

# FEM Simulation Tool for Electromagnetic NDT System in Different Inspection Situation and Visualization Platform

---

Dr. Yasmine GABI

Dr. Bernd Wolter

Dr. Olivier Martins

Andreas Gerbershagen



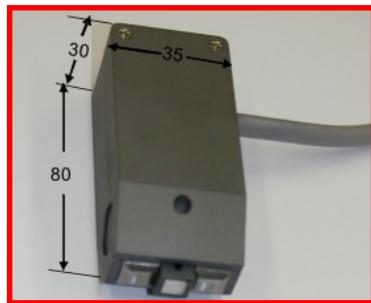
---

# Structure

---

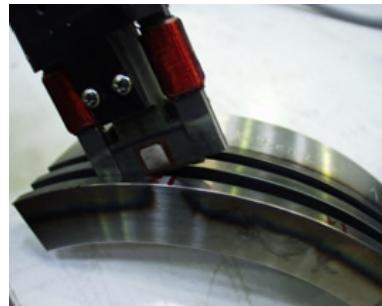
1. Introduction
2. Modeling of the magnetic material
  - General procedure
  - Characterization
3. FEM simulation
  - 3MA principal and challenges
  - Impact of hysteresis
  - Low frequency eddy current
  - Incremental permeability
4. Validation on a homogeneous case
5. Correlation between mechanical properties and 3MA outputs

# Introduction: 3MA probes



**Type E1030-B**

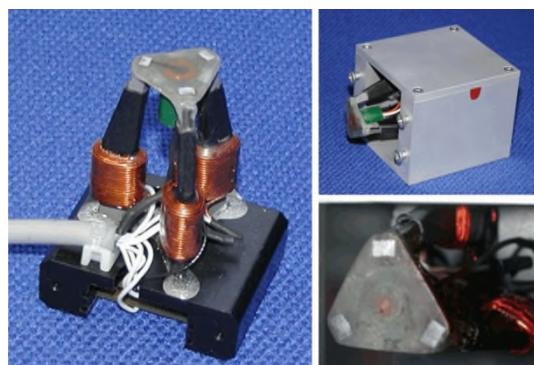
Spherical pole shoes Max.  
measuring depth  $\leq$  4 mm



**Special Probe Head  
for Piston Grooves**



**For large gear wheels**



**Rotating field probes allows  
directional determination of stress,  
elongation, grain orientation**



**Automated Strip Steel  
Inspection Systems**



**Rotating sample**

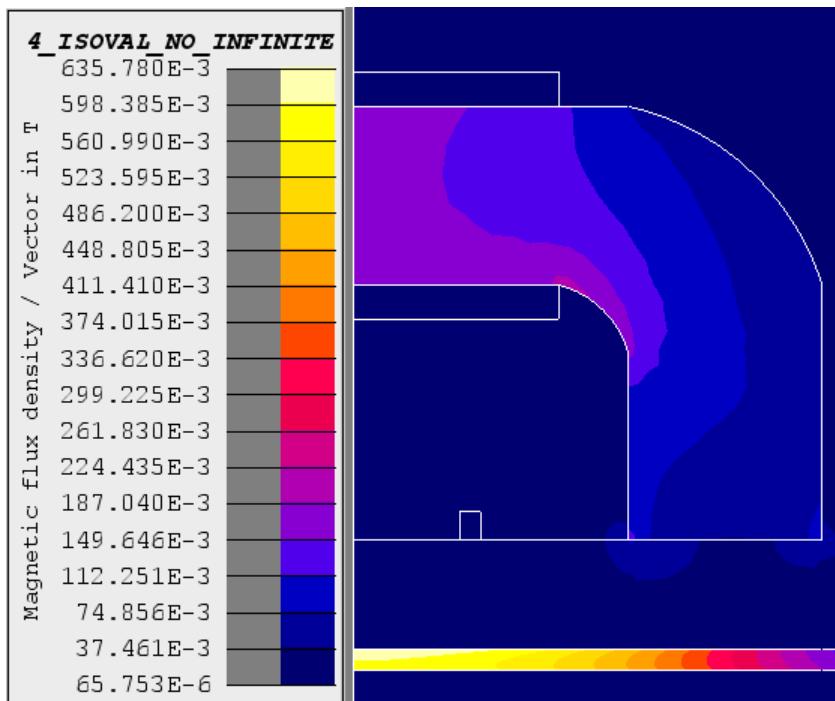
# New: Magnus probe ( 3MA +ultrasound)



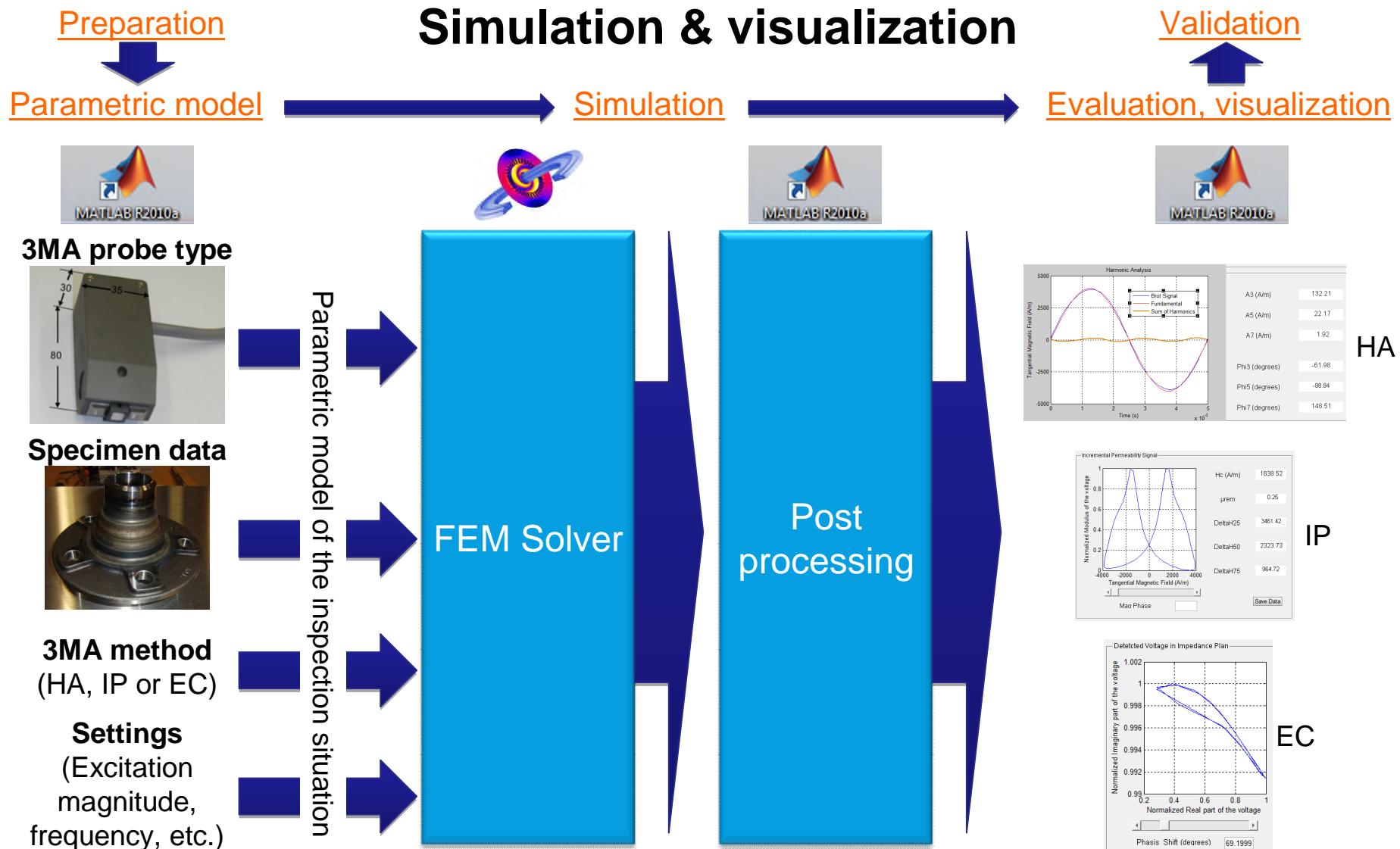
Magnus

Specificity:

- Eddy current
- Harmonic analysis
- Barkhausen noise
- Incremental permeability
- Ultrasound



For the incremental permeability  
The magnetization coil send  
superimposed signals  
LF+HF



