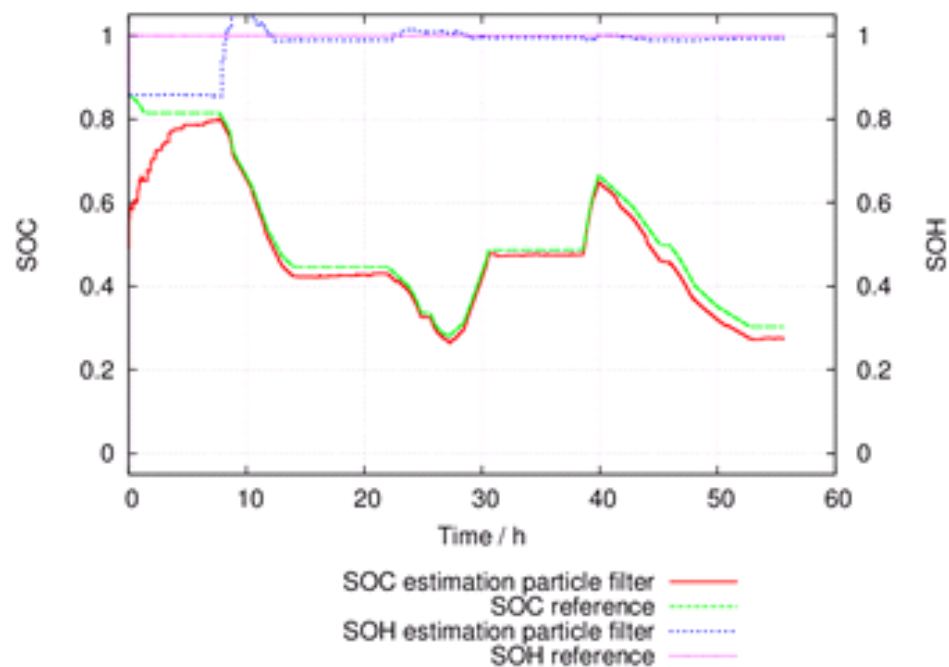
Evolution of probability density function



