

ROS-Industrial: Closing the Gap between Robotics Research and Industry

Dipl.-Ing. Ulrich Reiser

ROS-Industrial: Closing the gap between robotics research and industry

- Dipl.-Ing. Ulrich Reiser
- Technology Seminar – ROS in Industrial Applications



1

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Potential of ROS Industrial

Robotics Research



- Unstructured and dynamic environments
- Variability of objects to be handled
- Typically little robustness and reliability required



Robotics Industry



- Structured and fix environments
- Small set of different well-defined objects
- High Robustness and high reliability

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What is ROS-Industrial (today)?



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Available Hardware Support

(Technically) Available
in an alpha version:



- PLC Interfaces
- Industrial Networks / Buses
- Industrial HMIs
- Interfaces to Industrial Robots
- 2D/3D Sensor Drivers
- Some I/O Devices (e.g. WAGO ethercat)

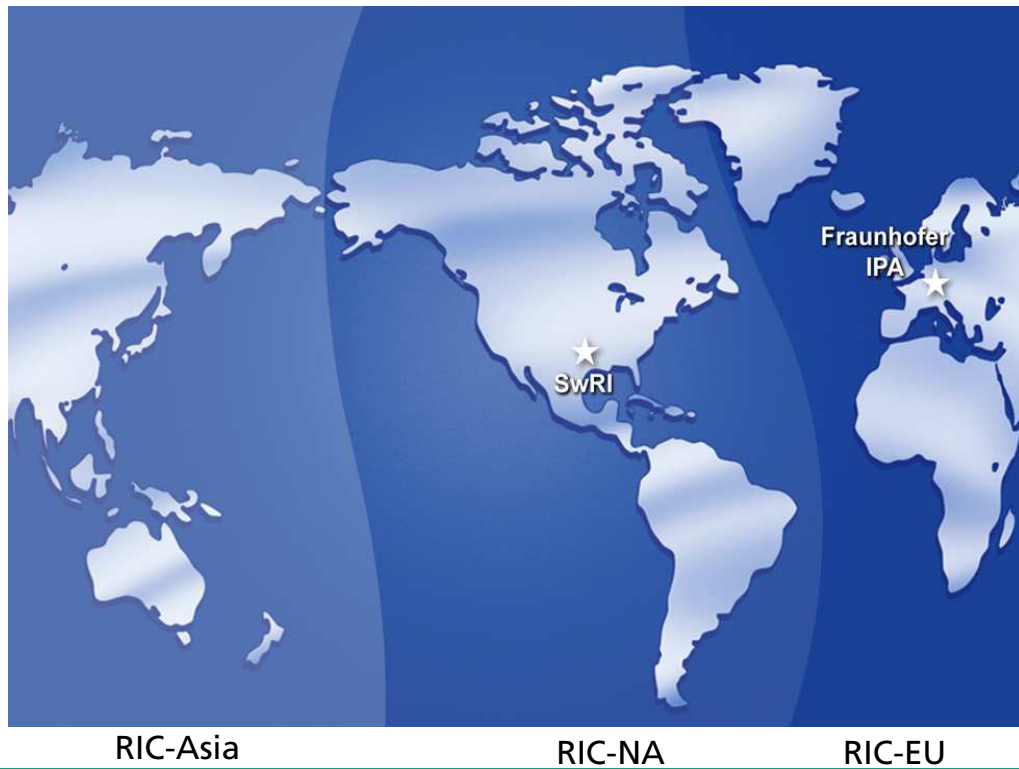
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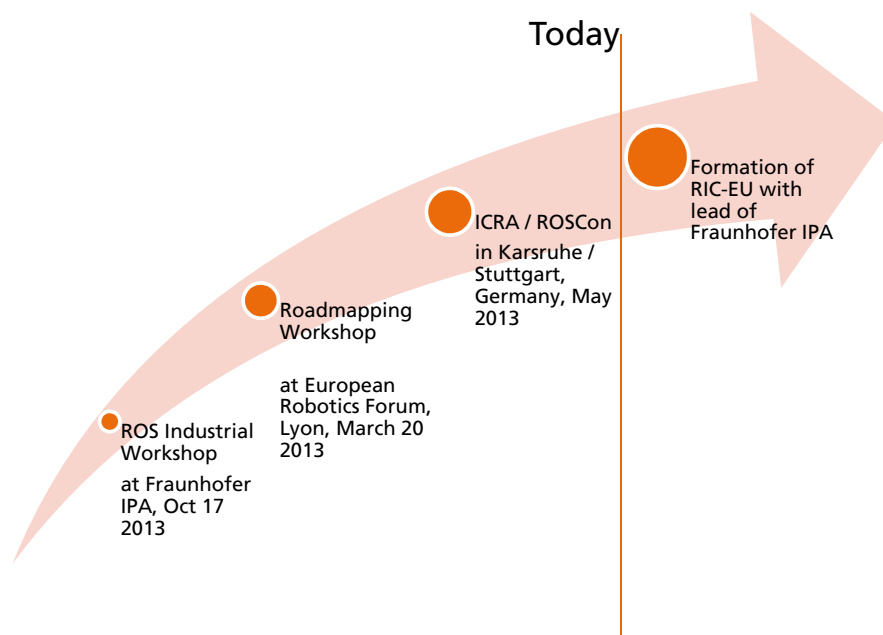
ROS Industrial Consortium



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Outlook ROS-Industrial



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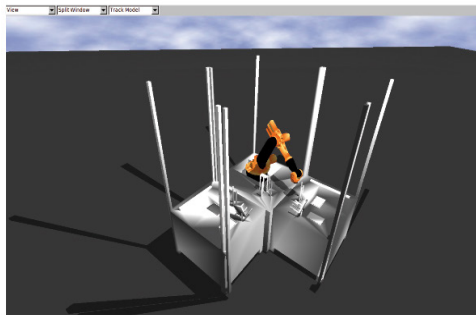
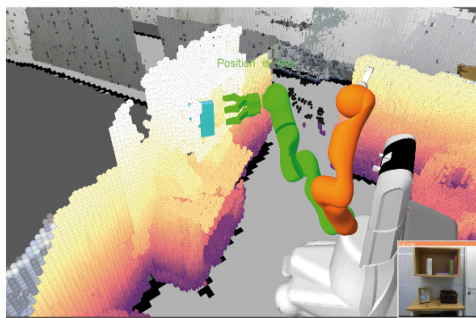
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ROS IN DER INDUSTRIELLEN ANWENDUNG



Seminar **SPA 025**
1. Oktober 2013
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