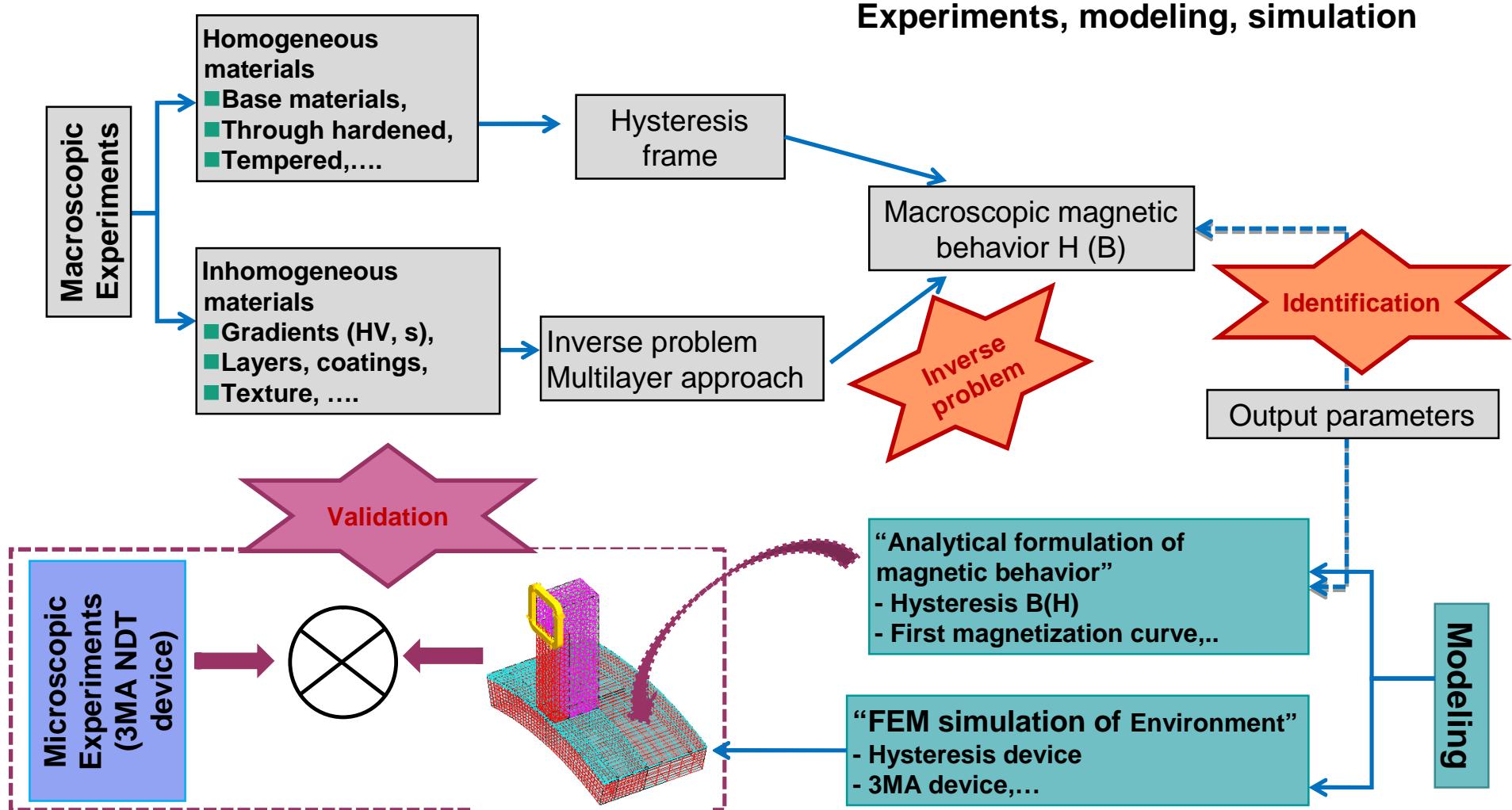
---

# Structure

---

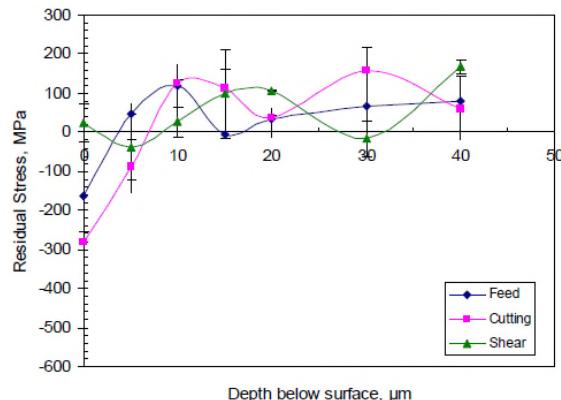
1. Introduction
2. Modeling of the magnetic material
  - General procedure
  - Characterization
3. FEM simulation
  - 3MA principal and challenges
  - Impact of hysteresis
  - Low frequency eddy current
  - Incremental permeability
4. Validation on a homogeneous case and correlation to mechanical properties

# Material modeling: General procedure

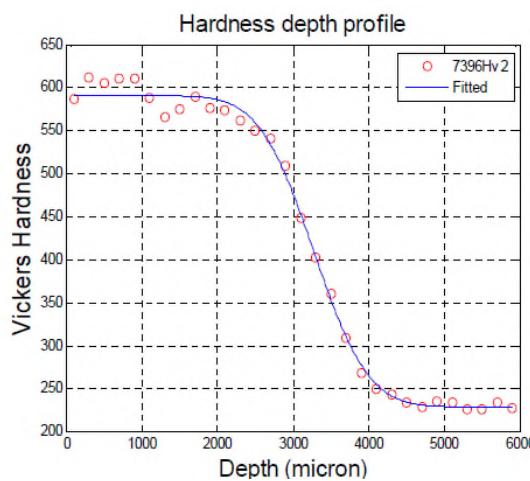
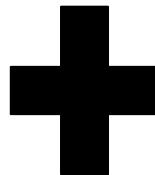


# Multi layer approach

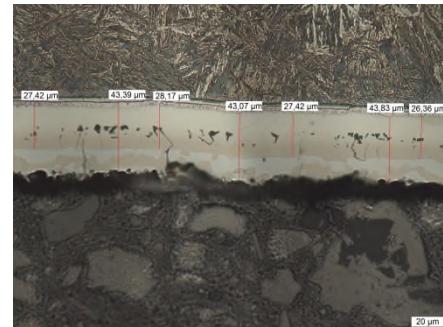
## Mechanical Profiles (literature example)



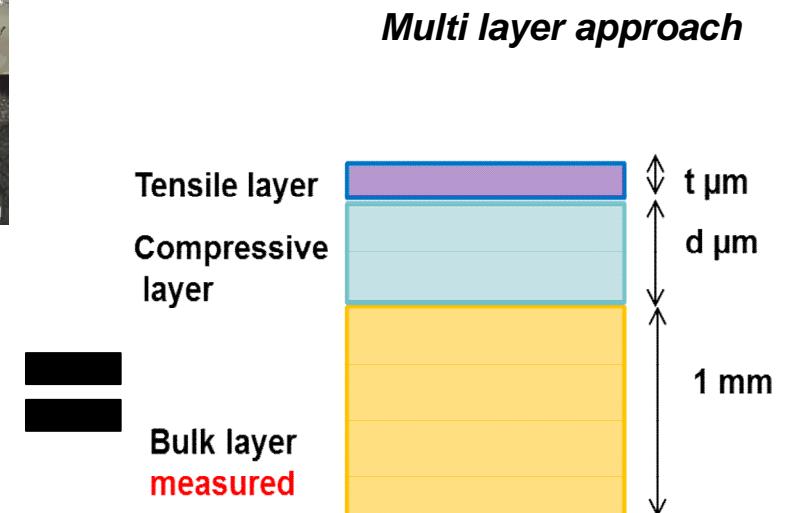
Hardening profile  
(literature example)



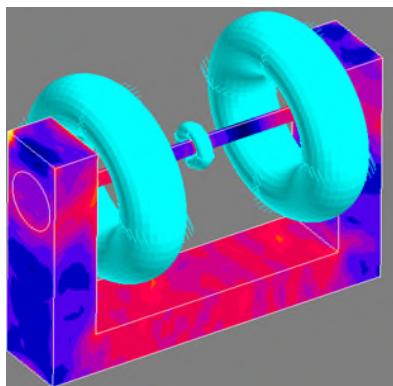
Inverse problem  
-Combination of 3MA  
-Analytical formulation of  
linear eddy current



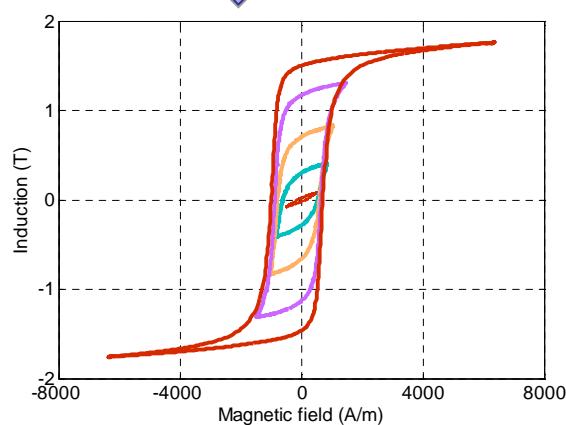
Microstructure



# Material modeling: Global and local characterization

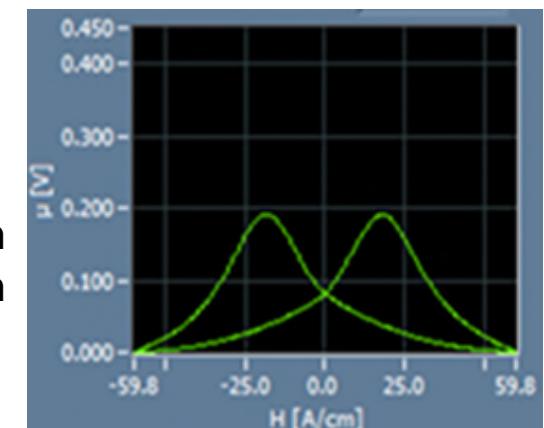


Hysteresis frame measurements



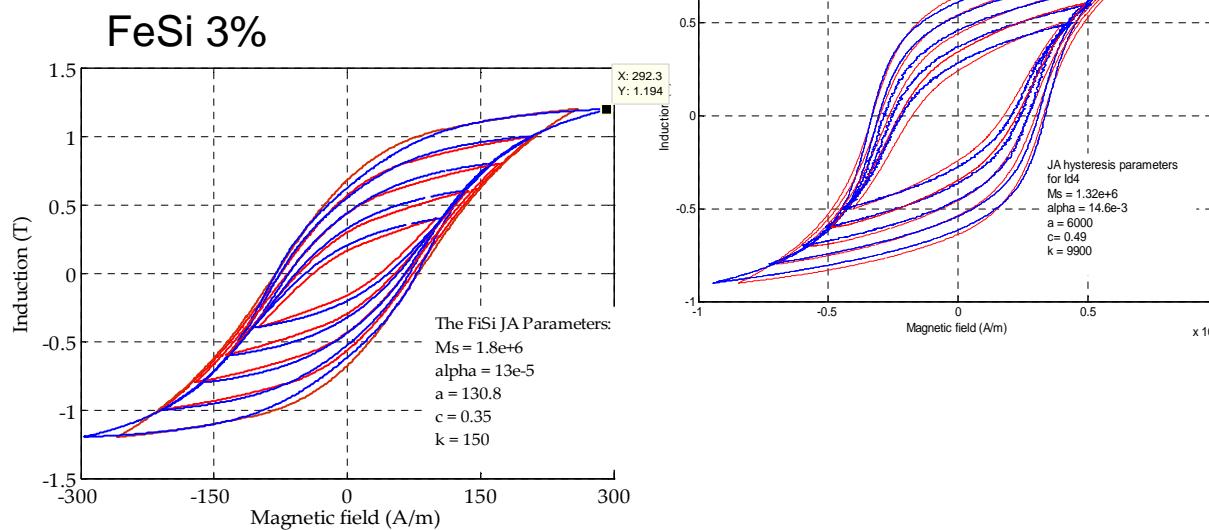
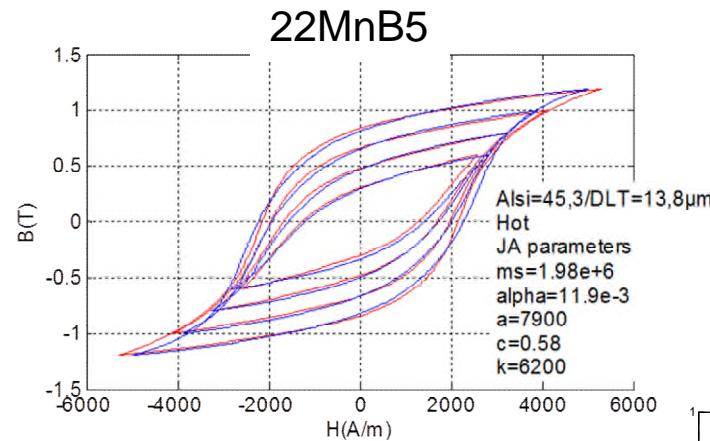
**Results:**  
 $-J_s = 2\text{T}$   
 $-\mu_r = 419,$   
 $-H_c = 708 \text{ A/m}$   
 $-B_r = 1.5\text{T}$

3MA measurements

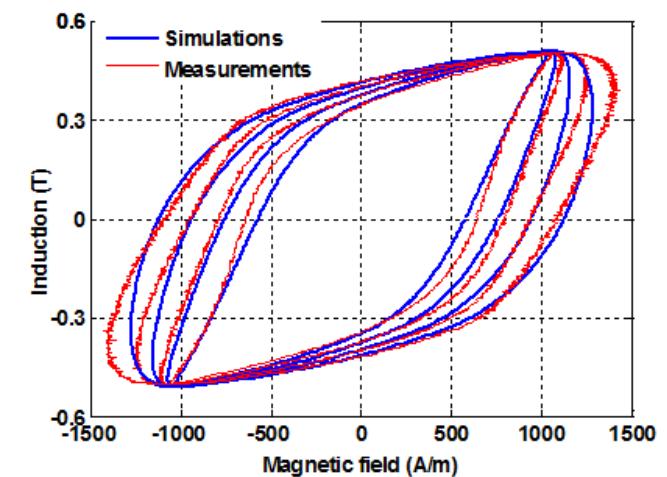
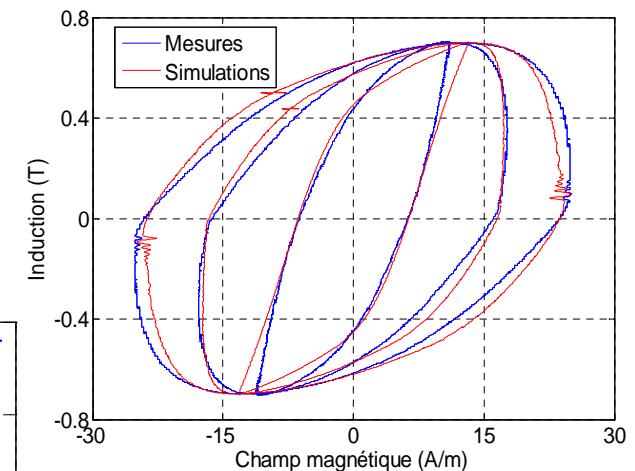