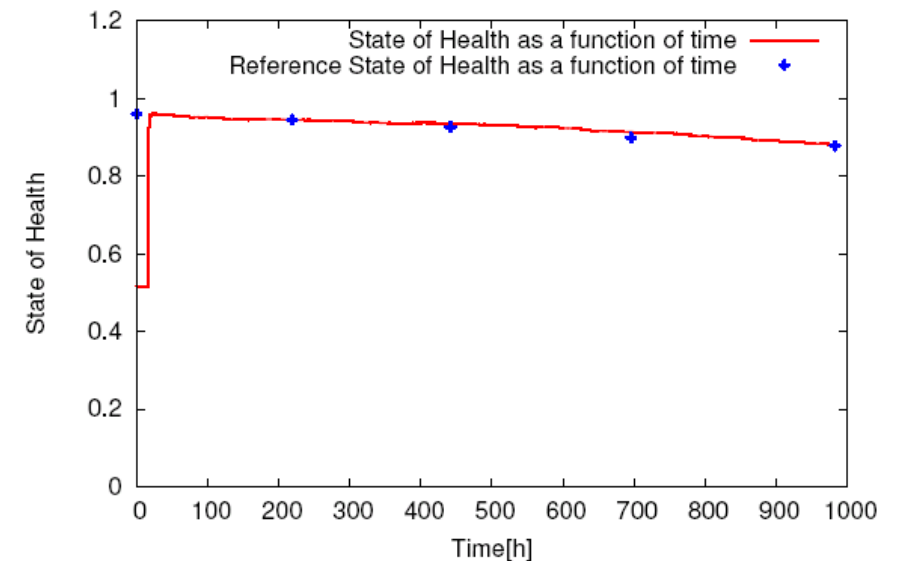
Particle filter

Results

Stationary PV application
State of charge and state of health for LiFePO_4



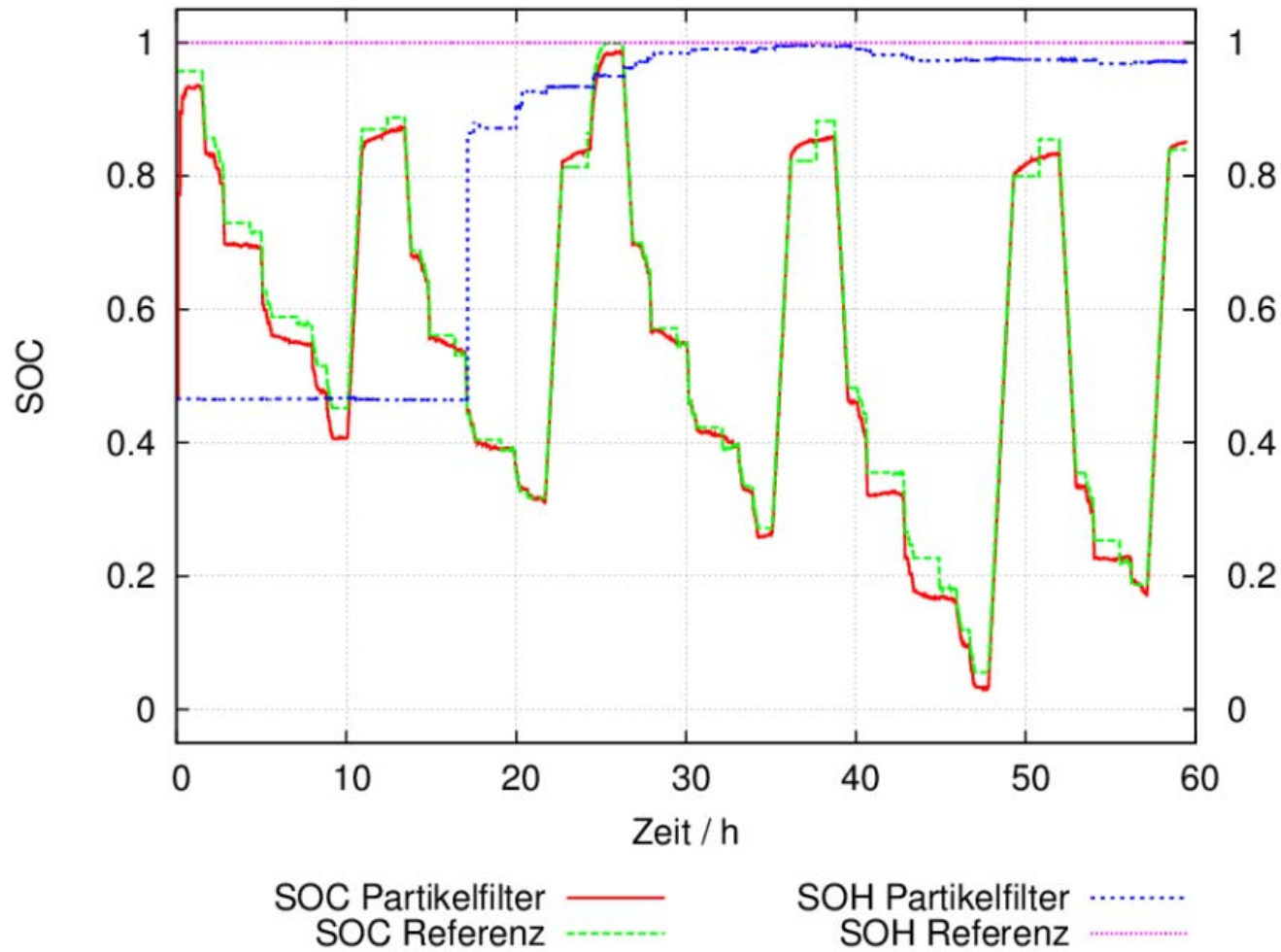
"Long-term" testing
State of health for NMC