**Results:**  
 $-H_{c\mu} = 18,1 \text{ A/cm}$   
 $-\mu_{max} = 0.2 \text{ V}$   
 $-DH_{25\mu} = 54.9 \text{ A/cm}$   
 $-DH_{50\mu} = 35.3 \text{ A/cm}$   
 $-DH_{75\mu} = 18 \text{ A/cm}$

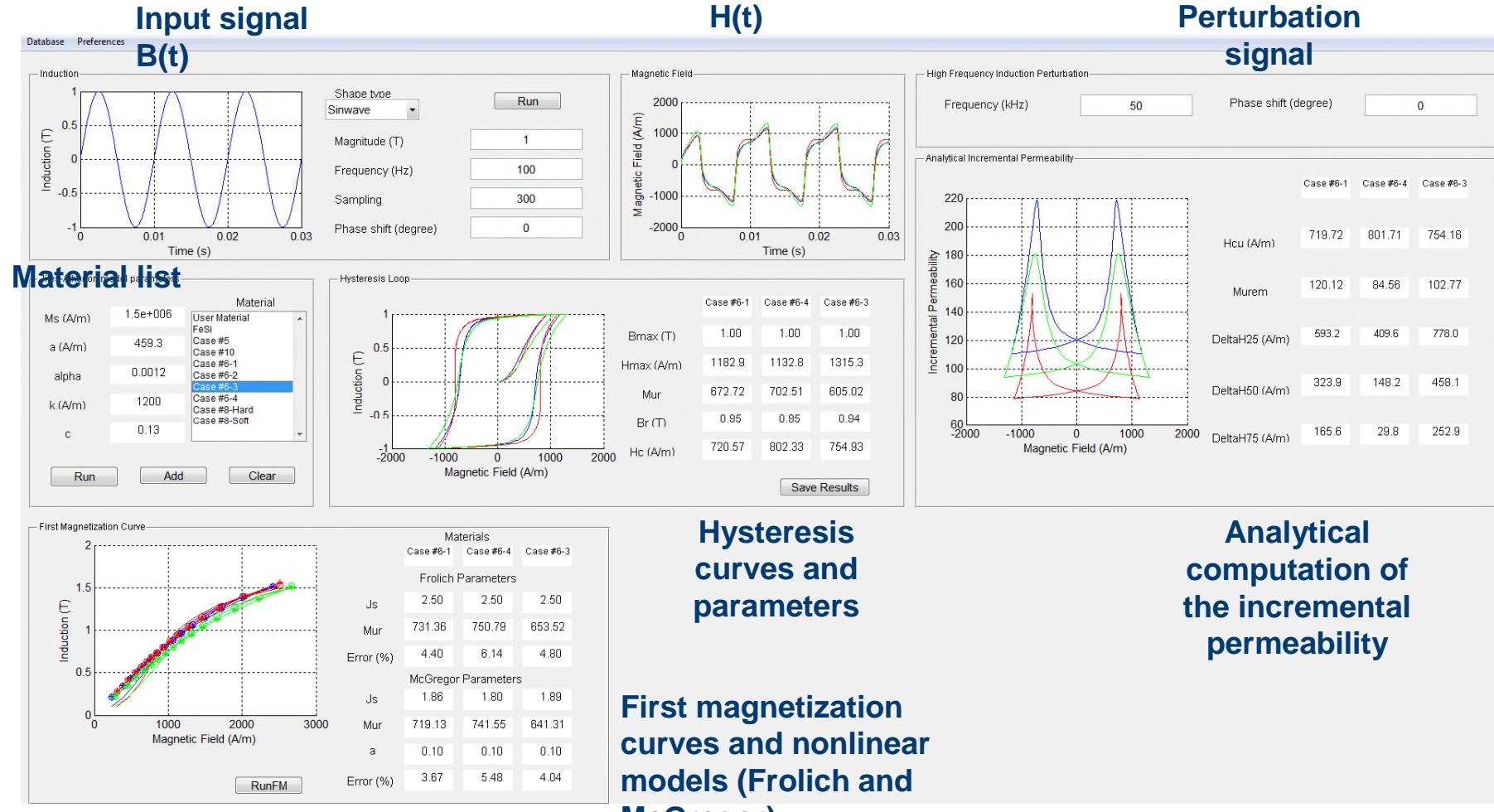
# Material modeling: Calculation and experiment



**Dynamic: Jiles Atherton+ Bertotti**  
 $f = 50\text{Hz}, 100\text{Hz}, 200\text{Hz}$



# Material modeling: Material data base in the platform



---

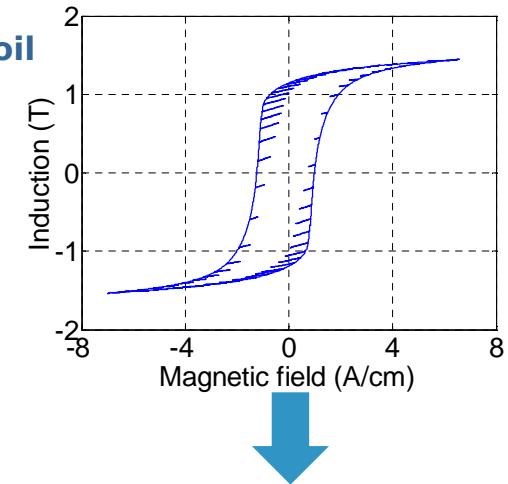
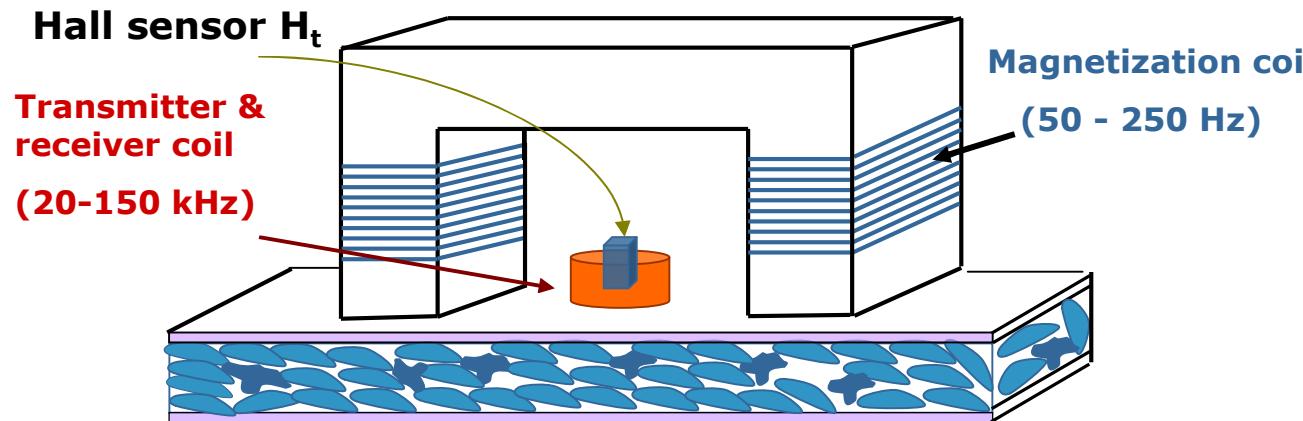
# Structure

---

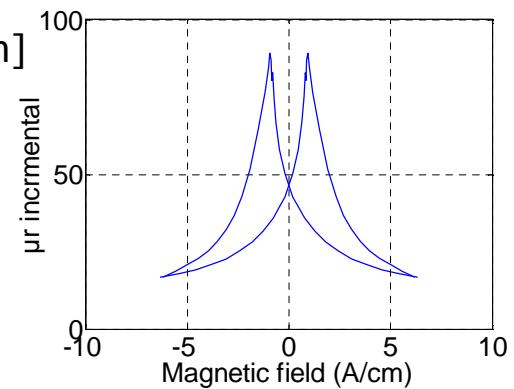
1. Introduction
2. Modeling of the magnetic material
  - General procedure
  - Characterization
- 3. FEM simulation**
  - 3MA principal and challenges
  - Impact of hysteresis
  - Low frequency eddy current
  - Incremental permeability
4. Validation& Correlation to mechanical properties

# FEM simulation: Modeling of the 3MA inspection situation

**3MA:** Micromagnetic Multi-parametric Microstructure & Stress Analysis

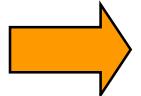


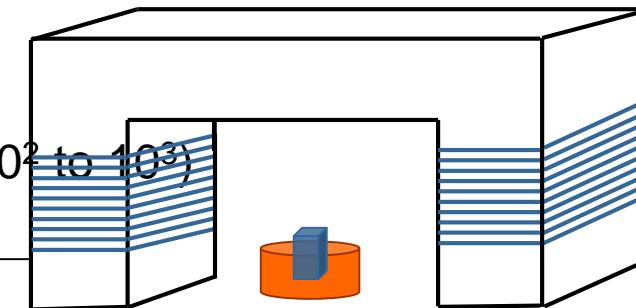
1. **Harmonic analysis:**  $F_{LF} = [50-200] \text{ Hz}$ ,  $H_{tmax} = [5 \text{ A/cm}-80 \text{ A/cm}]$
2. **Eddy current:**  $F_{HF} = [20-200]\text{kHz}$ ,  $H_{tmax} = \mu\text{T}$
3. **Incremental permeability:** combination of both methods



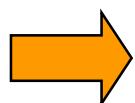
# FEM simulation: Challenges

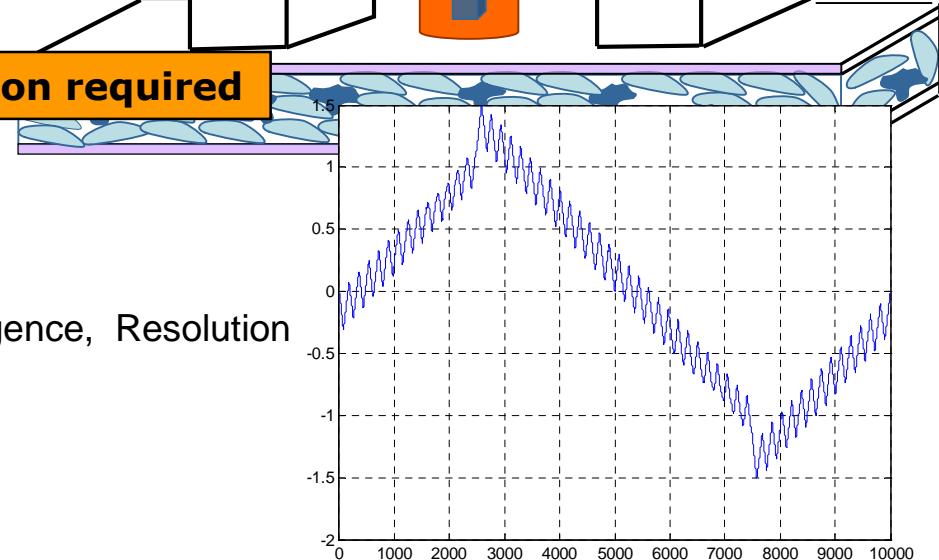
- Multiscale geometry system (scale factor of about  $10^4$ )
  - System size #  $100 \times 100 \text{ mm}^2$
  - multilayer specimen: 1mm thick sheet, 10 $\mu\text{m}$  thick for surface layers

 **Adapted mesh required**



- Multiscale time signal (scale factor of about  $10^2$  to  $10^3$ )
  - Low Frequency LF: 50 Hz – 250 Hz
  - High Frequency HF: 20 kHz – 150 kHz

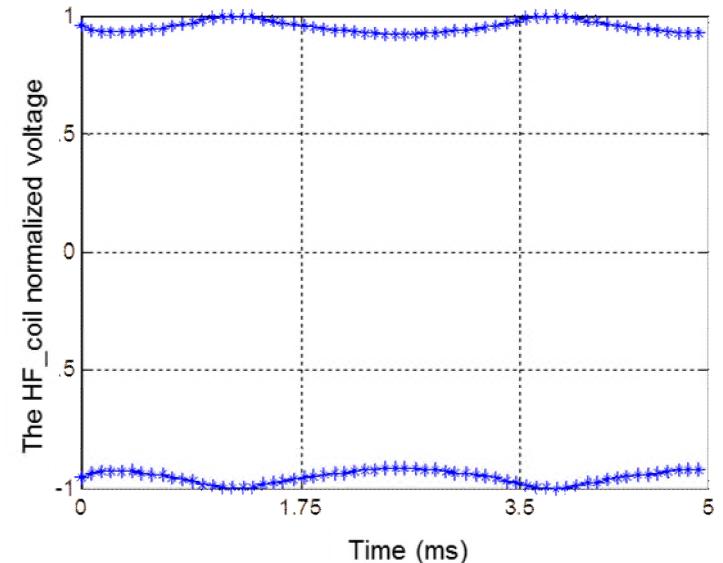
 **Adapted time stepping resolution required**



- Different layers magnetic properties :
  - Anhysteretic behavior in the first step
  - Hysteresis behavior consideration : convergence, Resolution time, Memory space.
- Eddy current at LF & HF excitations

# FEM simulation: IP signal - Combination of LF & HF

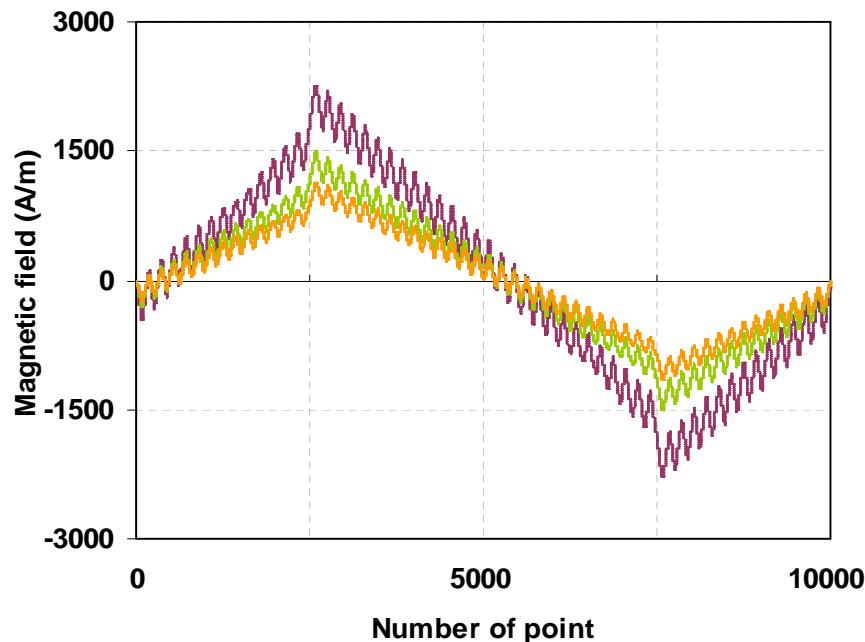
- **The computation is performed in transient, step by step in time considering:**
  - 1 LF period ( $f_{LF} = 200$  Hz)
  - 50 pts on HF period ( $f_{HF} = 20$  kHz)
  - $dt = 1.66\mu s$
- **Problems:**
  - Time computation exceed 3h (PC standard)
  - « intel ® core ™ 2CPU with 2.13 GHz, 3Gb RAM)
  - Space memory (35000 surface elements)
- **Go to more efficient computation**
  - To separate the two excitations
  - The second computation (HF) is seen as a disturbance around an operating point which is imposed with LF excitation.



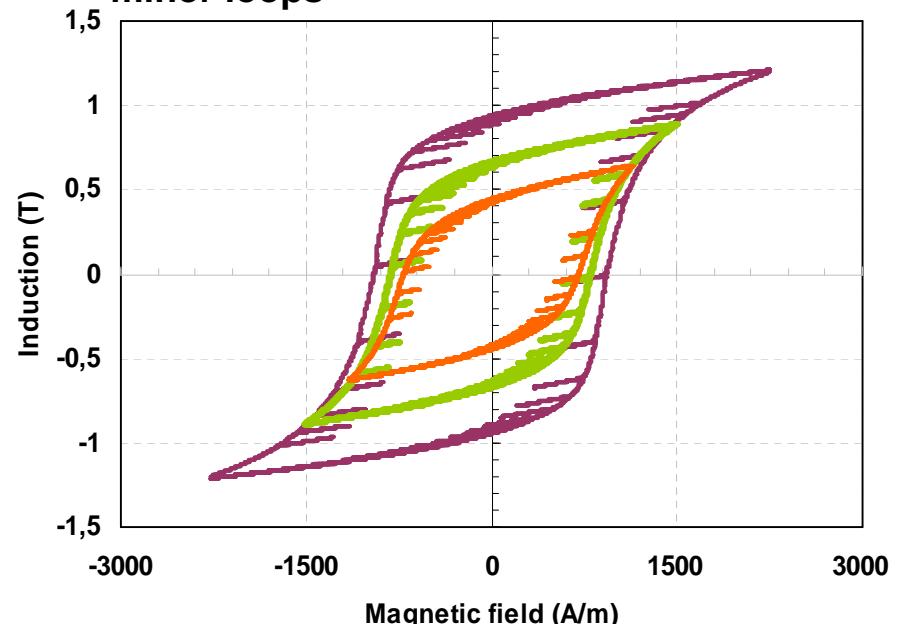
# FEM simulation: IP signal - Combination of LF & HF

## What means disturbance around the signal?

Low frequency signal disturbed by HF signal



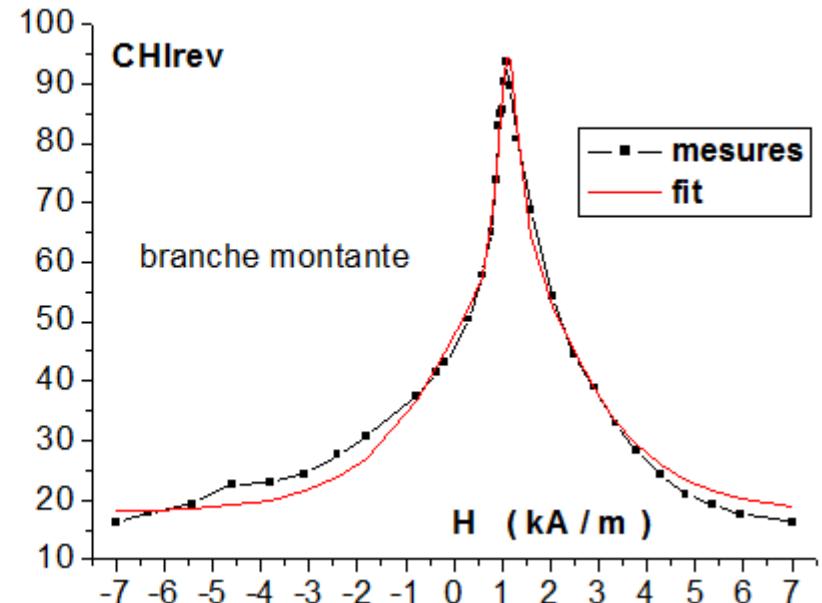
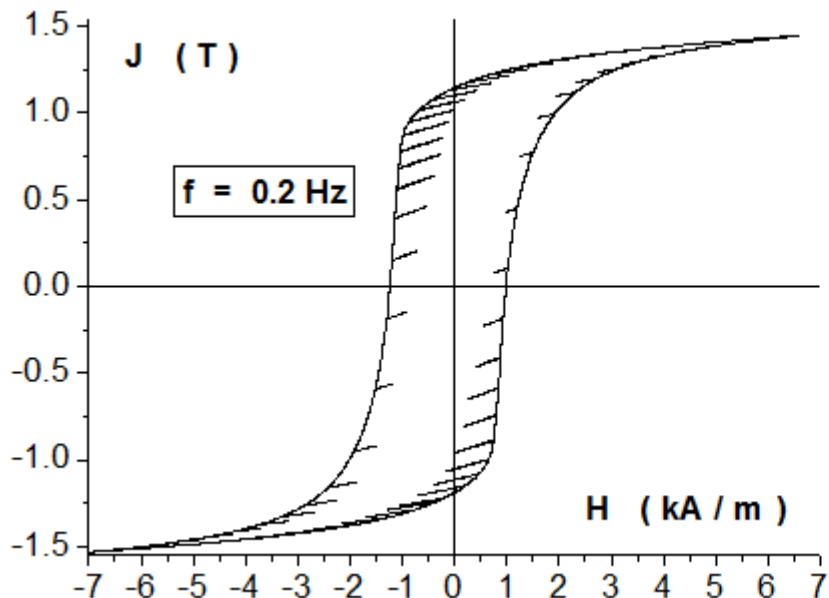
Symmetric and asymmetric hysteresis minor loops



The magnetic “answer” of the sample: Minor symmetric and asymmetric curves  
→ Slope of asymmetric curves is the incremental permeability