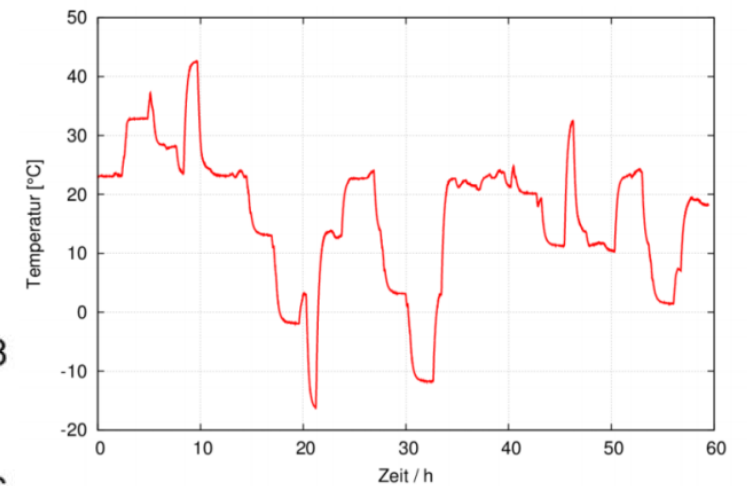
Particle filter

Results

EV application
State of charge and state of health for NMC



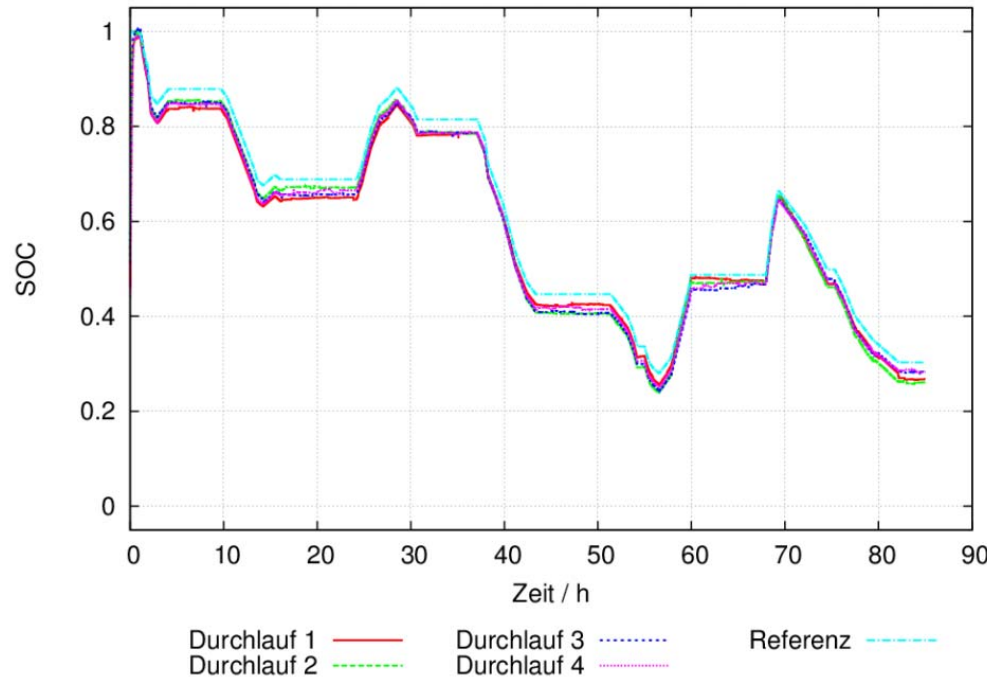
Imposed temperature



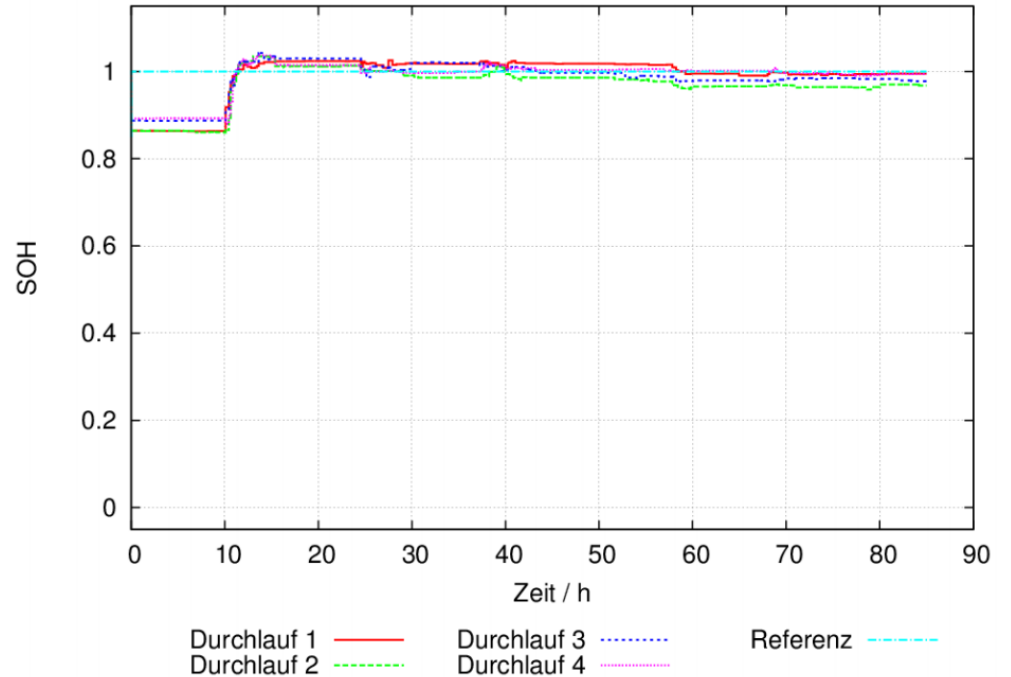
Particle filter

Results – Filter noise

Stationary PV application
SOC estimation for LiFePO_4



Stationary PV application
SOH estimation for LiFePO_4



Conclusions

- State of charge and state of health estimation very important but also sophisticated task for *nearly* all battery applications
- Particle filter for state of charge and state of health estimation with the following features:
 - **Precision:** Finds “true” value with minimal variation
 - **Speed:** Sufficiently fast to cope with PV as well as EV profiles
 - **Flexibility:** Able to cope with different initial values and temperature profiles
- Due to low computational efforts it can be implemented very well on small scale microcontrollers of battery management systems
- ➔ Particle filter is a very flexible and reliable tool for estimating inner states of batteries



Thanks for your attention !!!

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