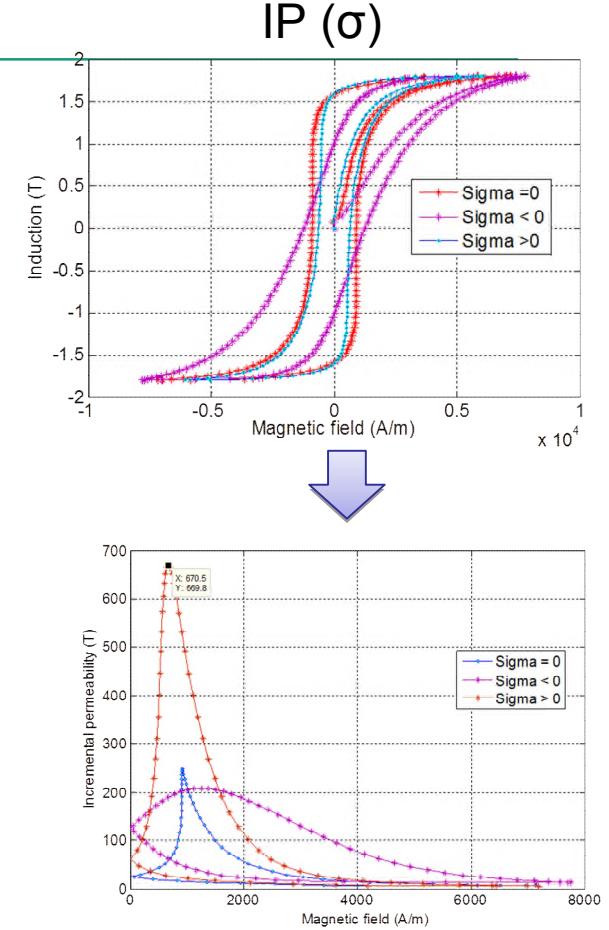
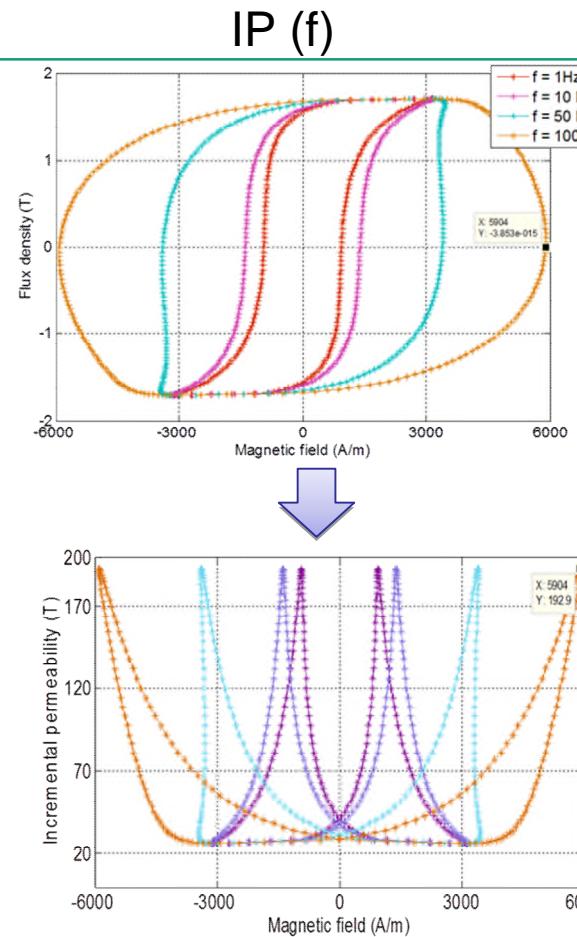
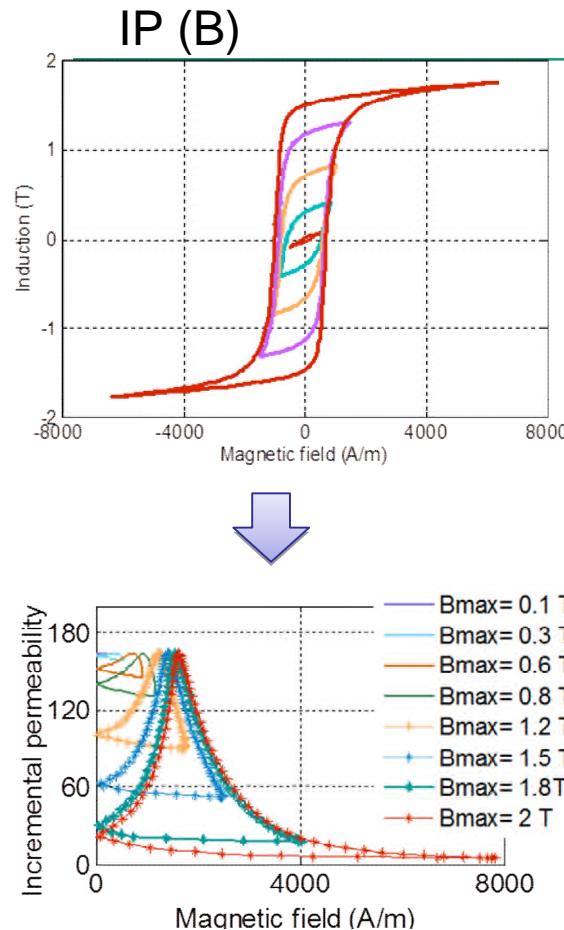
# FEM simulation: Validation of analytical formulation

## IP calculation: Epstein and analytical formulation



→ The results from the model fit correctly the measurements

# FEM simulation: Accuracy of the analytical IP algorithm



# FEM simulation: Modelling of 3MA IP method in FEM code

## How to model 3MA IP method in FEM code?

The permeability tensor:

$$[\mu_r] = \begin{bmatrix} \mu r_x & 0 \\ 0 & \mu r_y \end{bmatrix}$$

The IP tensor:

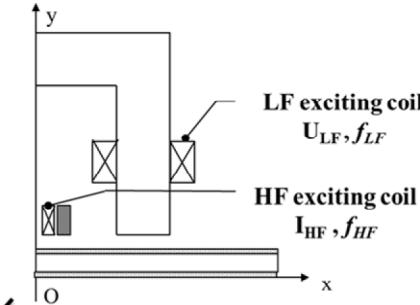
$$\left[ \frac{\partial B}{\partial H} \right] = \begin{bmatrix} \mu + 2H_x^2 \cdot \frac{\partial \mu}{\partial H^2} & 2H_x \cdot H_y \frac{\partial \mu}{\partial H^2} \\ 2H_x \cdot H_y \frac{\partial \mu}{\partial H^2} & \mu + 2H_y^2 \cdot \frac{\partial \mu}{\partial H^2} \end{bmatrix}$$

If the material is isotropic:

$$\mu r_x = \mu r_y$$

$$\mu r I_{\text{Inc}x} \neq \mu r I_{\text{Inc}y}$$

Incremental permeability signal  
depends on the magnetization direction



LF geometry with same mesh  
-  $H_t=0$  to (OY)  
- Transient ( $U_{LF} = 9V, f_{LF} = 100Hz$ )

HF geometry with same mesh  
-  $B_n=0$  to (Oy)  
- Harmonic

- Taking hysteresis into account through Jiles-Atherton formulation.
- Taking into account classical eddy current.

$t=[0-T_{LF}]$   
Transient solving at  $t_i$ :  
Computation and storing the nodal value on IP tensor

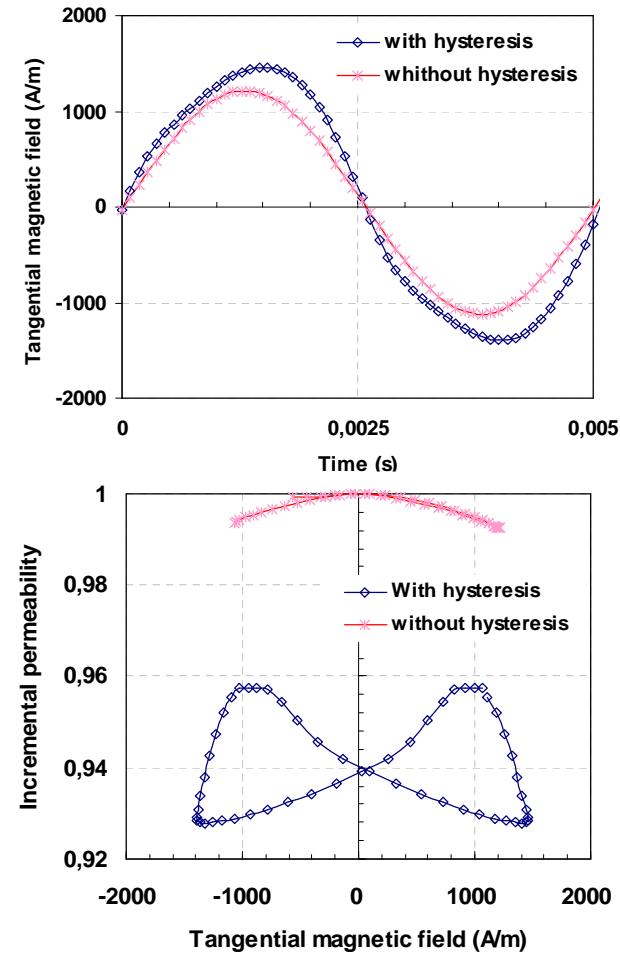
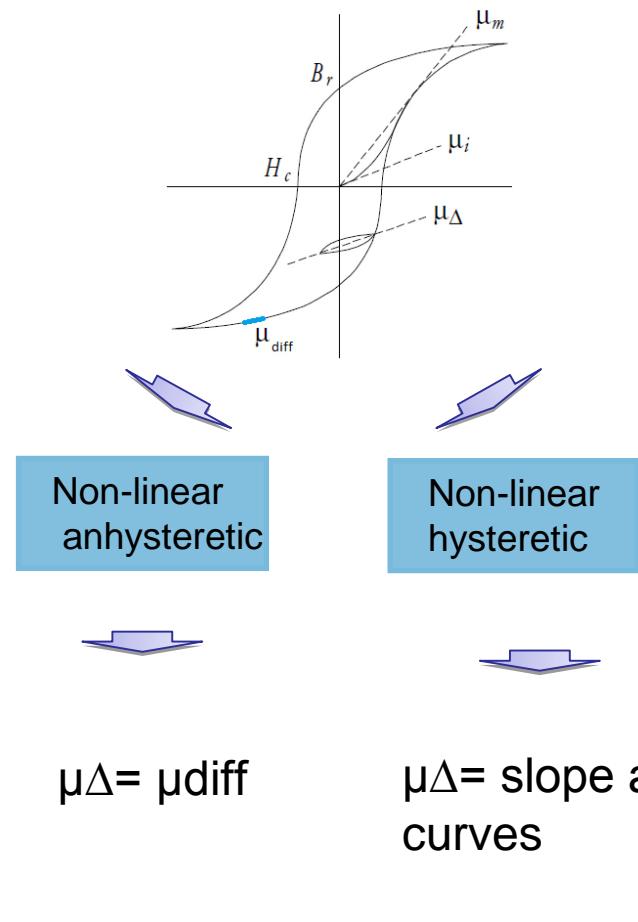
- Import of nodal IP tensor  
- Associate the value of IP at each node.  
- Computation in Harmonic

Computation of  $H_t$  on the middle of detection coil

Computation of  $V$  around the detection coil

# Simulation steps: Impact of hysteresis

Via FEM simulation using big 3MA probe



# Simulation steps: Impact of low frequency eddy current

Simulation condition:

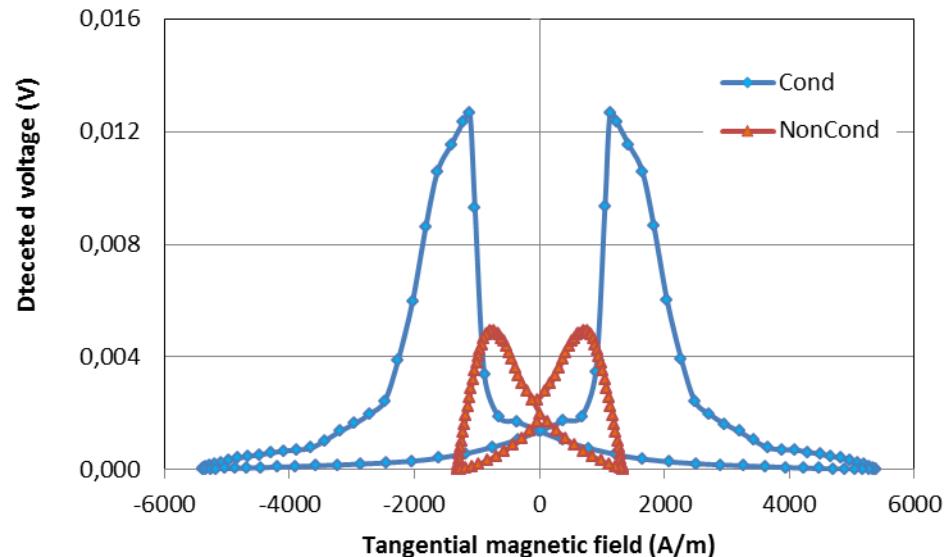
No lift-off!

$V_{max} = 20V$

$f_{LF} = 200 \text{ Hz}$

$f_{HF} = 20 \text{ kHz}$

$\sigma = 28.1 \mu\Omega \cdot \text{m}$



- Not conductive  $\rightarrow$  No eddy current effect

$$H_{tot} = H_{hyst}(B)$$

- Conductive  $\rightarrow$  Classical eddy-current

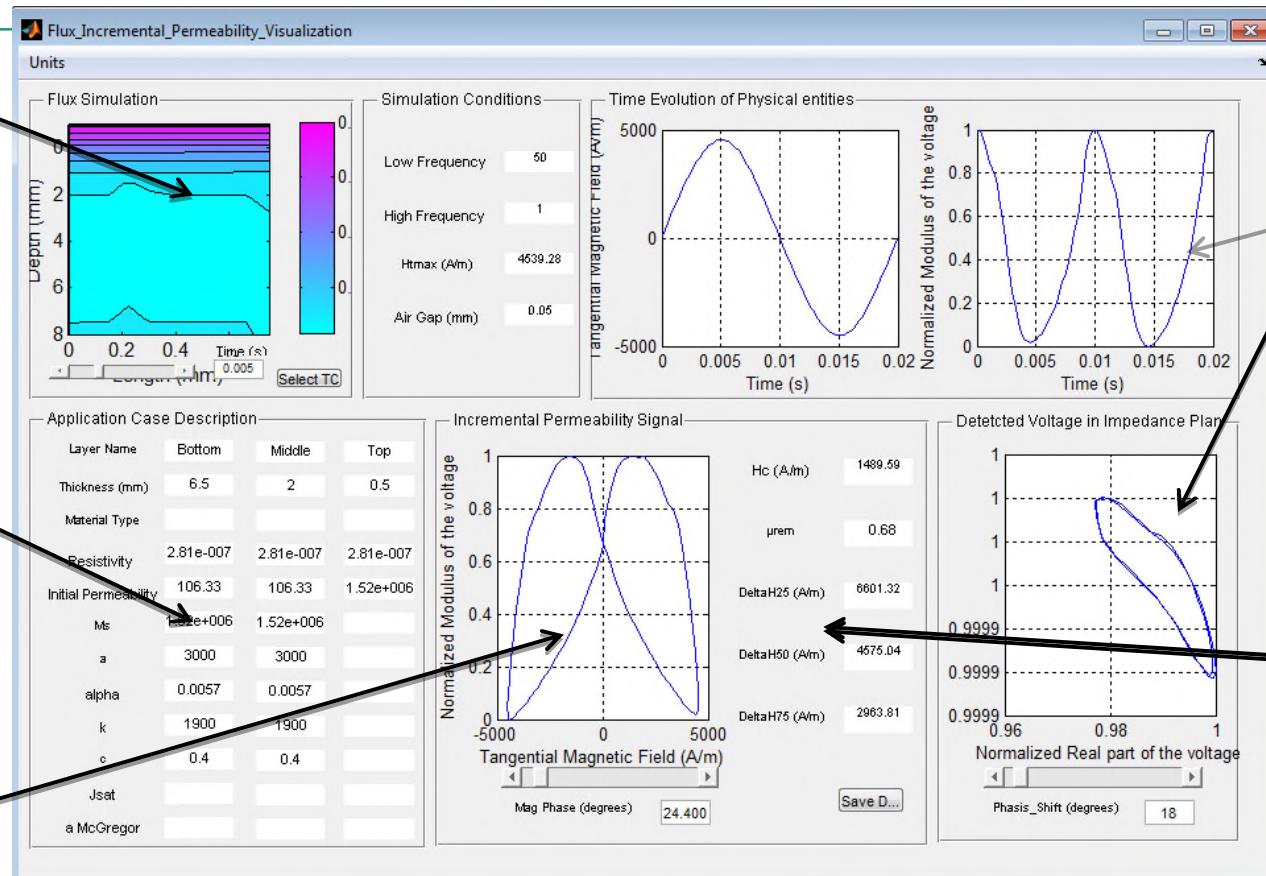
$$H_{tot} = H_{hyst}(B) + \sigma \frac{d^2}{12} \frac{dB}{dt}$$



If  $H$  increases  $\rightarrow$  Variation of IP increases significantly!

# 3MA visualization

Simulated flux distribution



Simulated signals

Specimen data

Simulated signals

Simulated signal parameters

3MA simulation user interface is similar to 3MA NDT user interface

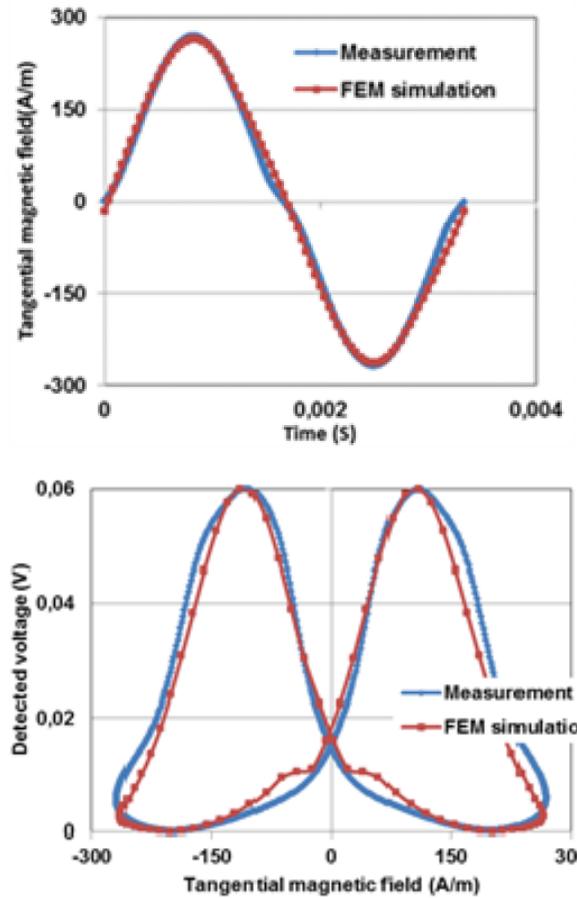
---

# Structure

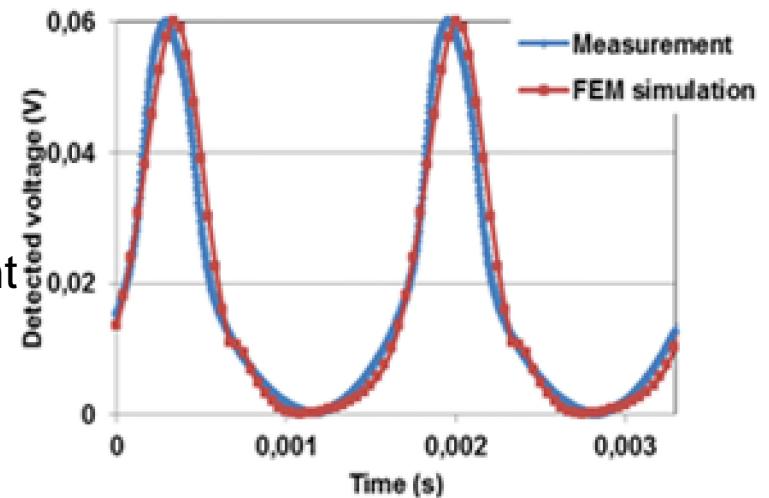
---

1. Introduction
2. Modeling of the magnetic material
  - General procedure
  - Characterization
3. FEM simulation
  - 3MA principal and challenges
  - Impact of hysteresis
  - Low frequency eddy current
  - Incremental permeability
4. Validation& Correlation to mechanical properties

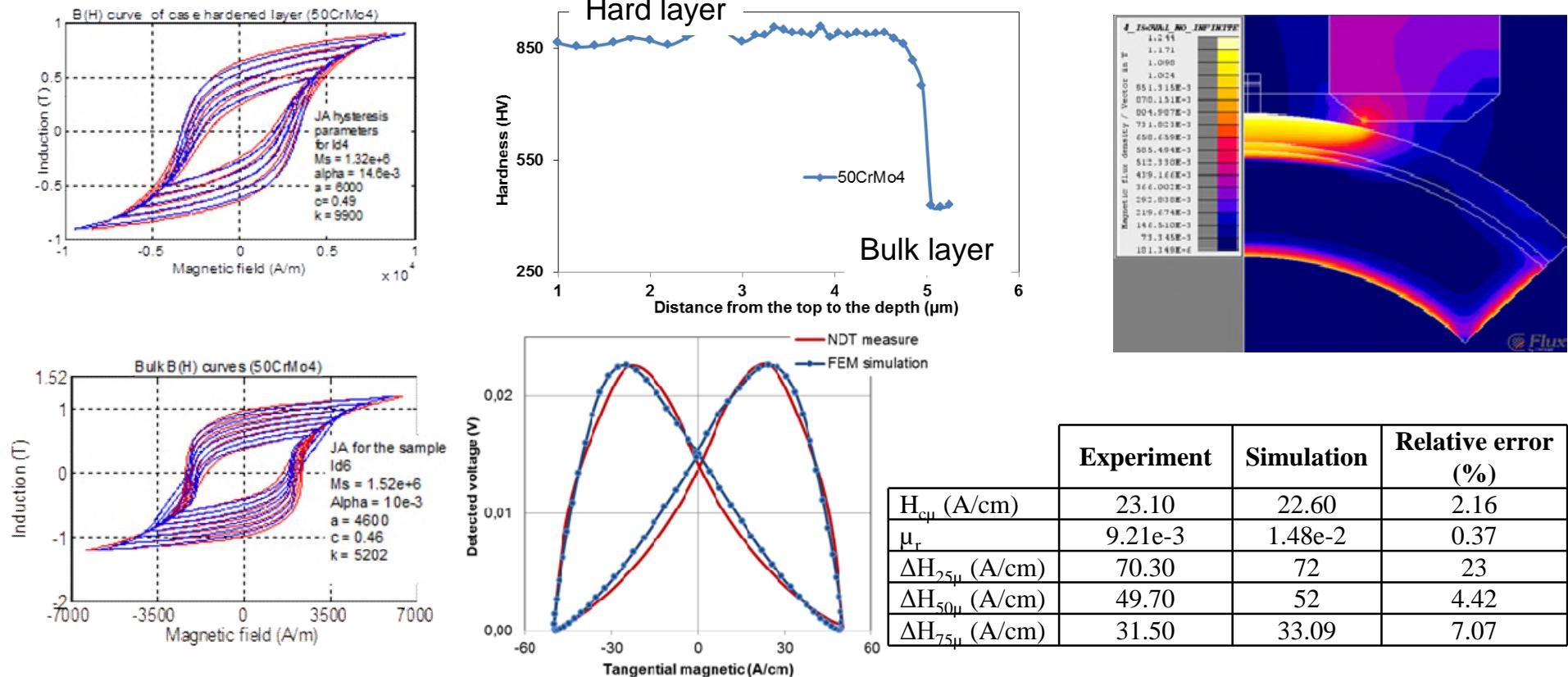
# Validation: Soft FeSi material



Good agreement  
between measurement  
and simulation!



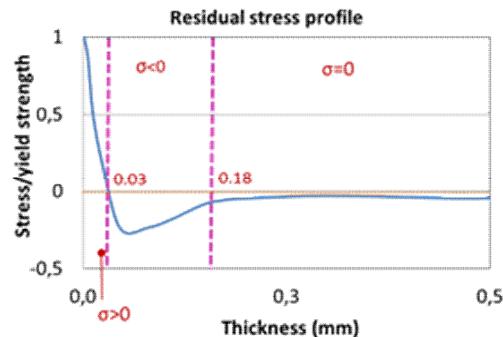
# Validation: hardened material



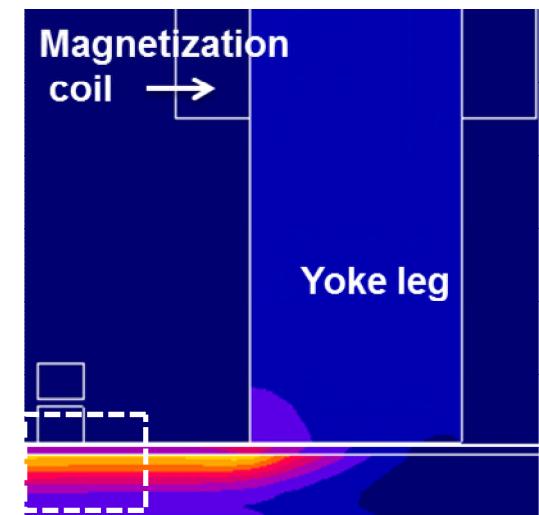
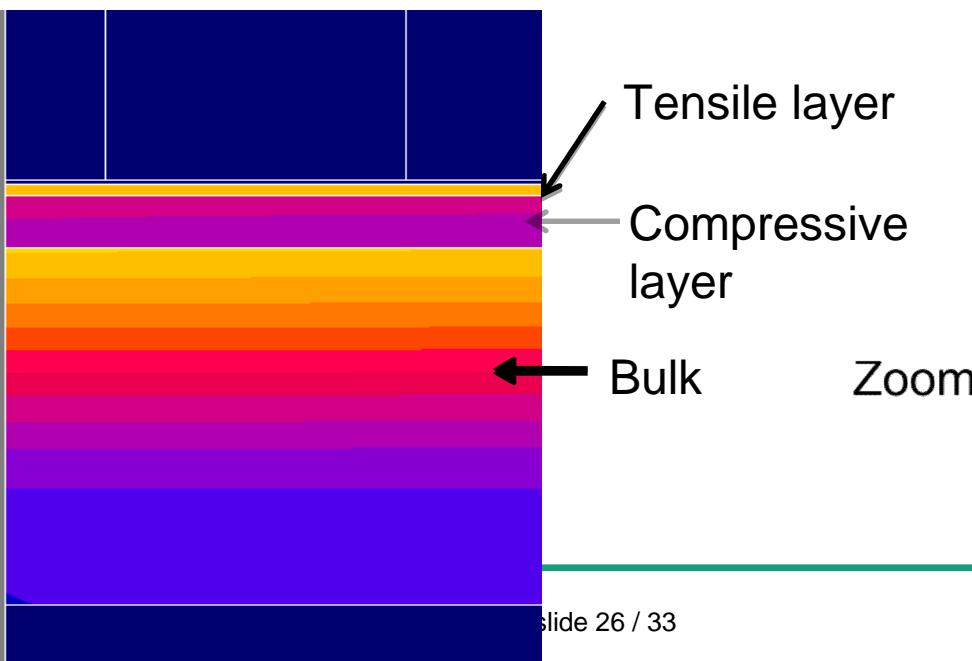
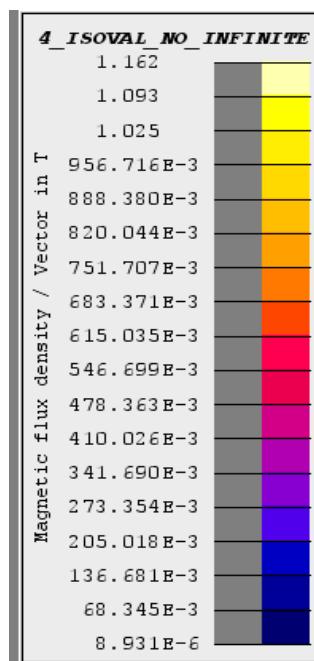
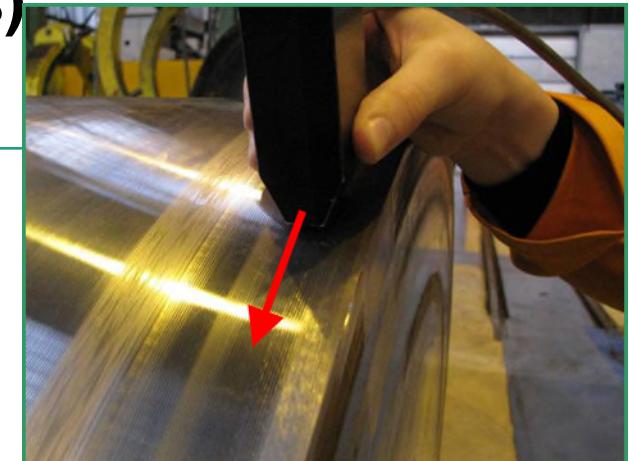
Results published in ECNDT 10/10/2014 at Prague  
 Y. Gabi, B. wolter, O. martins, A. Gerbershagen  
 ‘Examination of Hardened Depth of Steel Using 2D Nonlinear Hysteresis FEM Analysis’

# Validation: forged shafts (residual stress)

(Residual stress)

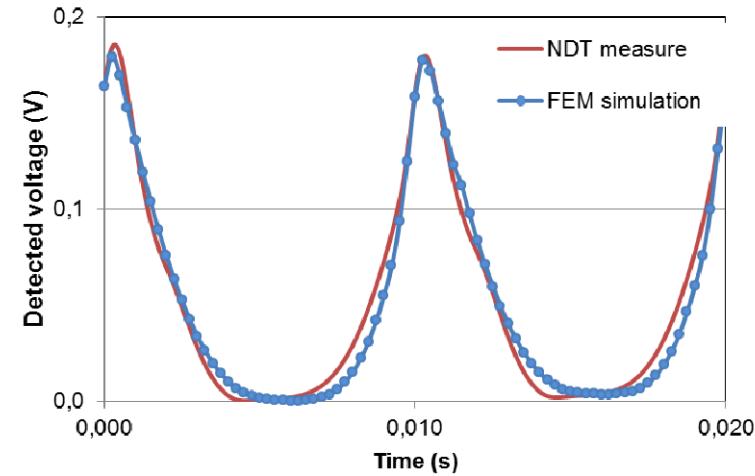
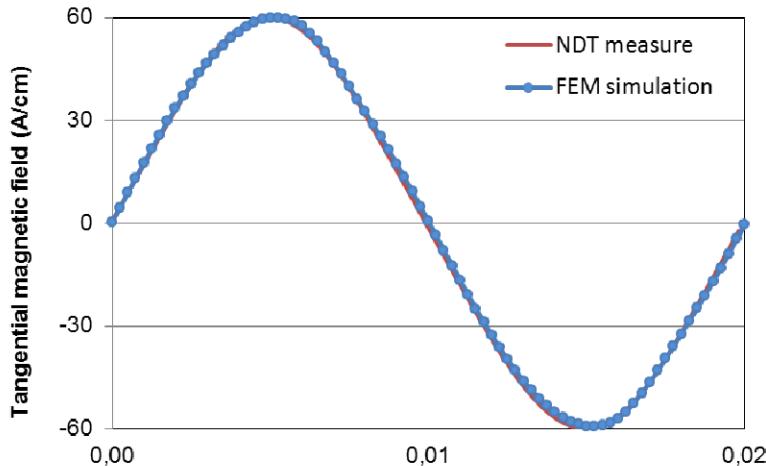


Material modeling



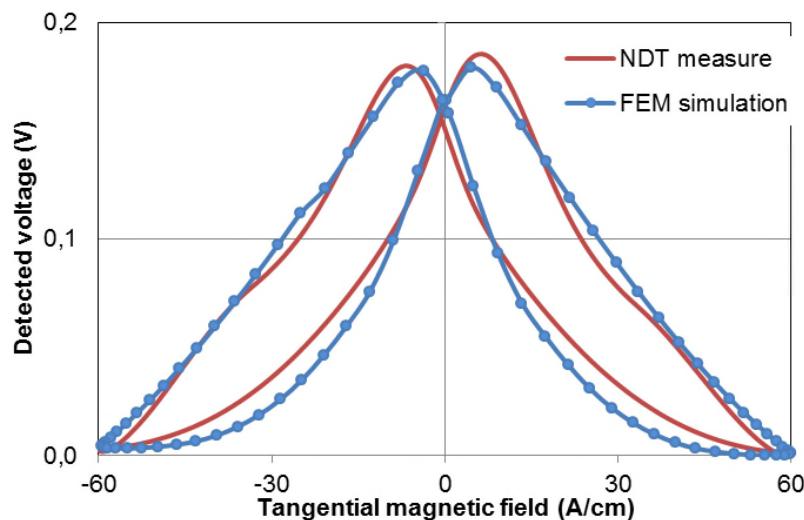
# Validation:

In axial direction



	Measurements	Simulation	Relative Error
$H_c$ (A/m)	645	550	13 %
$\mu_r$ (V)	0.169	0.175	3.42 %
$\Delta H_{25}$ (A/m)	6819	6474	5.05 %
$\Delta H_{50}$ (A/m)	3862	3850	0.31 %
$\Delta H_{75}$ (A/m)	2029	1800	11.28 %

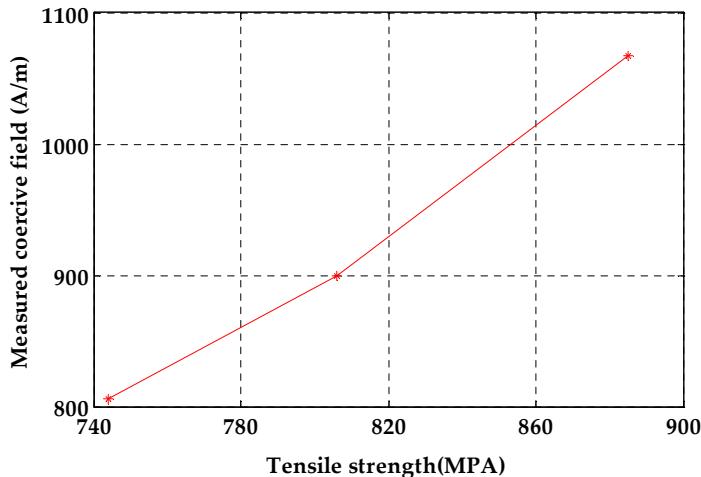
Results published in IMF conference in China,  
Paper awarded: M. Ewen, P. Braun, Y. Gabi, B. Wolter  
“Development of Nondestructive Determination of Mechanical Properties of Open-Die forgings and Potentials for Full Implementation in Production Process Chain”



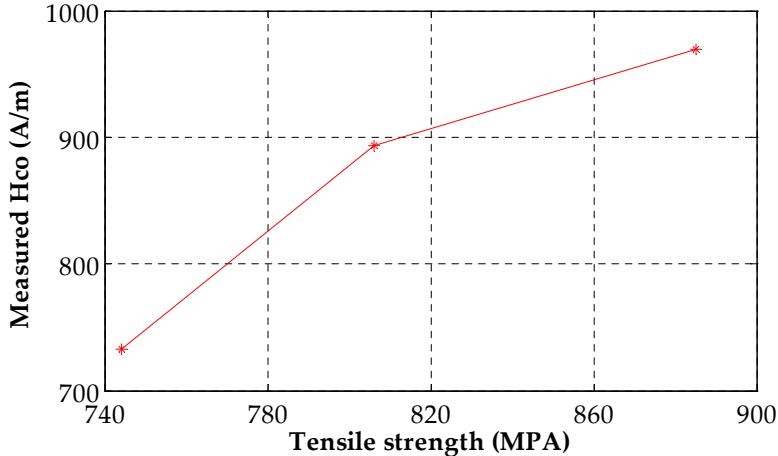
# Correlation

Evolution of the coercive field with the tensile strength :  $f_{LF} = 100 \text{ Hz}$ ,  $Ht = 30 \text{ A/cm}$

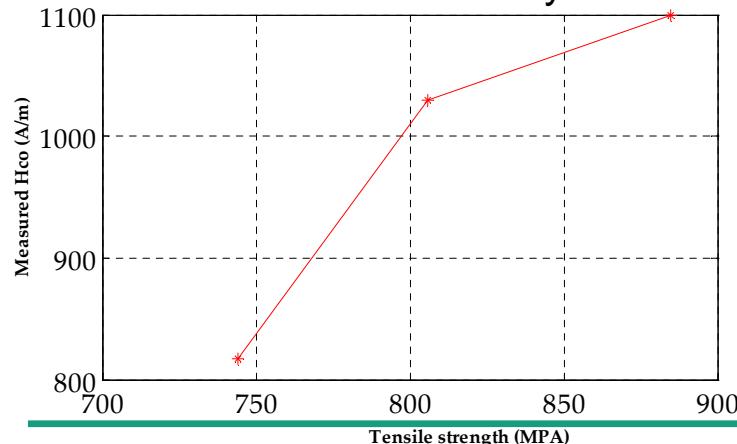
Hysteresis measurements



Harmonic Analysis Simulation



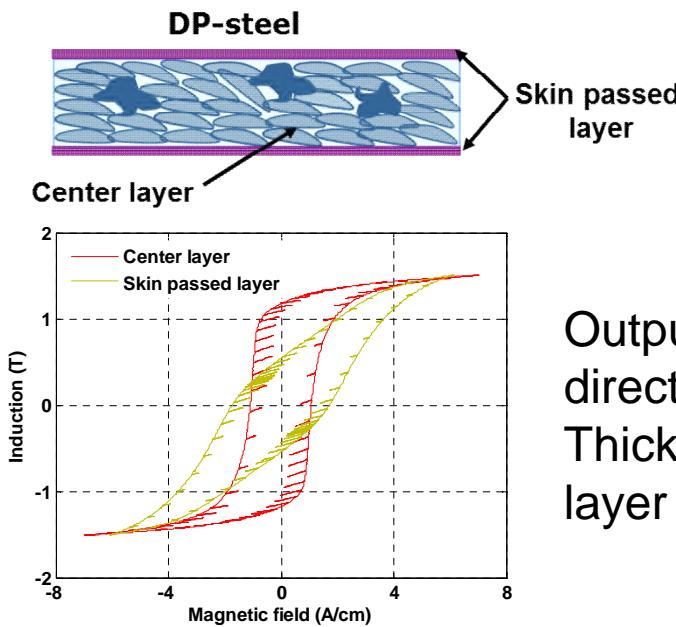
Incremental Permeability



Measured and simulated parameters

Applied Strength (MPa)	Measure- ment	Harmonic Analysis		Incremental Permeability
		Hc (A/m)	Hco (A/m)	
744	791	733	733	817.34
806	908	893	893	1030
885	1065	970	970	1100

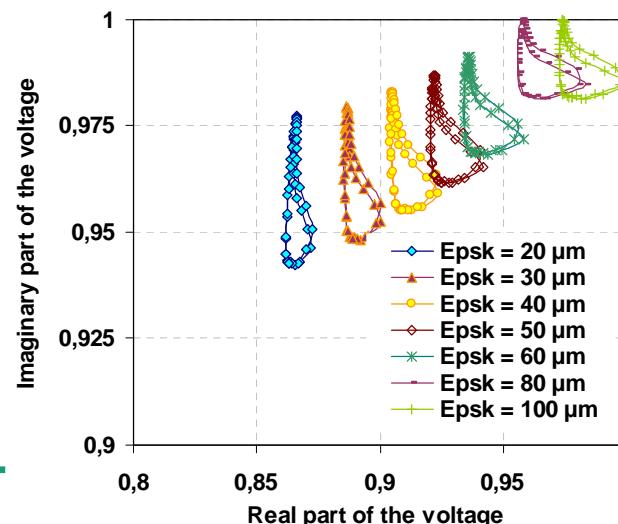
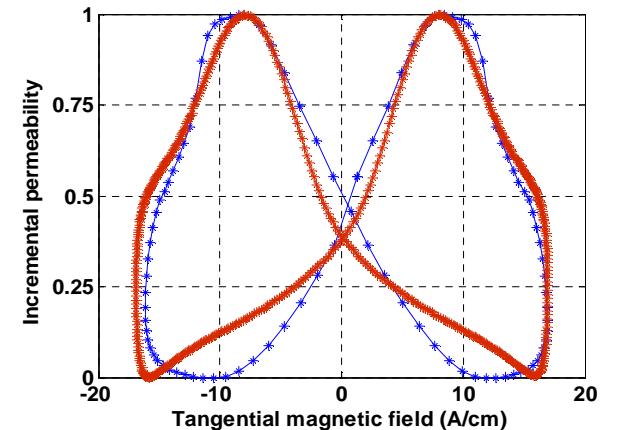
# Validation on dual phase steel



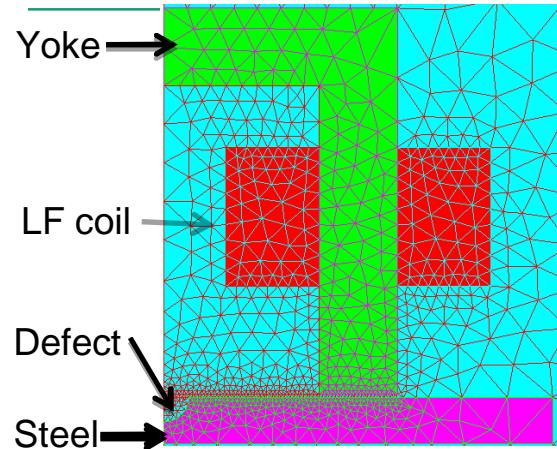
Output 3MA parameters directly correlated to Thickness of skin passed layer !

PHD Y. GABI : Dr. A.Lebouc, Dr. G.Meunier,  
Dr.Ol.Geoffroy, from G2Elab  
Dr. P. Meilland , Arcelormittal  
Dr. B.Wolter, IZFP Saarbrucken  
Dr. C. Guerin and P. Labie from Cedrat

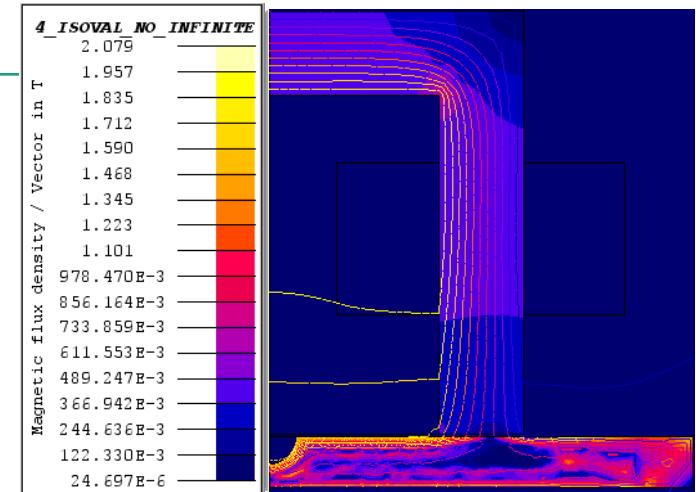
IP :  $H_t=17\text{ A/cm}$ ,  $f_{LF}=200\text{ Hz}$  &  $F_{HF}=20\text{ kHz}$



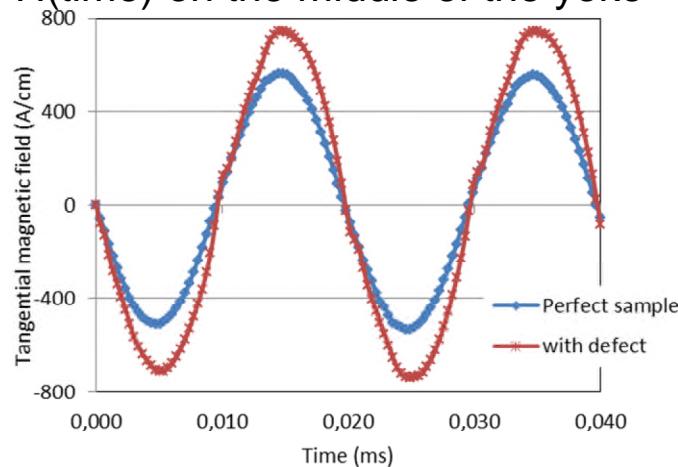
# Defect on steel



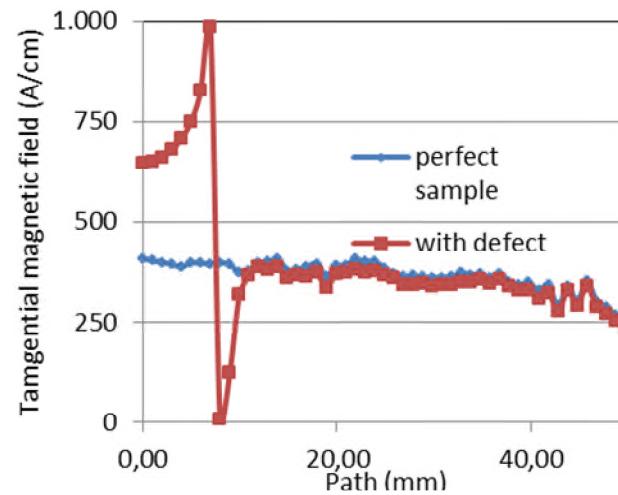
Radius=16 mm  
Sample thickness=16 mm



H(time) on the middle of the yoke



H(path) from the middle to the yoke leg



---

# Summary & conclusions

- **3MA FEM modelling**
  - Modeling of the magnetic material (Hysteresis, eddy current, excess, stress,...)
  - FEM simulation (strategy computation,...)
  - Modeling of the 3MA Signature and the output parameters is completed!
- **Advantage of the used code:**
  - Complex geometry can be simulated
  - Automatic meshing
  - Time computation: 3 periods, 30mn
  - Convergence: Newton Raphson, 7 iterations
- **IZFP interest:**
  - Succeed to reproduce 3MA experiment signals and outputs
  - Link the NDT output parameter to mechanical properties
  - Support calibration process
  - Indirect manner to characterize surface layers using the combination of models + experiments

---

# Summary & conclusions

- **3D modeling of 3MA**
  - especially for complex yoke and rotating magnetic field
  - Manage the convergence and stability
- **Combine electromagnetic code and mechanical I code**
  - So far, residual stress was represented by multi layer approach
  - It is necessary to calculate the local value of residual stress
  - Found  $B(H\sigma)$  formulae
  - Multi physic calculation
- **Main interest:**
  - Multi scale modeling, ex press hardened steel → complex soft phase
  - Inverse problem taking into account non linear hysteretic behavior
  - Built an intelligent calibration process!

## Acknowledgements

---

- The research leading to these results has received funding from the European Community's Seventh Framework Program (FP7/2007-2013) under Grant Agreement No. 285549: SIMPOSIUM project.



- Funding Scheme: Collaborative Project
- Homepage: [www.simposium.eu](http://www.simposium.eu)

---

---

Many thanks for your attention!